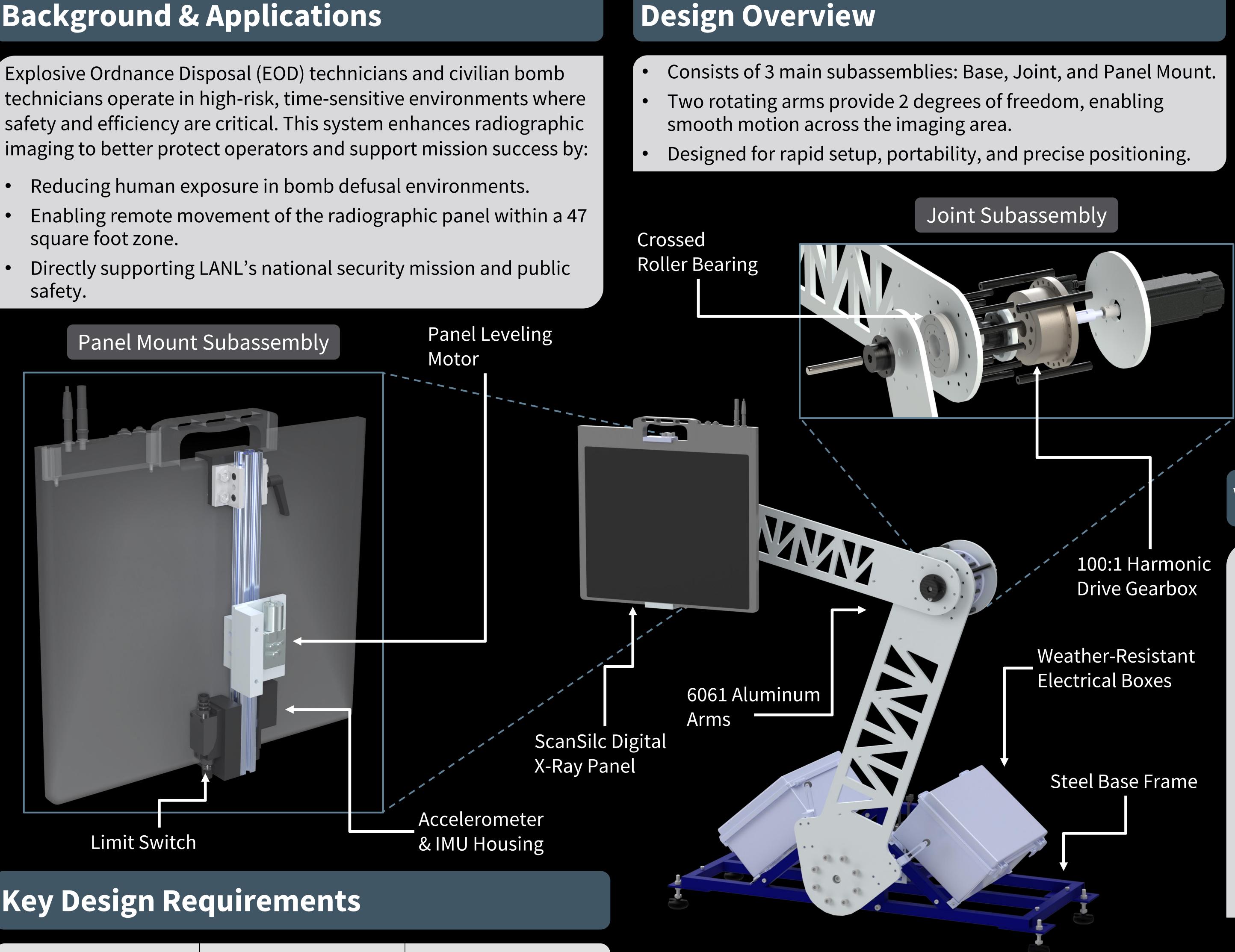


LOS ALGENALIABORATORY

# **Background & Applications**

- square foot zone.
- safety.



