Note: this is an example of a checklist that might be used for a typical multirotor, such as a DJI Mavic. The PIC is responsible for knowing the specific procedures needed to safely operate their specific aircraft type, and is responsible for executing those procedures according to a checklist.

Normal Procedures

**PREFLIGHT ACTION**

NOTAM …………………………………… FILED

MAITENANCE ISSUES………………. RESOLVED

**PREFLIGHT INSPECTION**

FLIGHT BATTERY……………………… VERIFY CHARGED

CONTROLLER BATTERY……………. VERIFY CHARGED

CONTROLLER ANTENNAE………… UNFOLD

GIMBAL LOCK………………………….. REMOVE

AIRCRAFT ARMS……………………… UNFOLD

PROPELLERS……………………………. UNFOLD

PROPELLER ATTACHMENT………. VERIFY SECURE

FLIGHT-CRITICAL A/C DAMAGE.. NONE

BATTERY…………………………………. INSTALL

**POWER UP**

CONTROLLER POWER……………… ON

CONTROLLER APP READY………… CHECK

AIRCRAFT POWER……………………. ON

**BEFORE TAKEOFF**

PREFLIGHT BRIEFING………………. COMPLETE

TAKEOFF LOCATION………………… CLEAR

AIRCRAFT STATUS…………………… READY

**BEFORE LANDING**

LANDING BRIEFING…………………. COMPLETE

LANDING LOCATION……………….. CLEAR

**POSTFLIGHT**

AIRCRAFT POWER…………………… OFF

CONTROLLER POWER……………… OFF

CONTROLLER ANTENNAE……….. STOW

PROPELLERS……………………………. STOW

AIRCRAFT ARMS……………………… STOW

GIMBAL LOCK………………………….. INSTALL

POSTFLIGHT BRIEFING…………….. COMPLETE

Emergency Procedures

**BATTERY BELOW 15 PERCENT**

LAND IMMEDIATELY

**AIRCRAFT CONTROL LINK LOST**

RETURN-TO-HOME………………….. ATTEMPT

If unsuccessful:

MOTOR CUTOFF……………………….ATTEMPT

If unsuccessful:

NEAREST AIRPORT…………………… CONTACT

*Provide altitude, time remaining, and direction of flight*