

Background

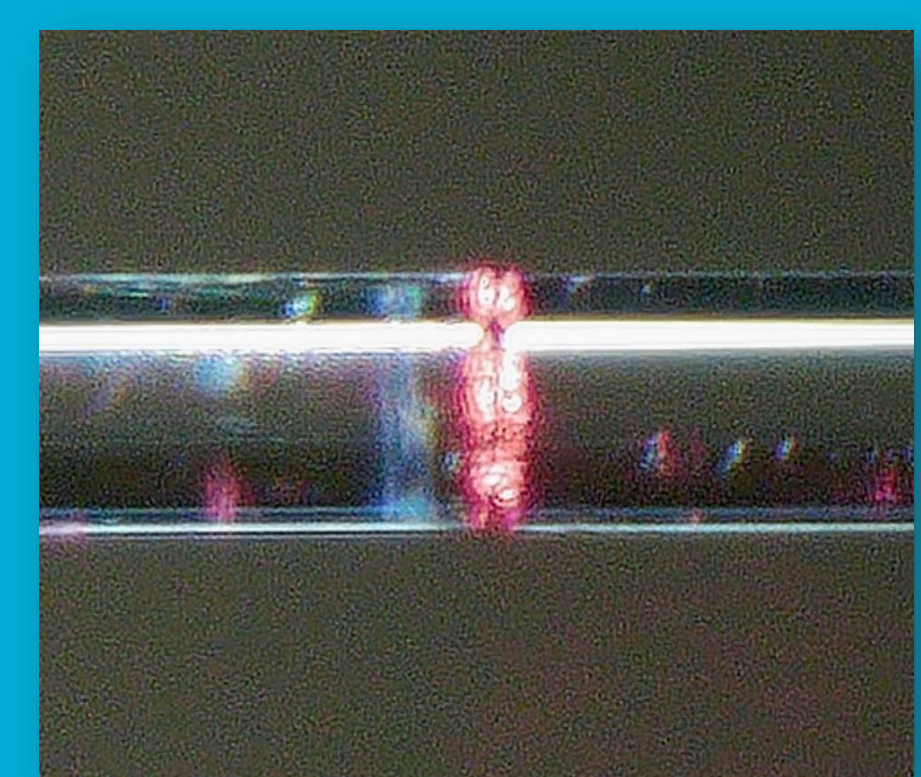
To make **quantum-computing** a reality, SNL is currently working to expand trapped-ion systems to support a larger number of ion qubits. This requires aligning arrays of fiber optics to microscopic precision; a frustrating, time intensive and inefficient process which is currently done by hand.

Objective

- Create an *automated* fiber optic alignment control system
- Streamline coupling process by reducing alignment time
- Create optical connections with less than 2 dB (40%) power loss
- Position fibers ~5 microns apart, while avoiding collisions
- Enable handling and transportation after establishing a connection