## **Key Design Requirements**

General	Performance	Enviro
✓ Setup in ≤10 minutes (2-person)	✓ 68" x 56" minimum imaging area	Gravel, cor
Easily lifted by 2 people (NIOSH)	±0.125" positional accuracy	Withst incline wit
Fit in travel case (40" x 24" x 18")	✓ Position panel in ≤20 seconds	Resistant wind load
Operable by 1 trained user	Panel battery removable in-mount	Weath electronic

A special thanks to: Thomas Noll | Brent Harrington | Dr. Greg Rieker | Dr. Julie Steinbrenner | Dr. Daria Kotys-Schwartz | Victoria Lanaghan | Andy Kain | Chase Logsdon | Patrick Maguire | Greg Potts

# **Automated Radiographic Panel Positioner** Benjamin Green | Daphne Felt | Mateo Medellin | Dylan Mills | Thomas Montgomery | Jakson Praeger | Kyle Varra | Luca Voeller | Bella Wolf

#### onmental

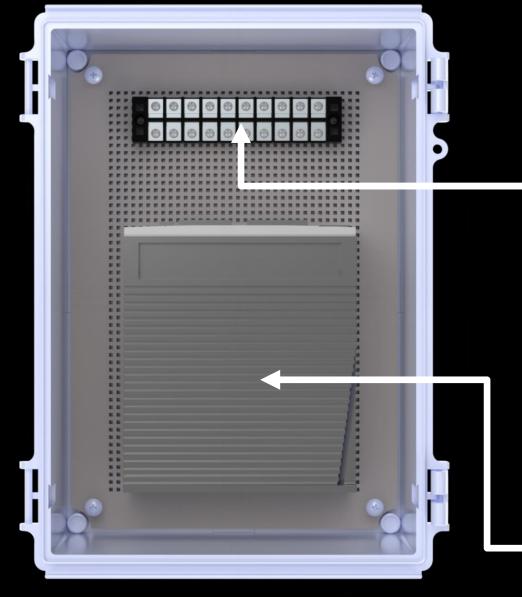
ate on snow, oncrete

stand 10° ithout tipping

tant to light ding (10 mph)

her-resistant electronics housing

#### High Voltage Box



Arduino Uno -Raspberry Pi Voltage Converter -Joint Motor Driver -— Terminal Block — **Base Motor Driver** 

# Software Development

**Motor Control** 

Adjusts motion with

• Drives motors to

target positions

sensor feedback

Ensures accurate

panel placement

### **User Interface**

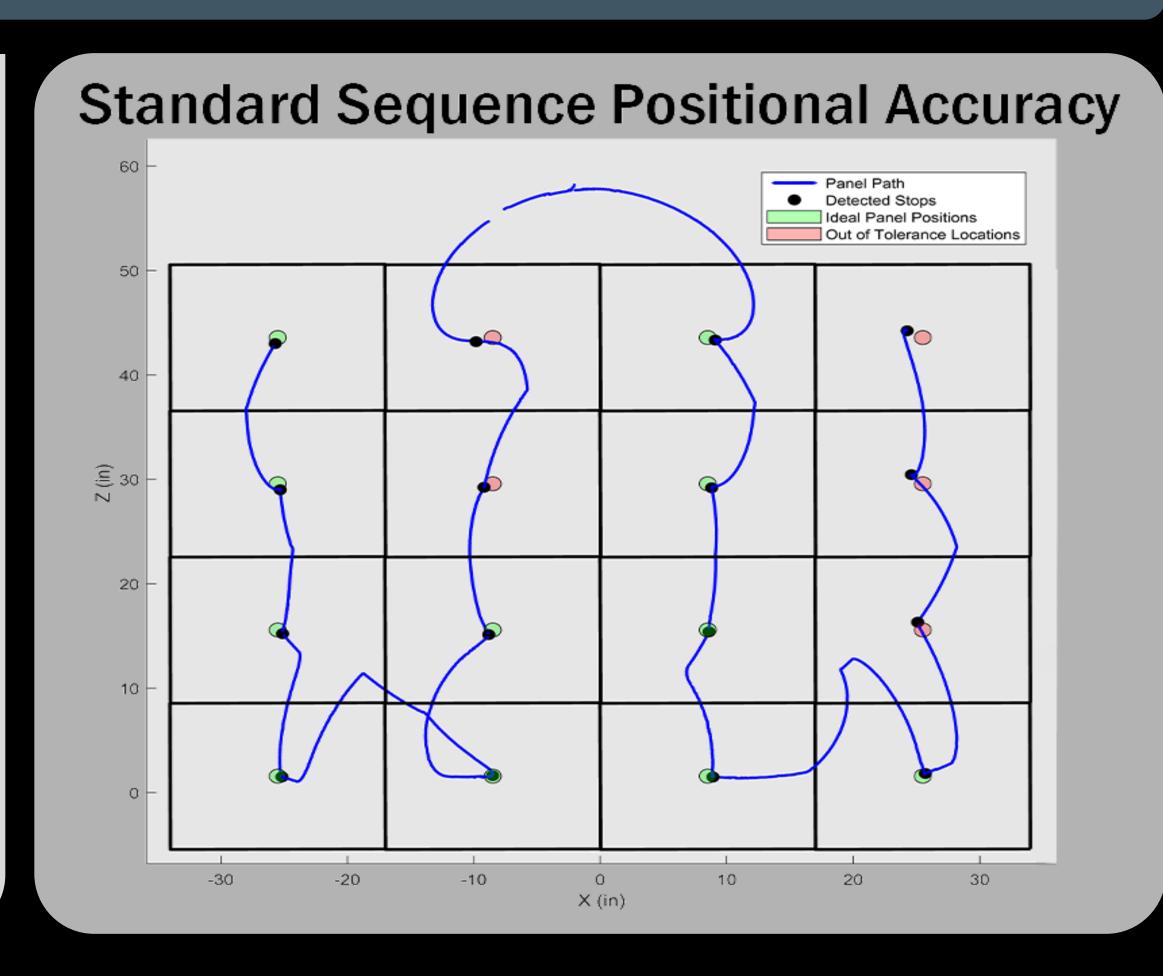
- Input panel destination (manual or sequence)
- Display positioner status (Ready, Moving, Error)
- Confirm/cancel image and select next

