

# Using Dynamic Polarization as Leverage to Extract the Global Signal

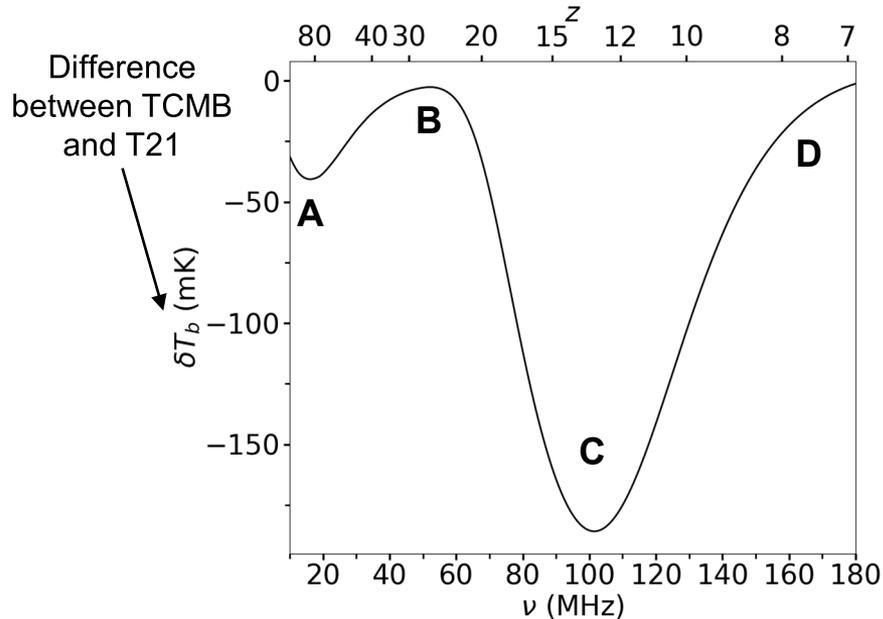
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# Why do we pursue the global 21-cm signal?

- Interaction of excitation temperature,  $T_S$ , of HI's 21-cm transition with radiation fields produces signal which opens up the first billion years after recombination to new inquiry



**A:** Collisions between H atoms no longer relevant to  $T_S$  because CMB temperature exceeds kinetic temperature of H gas