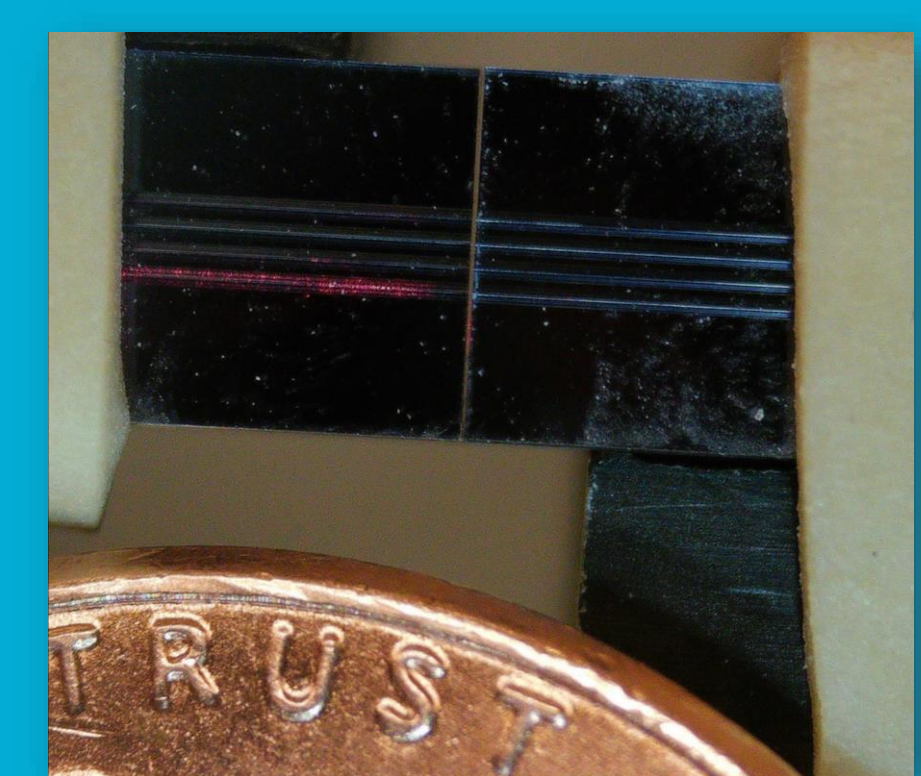
Project Phases

Phase 1: Optical Fiber Alignment



Fiber to fiber: Single optical fibers, with cores 4 microns wide, transmit light using total internal reflection.

Phase 2: V-Groove Alignment

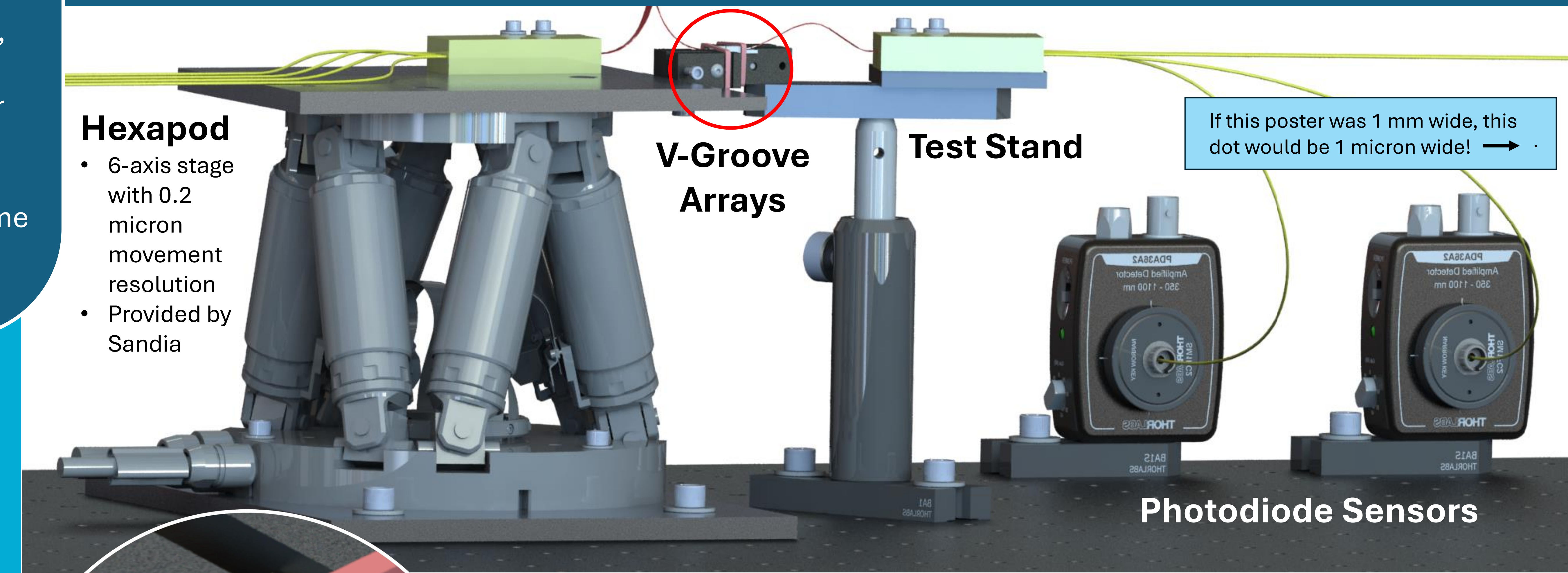


Multiple fibers arranged in a line form a V-groove array, which provides multichannel laser input and thus delivers more power.

