# DISCUSSION PAPERS IN ECONOMICS 

Working Paper No. 06-09

New Tests for Cointegration in Heterogeneous Panels

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November 2006

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#### Abstract

This paper makes the following contributions to the existing literature on panel cointegration. First, two new tests based on the principle of weighted symmetric estimation are proposed for panel cointegration testing. Second, the asymptotic distributions of these new tests are examined, and these are shown to be well defined Weiner processes that are free of nuisance parameters. Third, the size and power properties of the proposed tests are studied with a Monte Carlo simulation, and their properties are found to be superior to those of the existing tests across a range of environments.

Keywords: Panel coingtegration test; heterogeneous panel data JEL classification: C12; C15; C22; C23


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## 1 Introduction

Panel data is commonly used in empirical research today by economists. Following the study of unit root tests in panels, research examining the properties of non-stationary time series in panel form is becoming more and more developed. Kao (1997) and Pedroni (1997) proposed the original tests for cointegration in panels under the null of no cointegration, and these tests are the most commonly used tests in empirical work. The Kao (1997) test is used for homogeneous panels. Pedroni(1997) gives two sets of statistics: the first set is for testing cointegration in homogeneous panels and the second set of statistics is for testing cointegration in heterogeneous panels.

McCoskey and Kao (1998) proposed the use of the average of the Augmented DickeyFuller (ADF) statistics over cross-sections based on Im et al.(1997) to test the hypothesis of no cointegration in heterogeneous panels.

In this paper, based on the idea of Maddala and Wu (1999) of using the Fisher test and the previously known weighted symmetric (WS) estimation, we proposed three new tests: the average weighted symmetric (AWS) test, the Fisher-ADF (FADF) test and the Fisher weighted symmetric (FWS) test, for testing cointegration in heterogeneous panels with the null hypothesis of no cointegration.

Although weighted symmetric estimation was first introduced by Park and Fuller (1993), this estimation method has not been used by economists doing empirical work in time series. Weighted symmetric estimation usually brings better results compared with the Dickey-Fuller (DF) and ADF estimations, the most commonly used estimation methods in time series. It was shown by Pantula et al. (1994) that the test using weighted symmetric estimation is the most powerful test for testing unit roots in a single time series. Hoang and McNown (2006) found that weighted symmetric estimation also dominates the other estimation methods in testing unit roots in panel data in terms of test power. In testing cointegration in hetero-
geneous panels where the cointegration vectors are allowed different between cross-sections, the Pedroni, McCoskey and Kao tests are the only choices for researchers now. Pedroni uses the DF estimation and adjusts the statistics as the Phillips-Perron test for unit roots, while McCoskey and Kao use the ADF estimation and average the test statistics over crosssections. The purpose of this study is to give more options for testing for cointegration in heterogeneous panels when the weighted symmetric estimation is used instead of DF or ADF estimation. The asymptotic distribution of weighed symmetric estimator in residual-based testing for cointegration in a set of single series is also derived and it is shown that the limiting distribution of WS estimators in testing cointegration is a function of standard Wiener processes and free of nuisance parameters.

A Monte-Carlo investigation is conducted to examine the performance of the available tests and the proposed tests under different data generating processes (DGPs). Consistent with what is already known about the weighted symmetric estimation, the AWS and FWS tests turn out to be the tests with the best performance, as they consistently dominate the rest of the compared tests in both size and power and in all studied data environments.

This study makes the following contributions to the existing literature on panel cointegration. First, two new tests based on the principle of weighted symmetric estimation are proposed for panel cointegration testing. Second, the asymptotic distributions of these new tests are examined, and these are shown to be well defined Weiner processes that are free of nuisance parameters. Third, the size and power properties of the proposed tests are studied with a Monte Carlo simulation, and their properties are found to be superior to those of the existing tests across a range of environments.

## 2 Current Tests for Cointegration in Panel Data

### 2.1 Testing for Cointegration in Homogeneous Panels

Chihwa Kao (1997) considered the following system of cointegrated regressions in the homogeneous panels:

Let

$$
\begin{aligned}
& x_{i t}=x_{i t-1}+\epsilon_{i t} \\
& y_{i t}=y_{i t-1}+v_{i t}
\end{aligned}
$$

Consider the regression:

$$
\begin{gather*}
y_{i t}=\alpha_{i}+x_{i t} \beta+u_{i t}  \tag{1}\\
(i=1, \ldots, N, t=1, \ldots, T)
\end{gather*}
$$

where $\alpha_{i}$ are individual constant terms, $\beta$ is the slope parameter, $\epsilon_{i t}, v_{i t}$ are stationary distubance terms and so $y_{i t}$ and $x_{i t}$ are integrated processes of order 1 for all $i$

The zero mean vector $\xi_{i t}=\left(v_{i t}, \epsilon_{i t}\right)^{\prime}$ satisfies

$$
\frac{1}{\sqrt{T}} \sum_{t=1}^{[T r]} \xi_{i t} \Longrightarrow B_{i}(\Omega)
$$

for all $i$ as $T \longrightarrow \infty$, where $B_{i}(\Omega)$ is a vector of Brownian motion with asymptotic covariance $\Omega$. Kao derives two types of panel cointegration tests based on residuals from panel least-squares dummy variable (LSDV) estimation.