**B:** First stars ignite, coupling  $T_S$  to the strength of their Lyman- $\alpha$  radiation

**C:** First black holes begin accretion, heating gas to warmer than the CMB

**D:** Reionization drives signal to zero since only neutral hydrogen emits 21-cm radiation

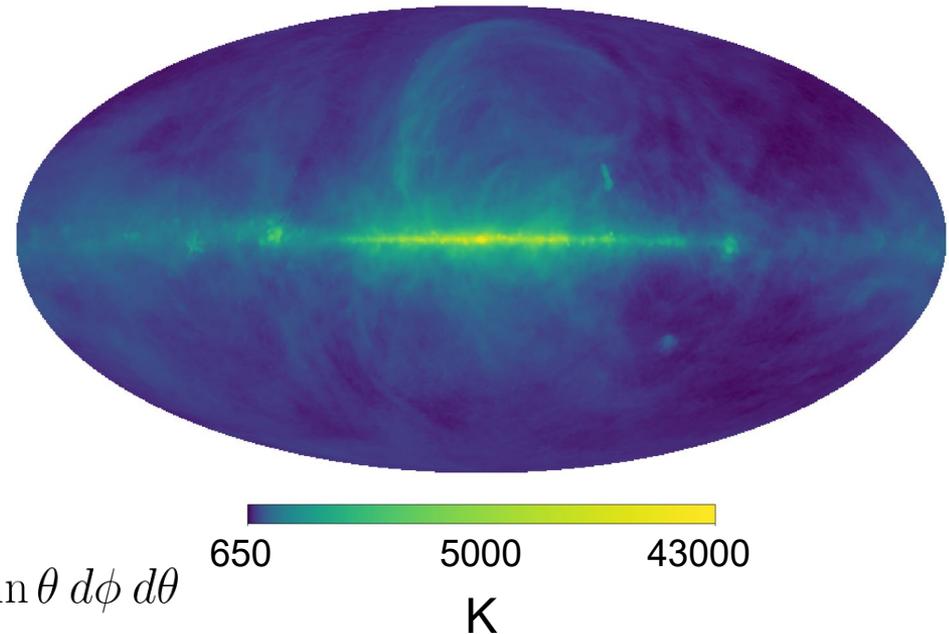
# Difficulty of measuring 21-cm signal

- Strong galactic foregrounds combine with antenna beam chromaticity to produce complicated spectral structure.
- Foregrounds have steep spectra with spectral index of -2.5, i.e.

$$T_{\text{FG}}(\nu, \theta, \phi) \approx A(\theta, \phi) \times \nu^{-2.5}$$

$$T_{\text{BWFG}}(\nu) = \int_0^\pi \int_0^{2\pi} B(\nu, \theta, \phi) T_{\text{FG}}(\nu, \theta, \phi) \sin \theta d\phi d\theta$$

Galaxy map from Haslam et al. (1982) scaled to 80 MHz



# Traditional approach to measurement

- Experiments such as EDGES attempt to calibrate out beam chromaticity from single spectra and then fitting a polynomial or polynomial-like model simultaneously with a chosen signal model.
- The beam corrections rely on the temperature of the sky model and the simulation of the beam model being correct.

$$BCF(\nu) = \frac{\int_0^\pi \int_0^{2\pi} B(\nu, \theta, \phi) T_{\text{FG}}(\nu, \theta, \phi) \sin \theta \, d\phi \, d\theta}{\int_0^\pi \int_0^{2\pi} B(\nu_n, \theta, \phi) T_{\text{FG}}(\nu, \theta, \phi) \sin \theta \, d\phi \, d\theta}$$

↑  
Beam chromaticity factor

Model of beam weighted foreground

$$M_{\text{BWFG}}(\nu) = \sum_{k=0}^{N-1} a_k \nu^{-2.5+k}$$

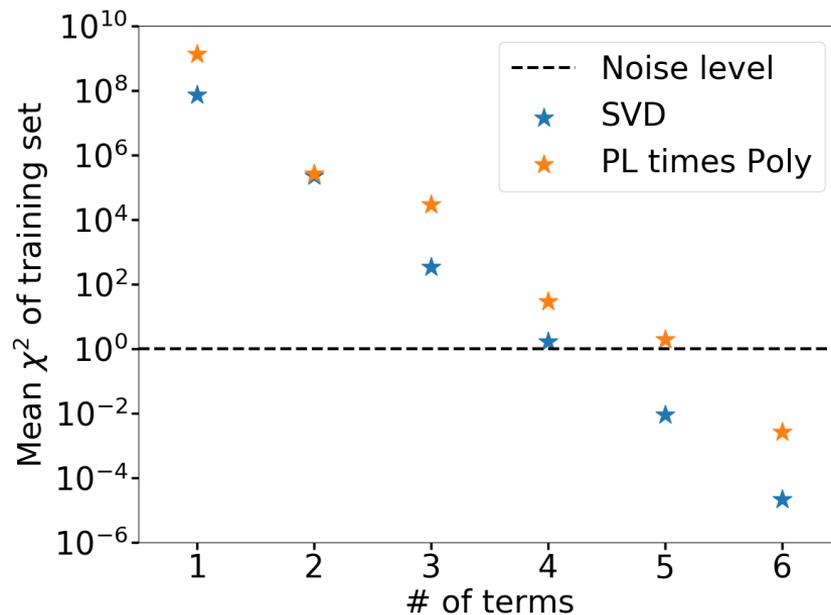
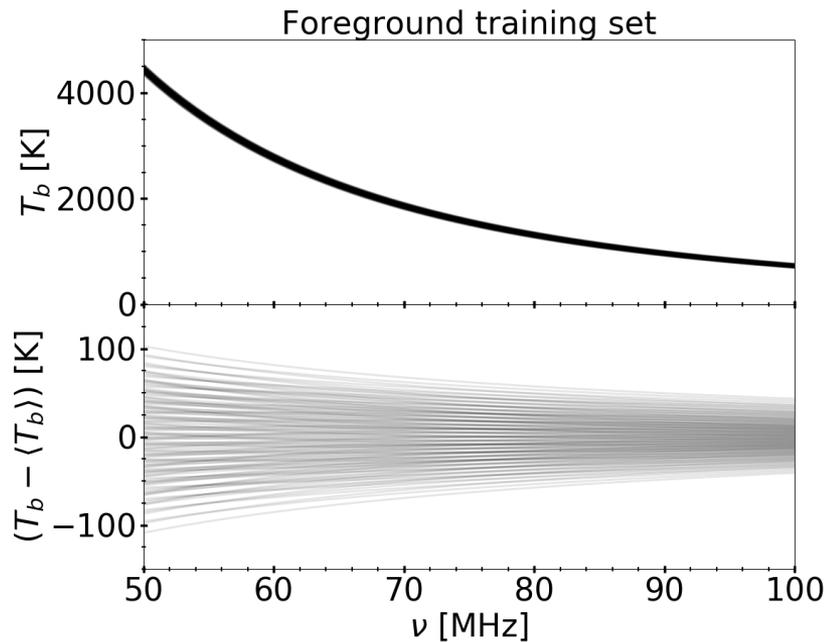
# Our new method, SVD/MCMC

