

Motivation

- Current security systems are location specific, expensive, require human monitoring, and time-consuming to set up
- Design a rapidly deployable remote sensor package that can survive impact, self-orient, and autonomously detect and differentiate between humans and vehicles for at least 30 days

Key Requirements

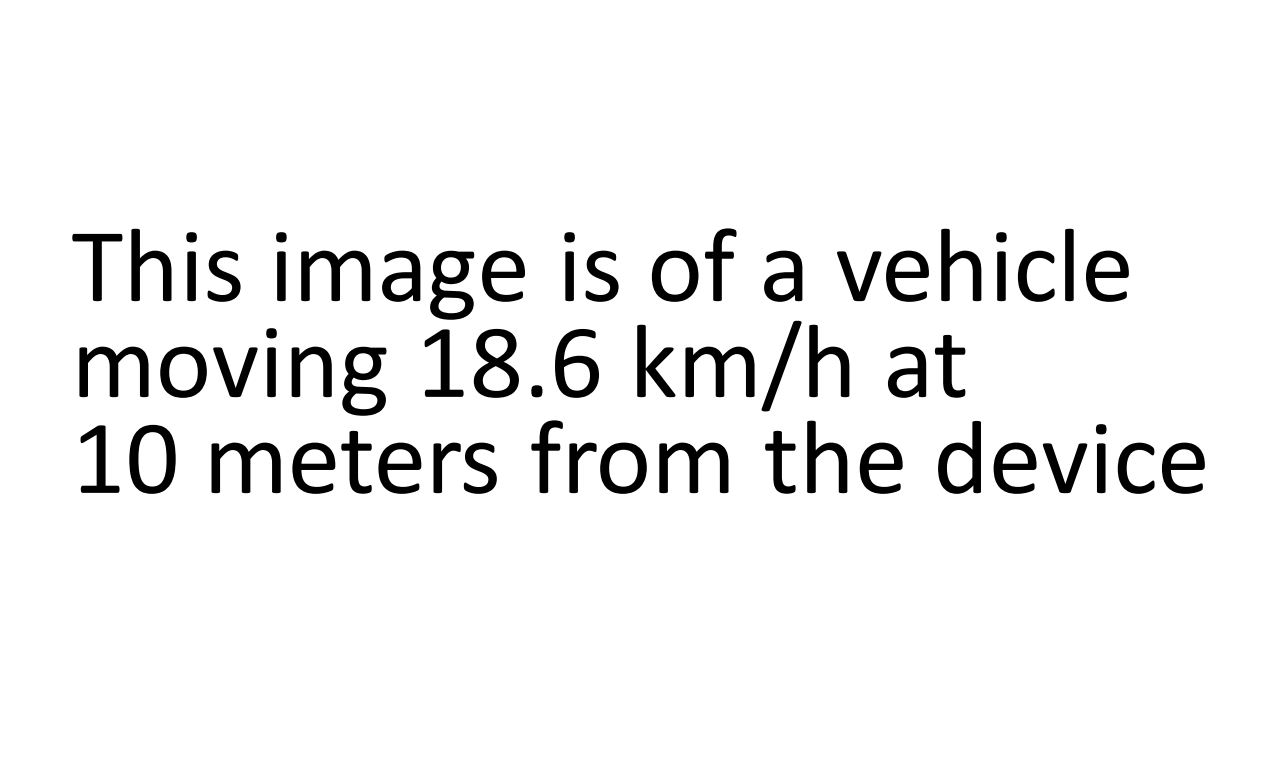
Identify vehicles and people at 10 m	✓
90% detection rate and data transmission	✓
IP54 (weather proofing) rating	TBD
Operational range of -20 to 60 °C	TBD
Single user deployable weighing <16 kg	✓
Withstand a 1.2 m drop and self-orient	✓
Operate for at least 30 days	✓

Testing and Results

- 100% success rate for positive detections within 15 m
- Detected vehicles and people at various speeds and directions of travel
- Passive system alerted up to 80 m away
- Test results met range specifications
- The device survived a max force of 160 G's when it was dropped on its side from 1.4 m