Phase 3: Epoxy Connection

Make connection permanent by applying optical epoxy

Test Setup



Hexapod

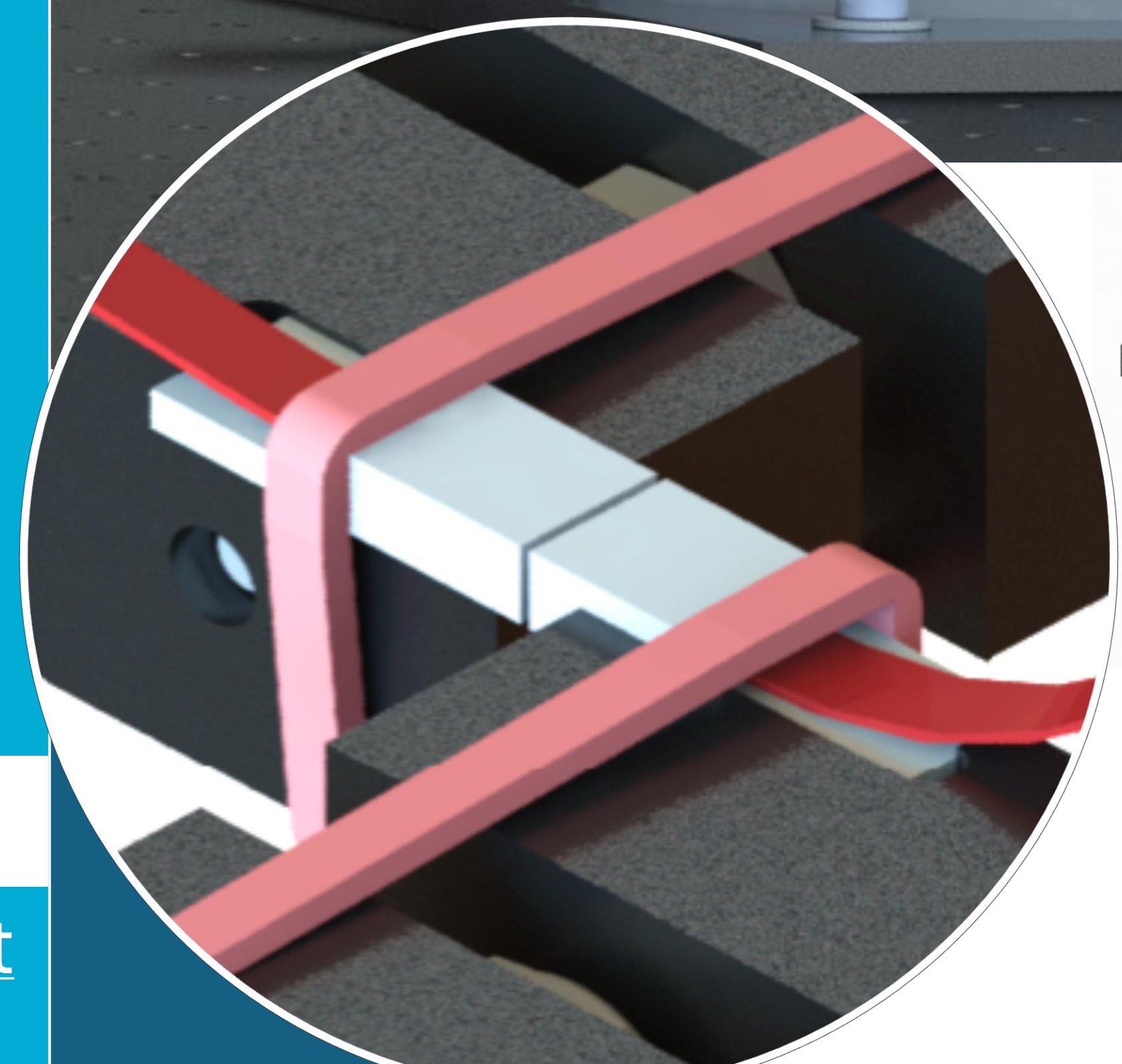
- 6-axis stage with 0.2 micron movement resolution
- Provided by Sandia

