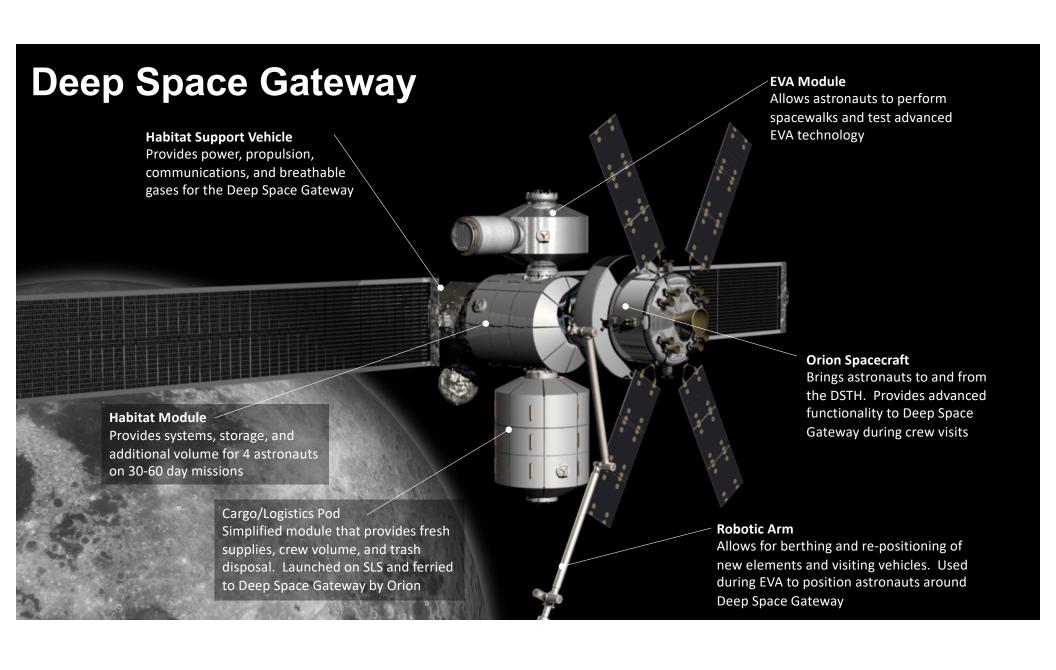
Lockheed Martin Status

- Line of Business Reorganization
- Orion and Secondary Payloads
- Deep Space Gateway
- Robotics

Scott Norris
Tim Cichan
Chris Norman

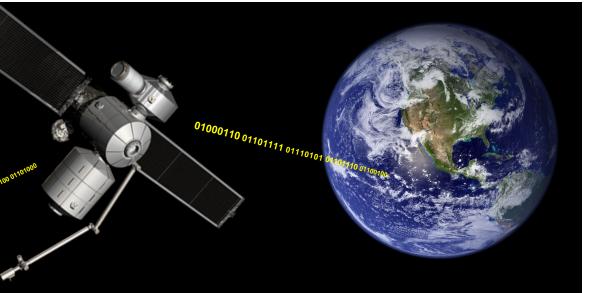








- Communications Relay
- Telerobotics
- Radio Astronomy
- Radiation
- Sample Return



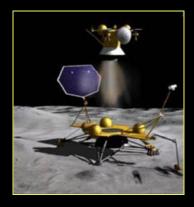
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Rover Image Courtesy MDA



https://sservi.nasa.gov/articles/ telerobotic-antennadeployment/



Lander Graphic Courtesy JPL

Deep Space Gateway Robotics

Design Considerations

- **⋄** Deep Space Habitat
 - Control all robotic systems from single station (manipulator, internal/external free-flyers, surface robotics)
 - Provide multiple methods of control for robotic systems (teleoperation, automated/scripted, task-level autonomous operations)
 - Operator awareness when operating remote systems (image/video display, telemetry handling and display)

⋄ Robotic Systems

- Changes in how the systems are operated will impact how systems are designed (especially power and communications)
- Need to develop operational strategies that support crew focused operation.

♦ LM Status

- Developing use case concepts that drive design and developing requirements for a workstation.
- Investigating use of virtual and augmented reality.