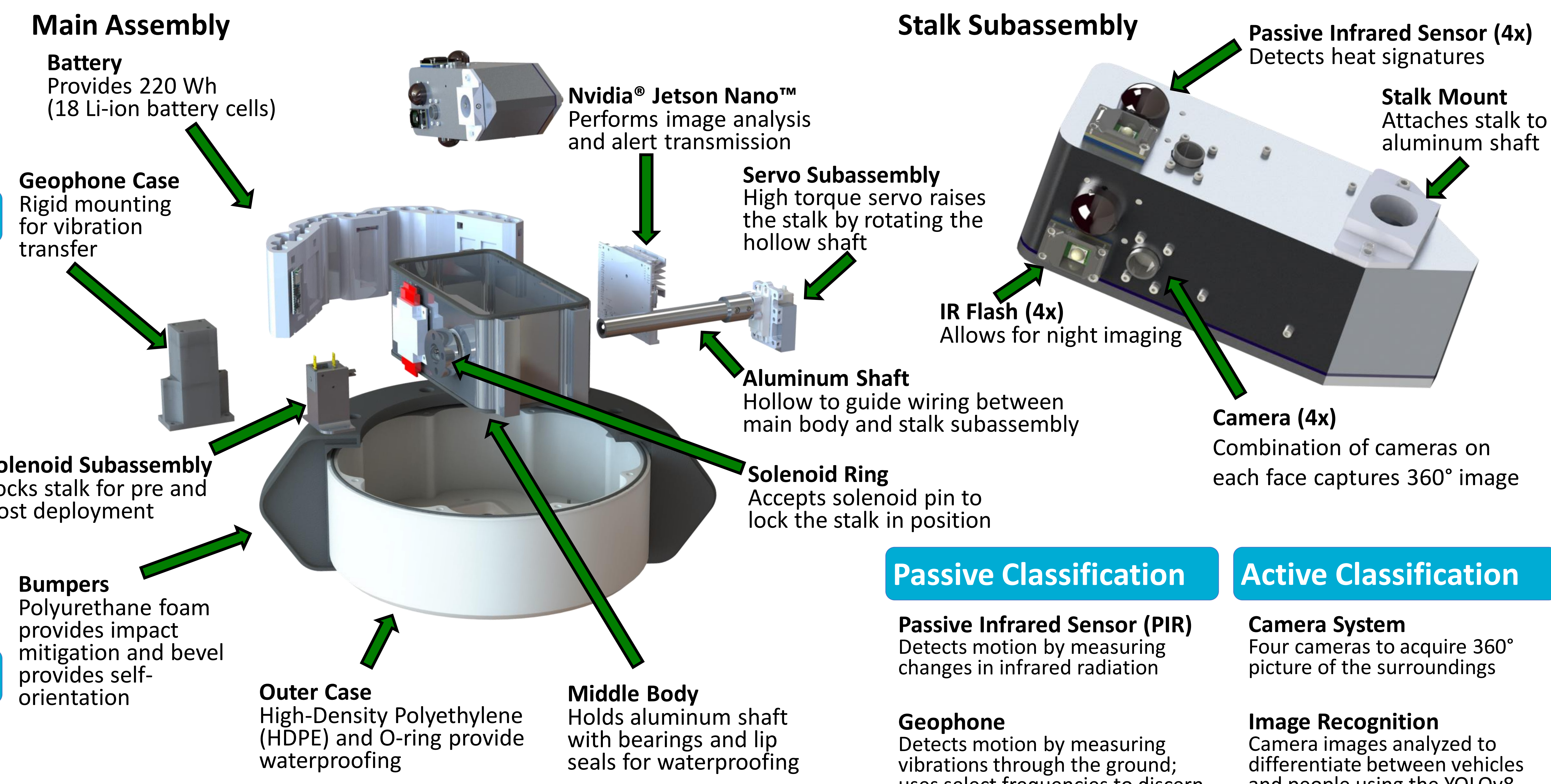


This image is of a person walking at 20 meters from the device



This image is of a vehicle moving 18.6 km/h at 10 meters from the device

Design



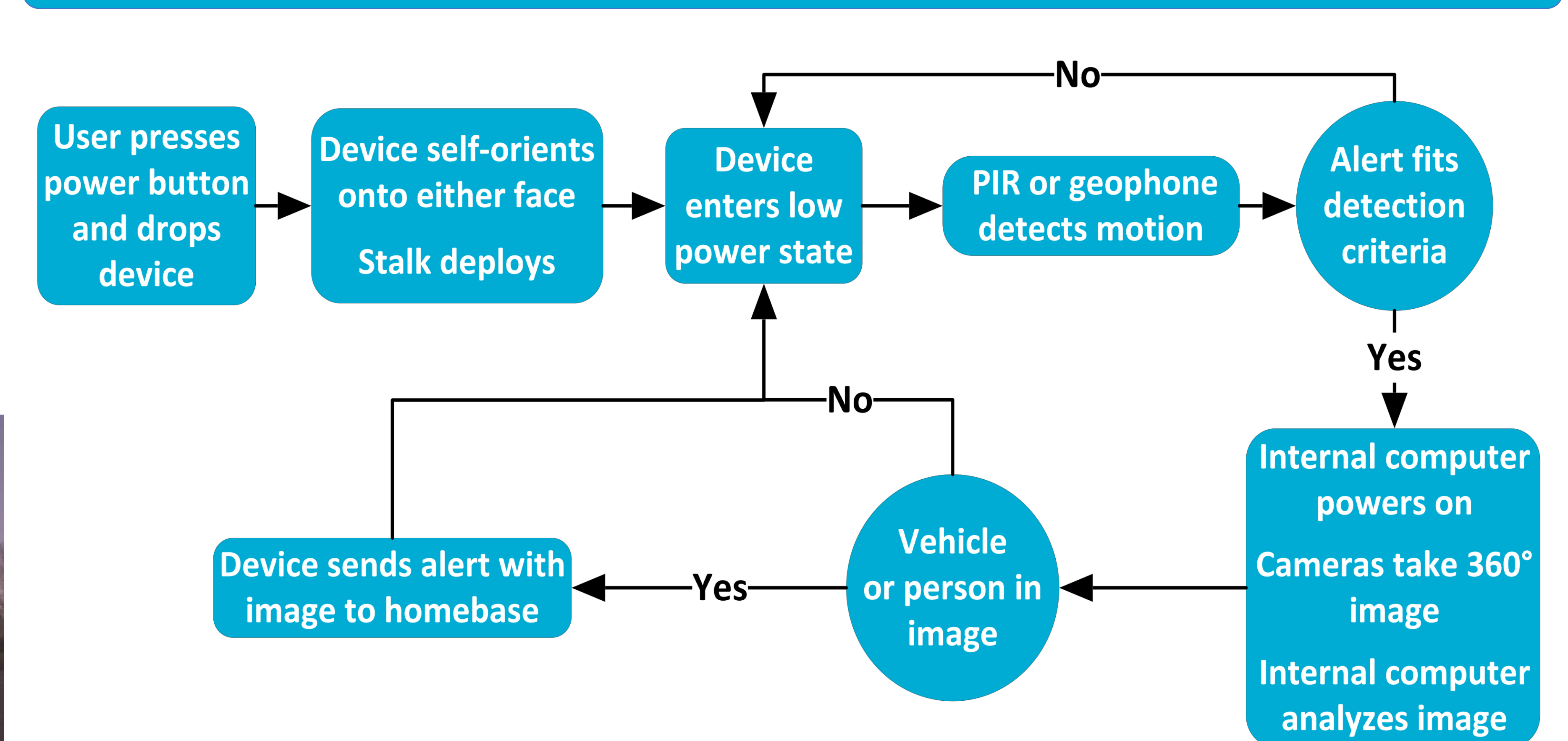
Passive Classification

- Passive Infrared Sensor (PIR)**: Detects motion by measuring changes in infrared radiation
- Geophone**: Detects motion by measuring vibrations through the ground; uses select frequencies to discern between humans and vehicles

Active Classification

- Camera System**: Four cameras to acquire 360° picture of the surroundings
- Image Recognition**: Camera images analyzed to differentiate between vehicles and people using the YOLOv8 model

System Flowchart



Electronics

- Custom designed electronics for <20mW ultra-low power passive operation
- Integrated in-house battery module for energy density
- Analog geophone detection circuit designed from ground up for high sensitivity and ultra-low power with high voltage front-end protection
- A total of 18 PCBs spread across 8 custom designs