- We have developed a technique to analyze many spectra at once.
  - The information relating different spectra (such as different foregrounds caused by looking in a different direction) can help extract the signal, which doesn't change from spectrum to spectrum, more rigorously.
- By simulating training sets for these sets of spectra, we can create models specifically suited for that dataset, instead of relying on an a priori model.
- We also use training sets of the signal derived from physical simulations.



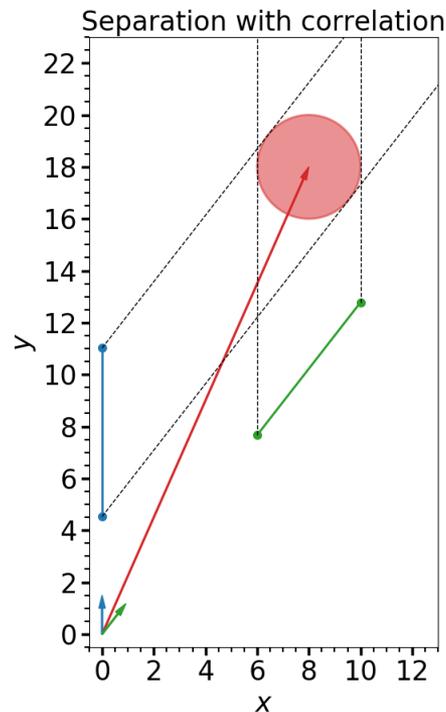
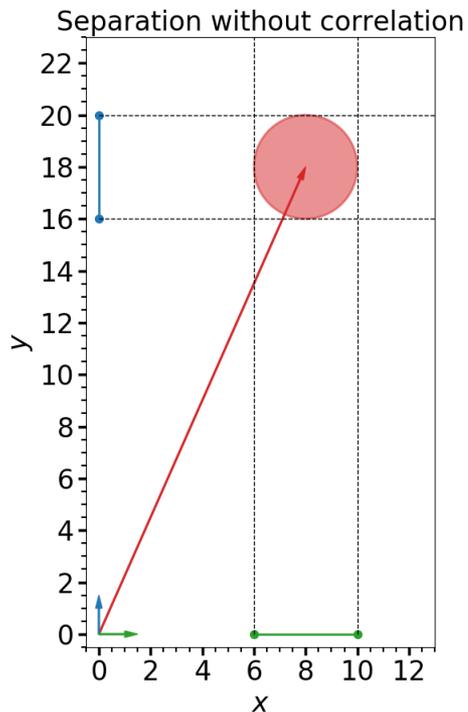
# Using SVD to generate optimal basis vectors

- Singular Value Decomposition (SVD) is a factorization of the training set that provides the optimal basis vectors with which to fit that training set.