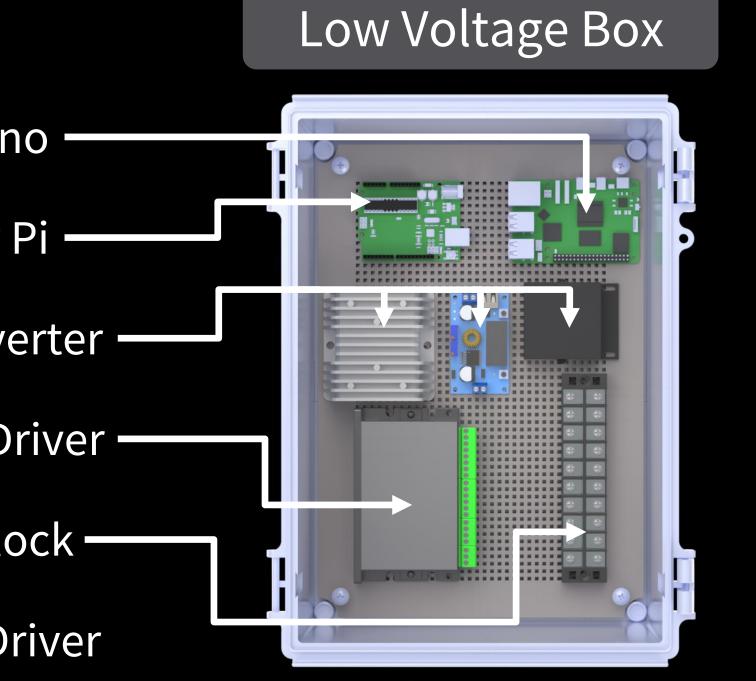
### **Emergency Logic**

- E-stop input override
- Safety abort switch in UI
- Hardware limits

# **Verification & Validation**

- Full autonomous imaging sequence performed by the panel positioner.
- Actual stops remain within ±0.50" of programmed locations.
- Entire scan sequence is completed in under 3 minutes.





# Next Steps & Impact

Los Alamos National Laboratory identifies strong potential for operational use in counterterrorism and national security applications and is interested in continued development focused on:

- deployment.

# COLORADO

## **Motion Planning**

- Calculates panel position
- Plans smooth movement path
- Sends target angles to motors

## **Sensor Feedback**

- Encoders  $\rightarrow$  Joint angles
- Limit switches  $\rightarrow$  Angle calibration
- IMU  $\rightarrow$  Panel leveling, Positional feedback

• Further reducing system weight for improved field portability. Integrating onboard power and panel charging for extended

Enhancing software integration with existing imaging software.