V-Groove Arrays

Test Stand

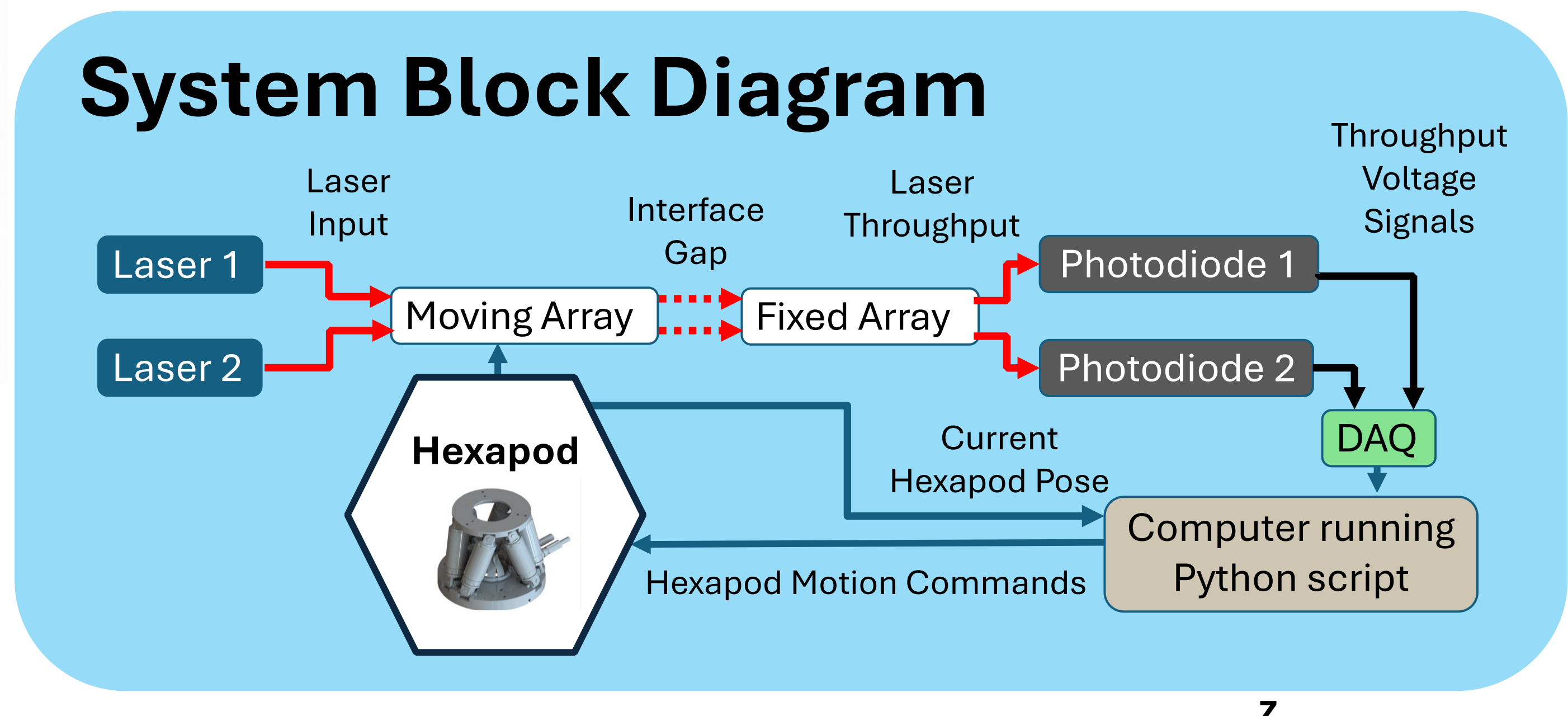
Photodiode Sensors

If this poster was 1 mm wide, this dot would be 1 micron wide! →



V-Groove Fixture

- Uses elastic band to hold V-Groove arrays in place without damaging them
- Adjustable tension with lead screw for fine-tuning