# Simultaneously fitting foreground and signal

- Once we have SVD models for both foreground and signal, we fit them simultaneously to the data.
- The uncertainties in this separation of the two components depend on how similar their models are.
  - **If the foreground and signal training sets are different enough and the experiment is designed well enough, then the signal can be constrained rigorously.**

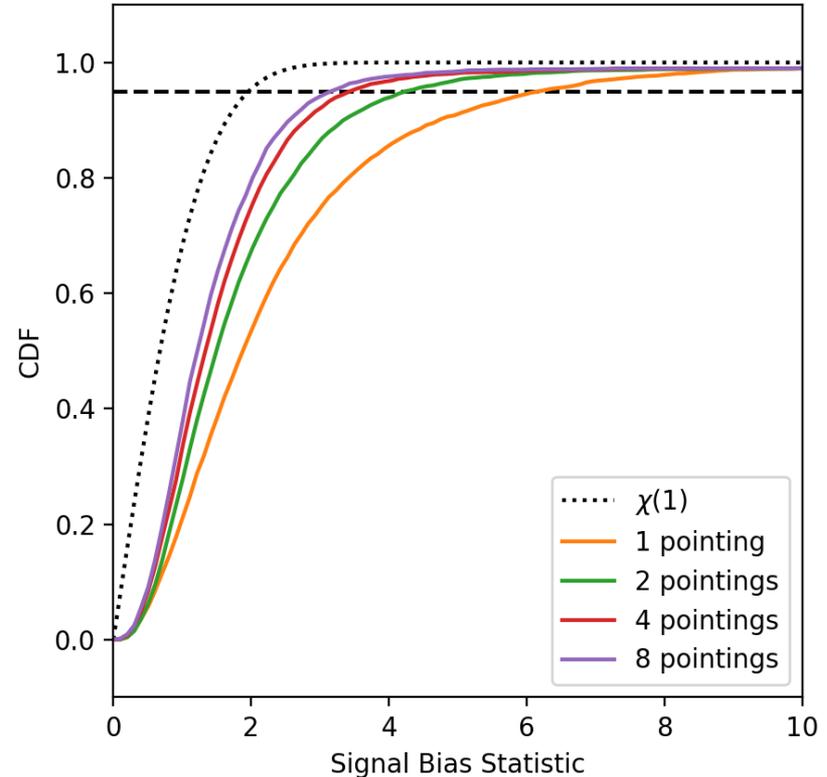


# Drift-scan measurements

- One example of experimental design that can lower the overlap/similarity between foreground and signal is drift-scan.
- Time introduces valuable structure into sky-averaged data because the antenna beam points at different points in the sky at different times.
- This leads to multiple spectra with the same signal but different foregrounds.

# Effect of multiple pointings

- Looking at multiple independent directions is a discrete form of drift-scan.
- The forecasted errors are smaller and the signals are less biased when simulating data with multiple antenna pointings instead of one.