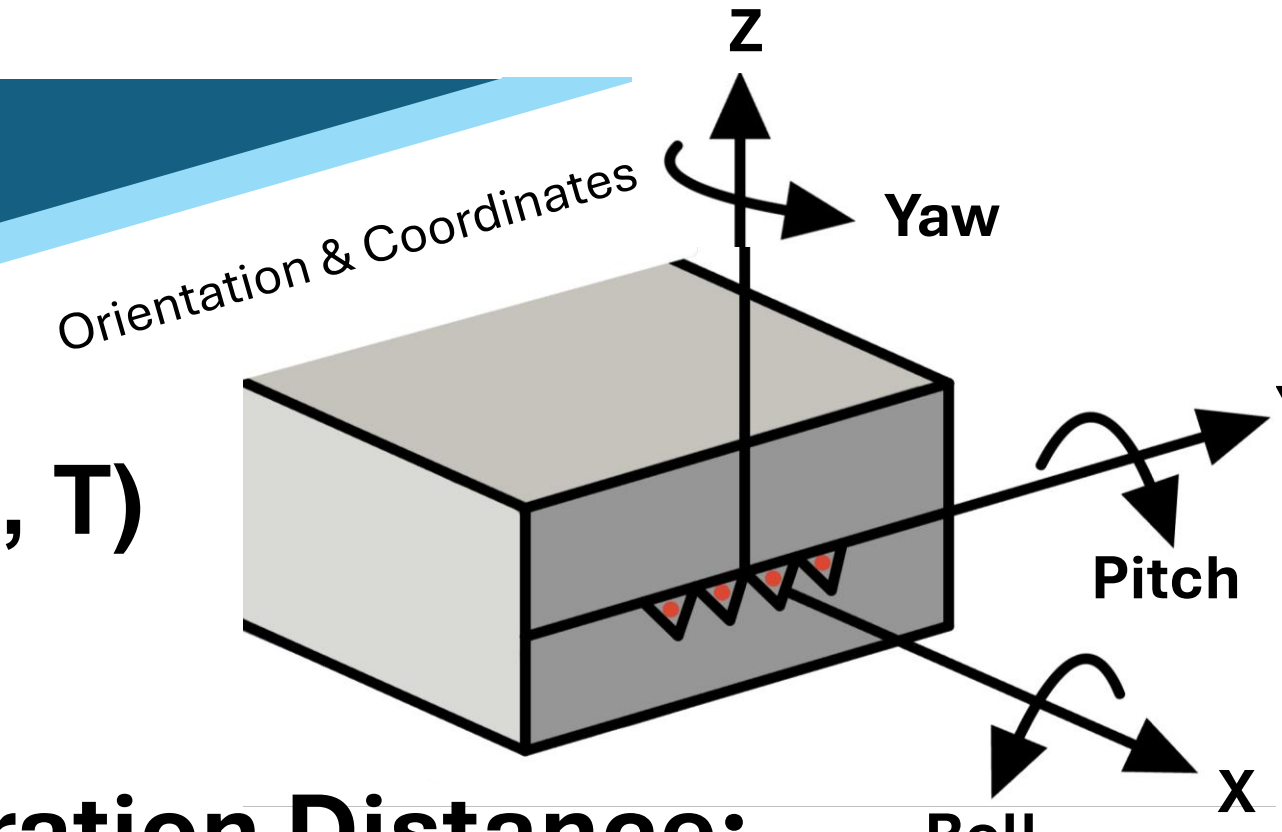


System Block Diagram

Laser 1 and Laser 2 feed into a Moving Array, which is mounted on a Hexapod. The Moving Array is connected to a Fixed Array via an Interface Gap. The Fixed Array feeds into Photodiode 1 and Photodiode 2. The photodiodes output Throughput Voltage Signals to a DAQ. The DAQ outputs Current Hexapod Pose to a Computer running a Python script. The computer outputs Hexapod Motion Commands back to the Hexapod.

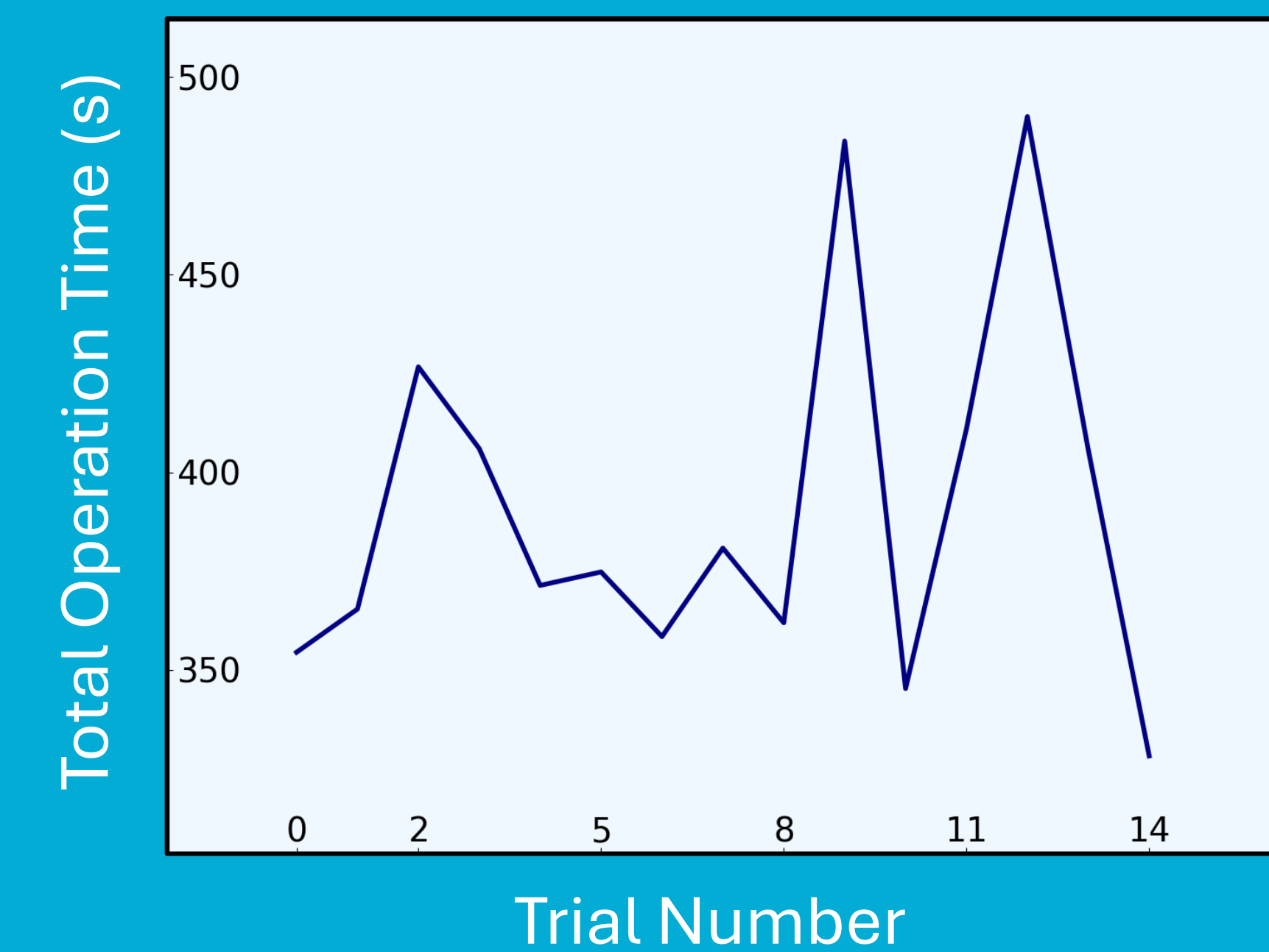
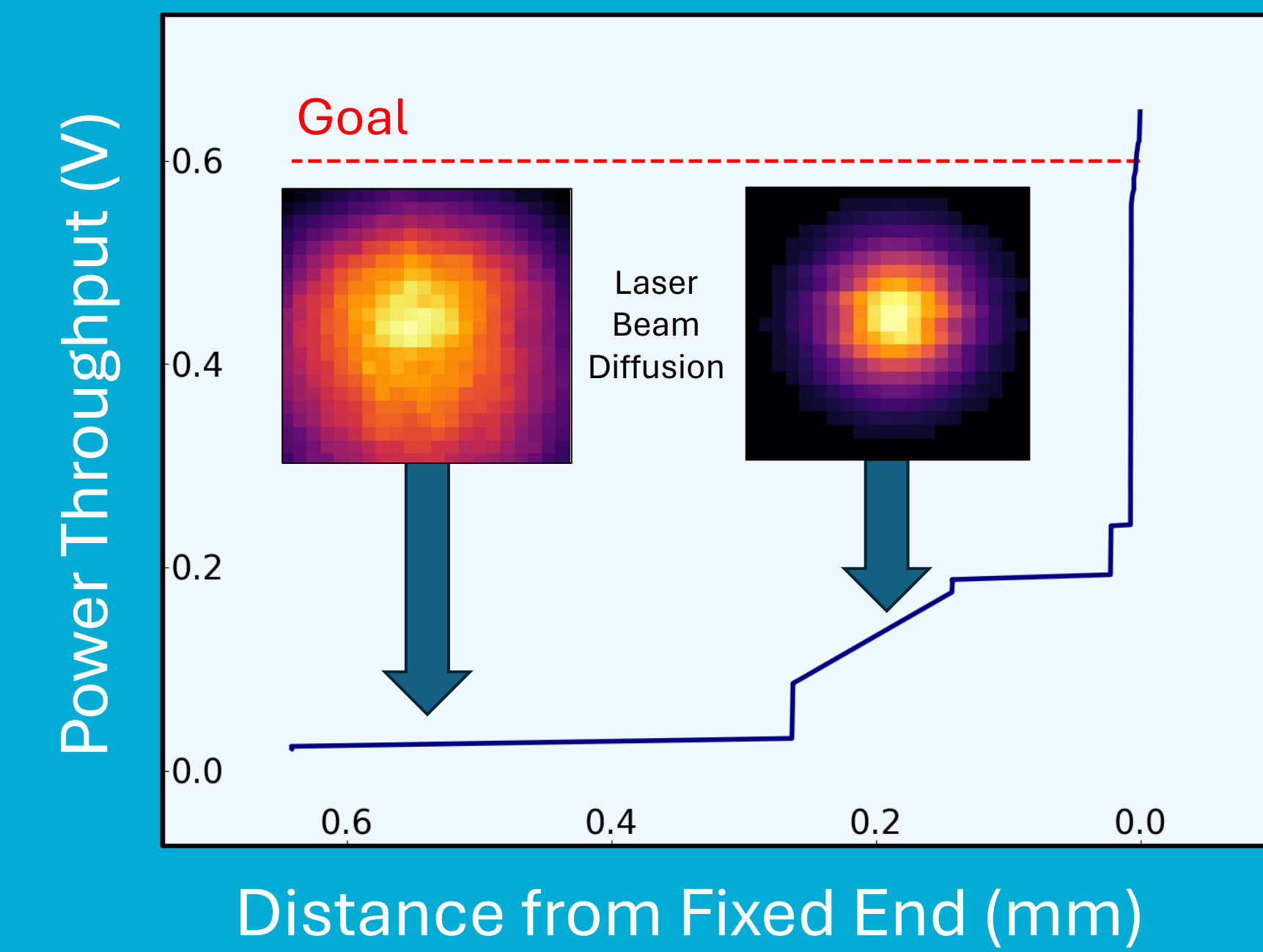