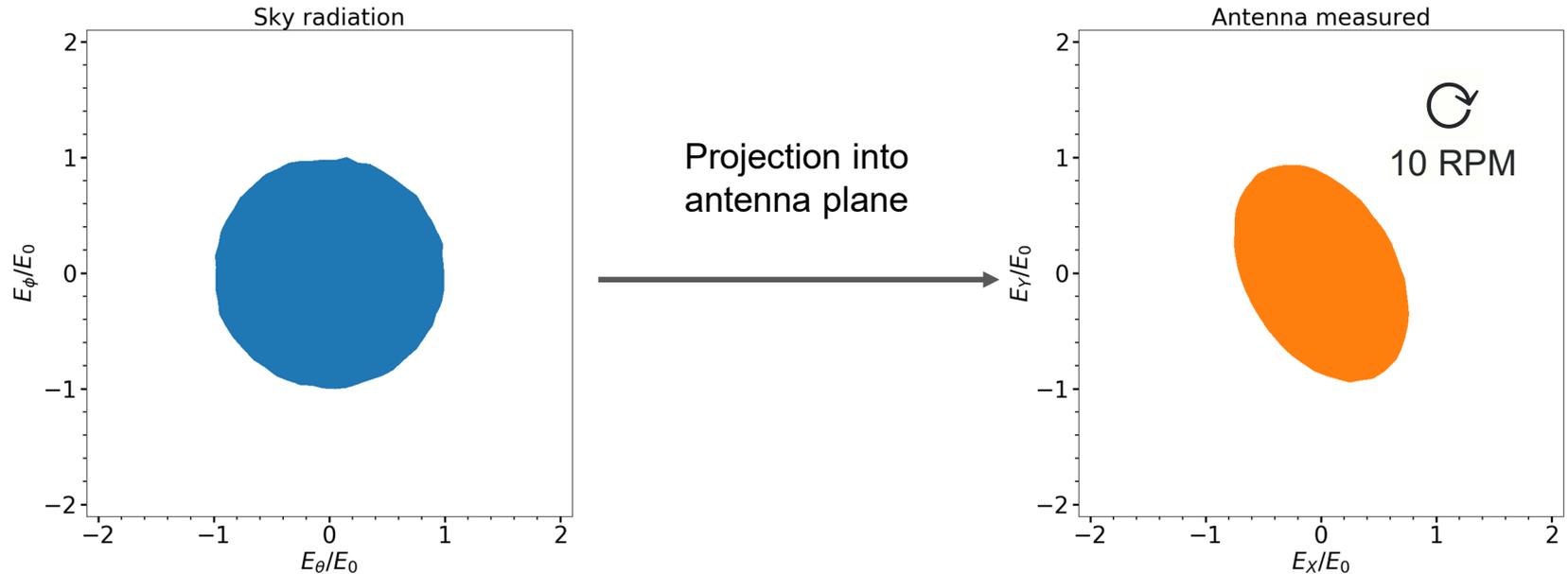
# Other benefits of SVD/MCMC generalization

- Since our pipeline does not require a foreground model to be given beforehand (only training sets), data aspects with no obvious extension in the polynomial-like approach can be utilized.
- One of these effects is polarization, which is measured in terms of the Stokes parameters I, Q, U, and V.

|  |   |   |
|--|---|---|
| Single antenna<br>experiments<br>(e.g. EDGES, SARAS) | $\left[ \begin{aligned} I &= \langle  E_X ^2 +  E_Y ^2 \rangle \\ Q &= \langle  E_X ^2 -  E_Y ^2 \rangle \\ U &= 2 \operatorname{Re}(E_X^* E_Y) \\ V &= 2 \operatorname{Im}(E_X^* E_Y) \end{aligned} \right.$ | Dual antenna<br>experiments<br>(e.g. DAPPER, CTP) |
|--|---|---|

# Induced polarization

- Projection onto the instrument's antennas induces a polarization signal measured by dual antenna instruments, which can help constrain foreground.