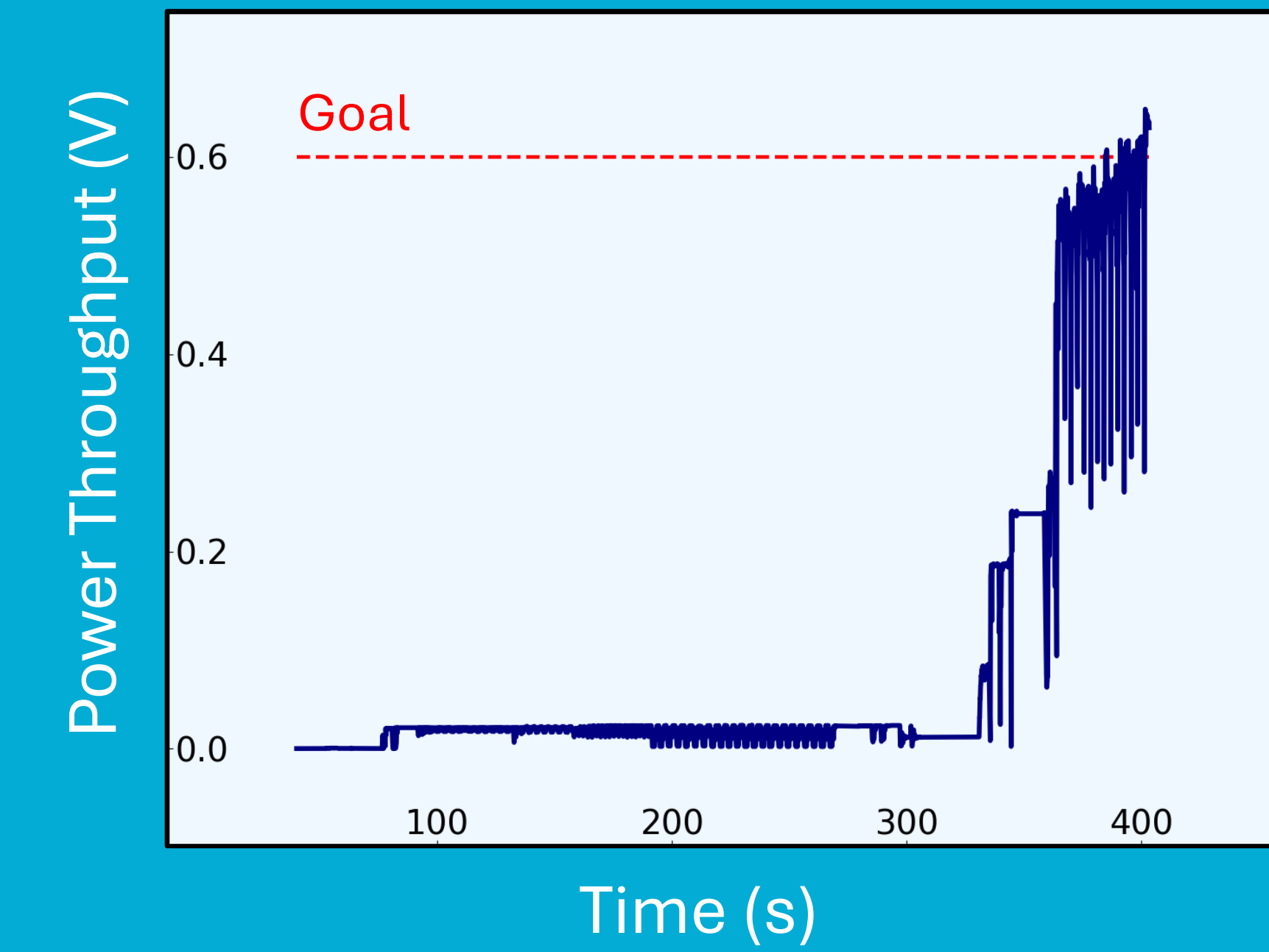
Alignment Procedure