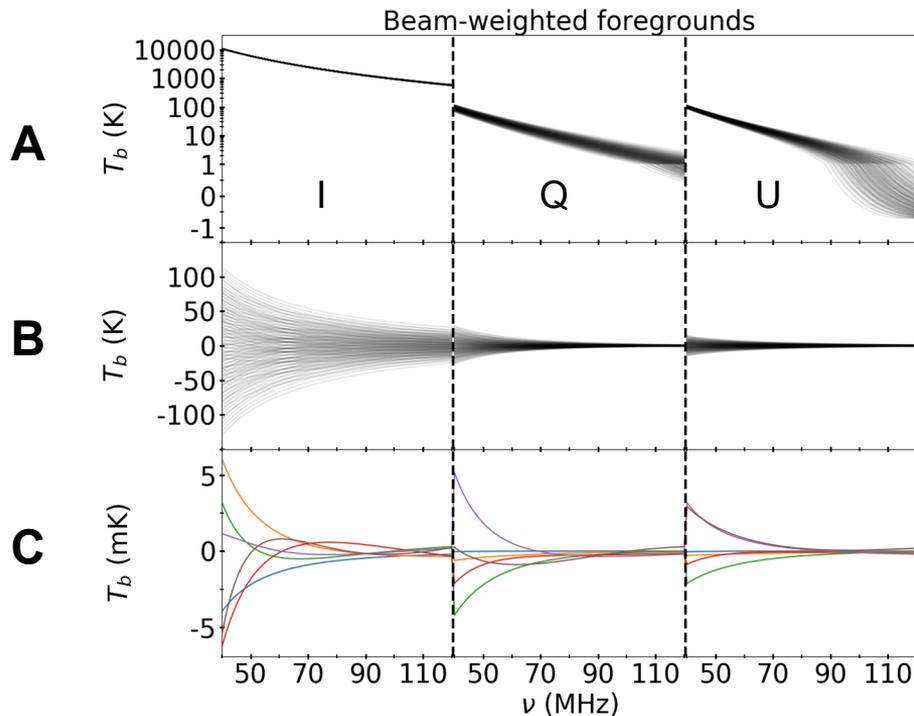
# SVD takes advantage of structure

- SVD naturally provides a model which accounts for connections between Stokes parameters

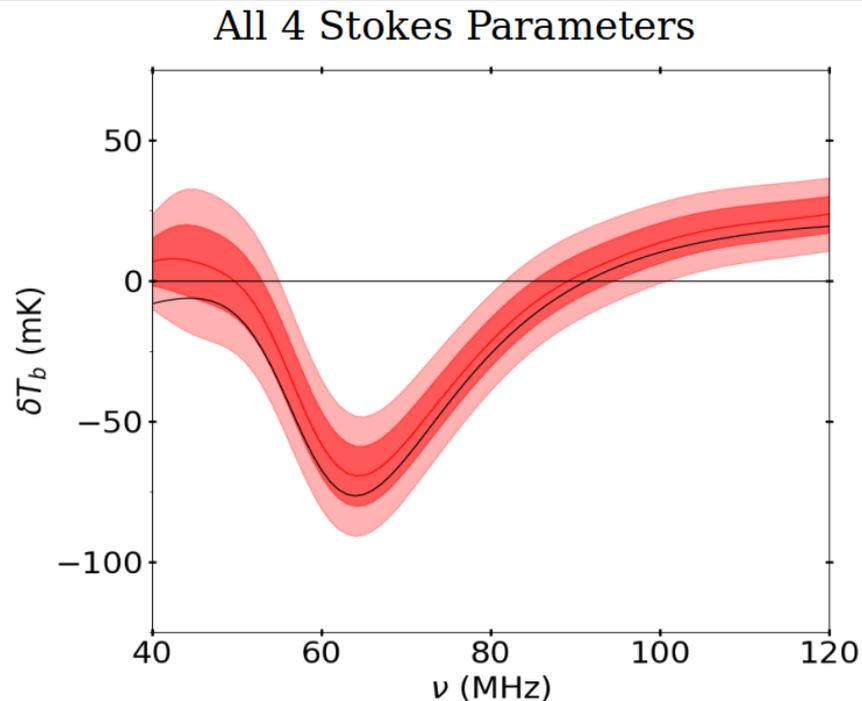
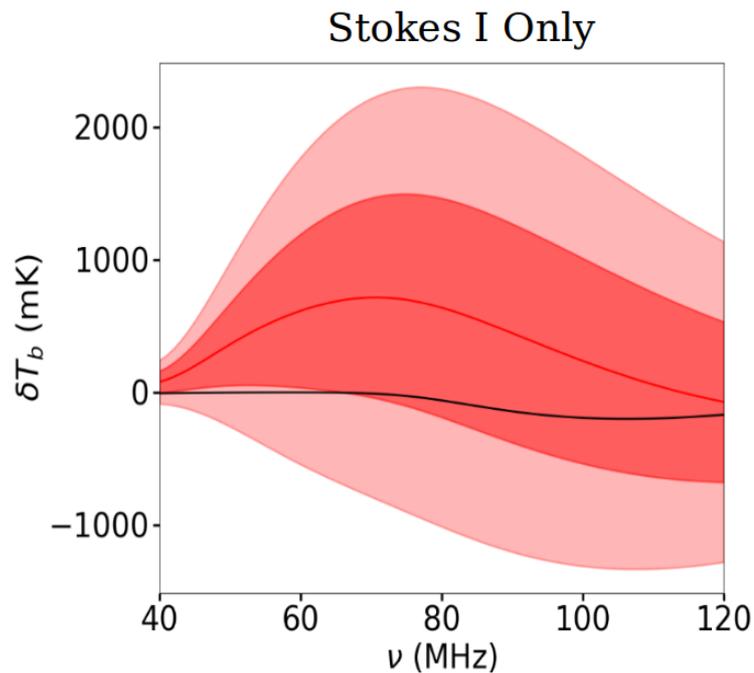
**A:** Training set of Stokes parameters accounting for induced polarization.

**B:** Training set with average subtracted

**C:** Optimal basis vectors to fit training set, provided SVD



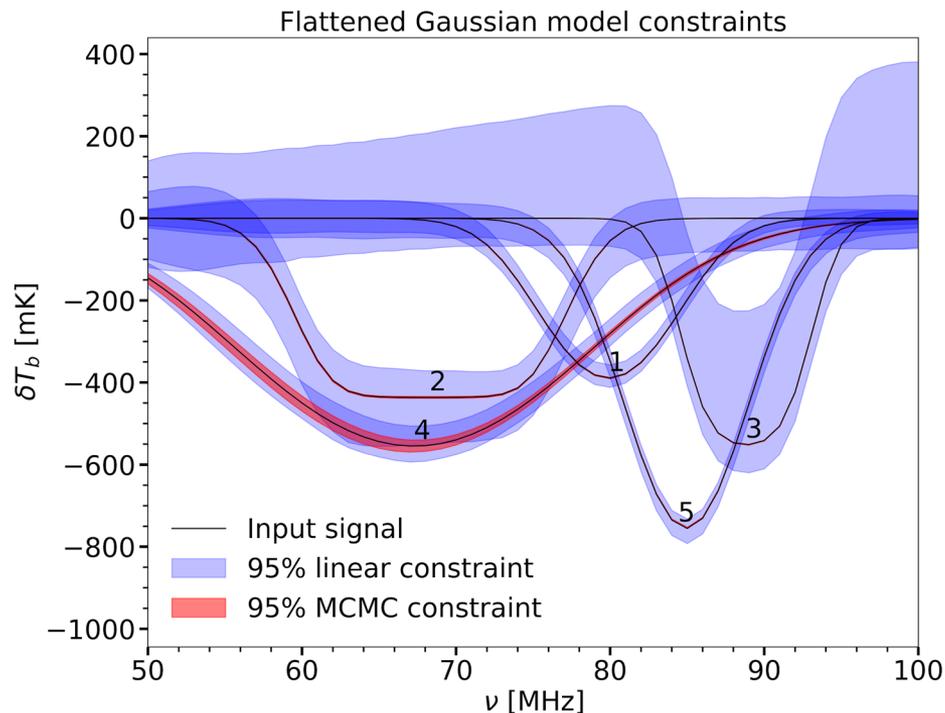
# Effects of induced polarization data on constraints



Note the large scale difference between the plots.

# Results with signal model from EDGES paper

- When using a training set of flattened Gaussian models defined as in EDGES Nature paper (Bowman et al. 2018), we obtain the confidence intervals on the right.
- These simulations include both induced polarization and multiple antenna pointings.



# Summary and ongoing work

- We have been developing a pipeline for extracting the 21-cm global signal from sky-averaged spectral data.
- Our training set based pipeline allows any effect that can be simulated to be included in the analysis.
- In our simulations, we include multiple antenna pointing directions (precursor to drift-scan measurements) and Stokes parameters because they lower the overlap between foreground and signal, decreasing uncertainties.
- In the past year, we have for the first time completed the pipeline to extract physical parameters from our 21-cm signal constraints in frequency space (see David R.'s talk)