- Optimization problem with **9 degrees of freedom**
- **Inputs:** Cartesian Position (X, Y, Z), Angles (U, V, W), and Rotation Point Coordinates (R, S, T)
- **Outputs:** Voltage Readings from Photodiodes 1 & 2



- 1 Initial Scan:** After rough manual alignment, hexapod moves in a spiral pattern until significant signal is detected.
- 2 Find Local Maximum in YZ plane:** Use Golden Section Search algorithm to find optimum power throughput at current distance.
- 3 Calculate Separation Distance:** Use beam diffusion radius to estimate remaining distance.
- 4 Optimize Rotation Point:** Use Golden Section Search to find a rotation point in 3D space that minimizes throughput difference before and after a slight rotation.
- 5 Align Angles:** Now that the angles have been isolated from the cartesian dimensions, optimize the pitch, yaw and roll. Roll is optimized using the second laser.
- 6 Final Approach:** Move forward towards the fixed v-groove array. Distance is inferred based on throughput voltage. Repeat until desired throughput is achieved!

Results/Analysis



Impact

- ✓ Automation creates a consistent and repeatable process
- ✓ Alignment time reduced
- ✓ Opportunity for alignment using multiple fiber optic cables
- ✓ First step towards scalability with epoxied connection
- ✓ Paves the way for the quantum-computing revolution