The first is of a Dickey-Fuller (DF) type, which can be applied to the residuals using:

$$
\begin{equation*}
\hat{u}_{i t}=\rho \hat{u}_{i t-1}+e_{i t} \tag{2}
\end{equation*}
$$

The OLS estimate of $\rho$ is:

$$
\hat{\rho}=\frac{\sum_{i=1}^{N} \sum_{t=2}^{T} \hat{u}_{i t} \hat{u}_{i t-1}}{\sum_{i=1}^{N} \sum_{t=2}^{T} \hat{u}_{i t-1}^{2}}
$$

The null hypothesis that $\rho=1$ is tested by:

$$
\sqrt{N} T(\hat{\rho}-1)=\frac{\frac{1}{\sqrt{N}} \sum_{i=1}^{N} \frac{1}{T} \sum_{t=2}^{T} \hat{u}_{i t-1} \Delta \hat{u}_{i t}}{\frac{1}{N} \sum_{i=1}^{N} \frac{1}{T^{2}} \sum_{t=2}^{T} \hat{u}_{i t-1}^{2}}
$$

The second is an Augmented-Dickey-Fuller(ADF) type test which can be calculated from:

$$
\begin{equation*}
\hat{u}_{i t}=\rho \hat{u}_{i t-1}+\sum_{j=1}^{p} \phi_{j} \Delta \hat{u}_{i t-j}+e_{i t p} \tag{3}
\end{equation*}
$$

where p is chosen so that the residuals $e_{i t p}$ are serially uncorrelated. The ADF test statistic here is the usual t-statistic with $\rho=1$ in the ADF equation.

The following specification of null and alternative hypotheses is used: $H_{0}: \rho=1$, $H_{1}: \rho<1$.

Kao proposes four DF-type statistics and an ADF statistic. The first two DF statistics are based on assuming strict exogeneity of the regressors with respect to the errors in the equation, while the remaining two DF statistics allow for endogeneity of the regressors. The DF statistic, which allows for endogeneity, and the ADF statistic involve deriving some nuisance parameters from the long-run conditional variances $\Omega$.

Kao showed that the asymptotic distributions of all tests converge to a standard normal distribution as $T \longrightarrow \infty$ and $N \longrightarrow \infty$

Kao is the first author to suggest the test for cointegration in homogeneous panels, The Kao test statistics are calculated by pooling all the residuals of all cross-sections in the panel. It is assumed in Kao's test that all the cointegrating vectors in every cross-section are identical.

### 2.2 Testing for Cointegration in Heterogeneous Panels

### 2.2.1 Pedroni (1997)

Pedroni (1997) considers the following model for heterogeneous panel data

$$
\begin{gather*}
y_{i t}=\alpha_{i}+x_{i t} \beta_{i}+u_{i t}  \tag{4}\\
(i=1, \ldots, N, t=1, \ldots, T)
\end{gather*}
$$

For the processes:

$$
\begin{aligned}
& x_{i t}=x_{i t-1}+\epsilon_{i t} \\
& y_{i t}=y_{i t-1}+v_{i t}
\end{aligned}
$$

where $\alpha_{i}$ are individual constant terms, $\beta_{i}$ is the slope parameter for the cross-section i of the panel, $\epsilon_{i t}, v_{i t}$ are stationary disturbance terms and so $y_{i t}$ and $x_{i t}$ are integrated processes of order 1 for all $i$

The zero mean vector $\xi_{i t}=\left(v_{i t}, \epsilon_{i t}\right)^{\prime}$ is assumed to satisfy

$$
\frac{1}{\sqrt{T}} \sum_{t=1}^{[T r]} \xi_{i t} \Longrightarrow B_{i}\left(\Omega_{i}\right)
$$

for each cross-section $i$ as $T \longrightarrow \infty$, where $B_{i}\left(\Omega_{i}\right)$ is a vector of Brownian motion on the interval $r \in[0,1]$ with asymptotic covariance $\Omega_{i}$. The asymptotic covariance matrix $\Omega_{i}$ is given by:

$$
\Omega_{i}=\lim _{T \rightarrow \infty} E\left[\frac{1}{T}\left(\sum_{t=1}^{T} \xi_{i t}\right)\left(\sum_{t=1}^{T} \xi_{i t}^{\prime}\right)\right]
$$

and can be decomposed as:

$$
\Omega_{i}=\Sigma_{i}+\Gamma_{i}+\Gamma_{i}^{\prime}
$$

where $\Sigma_{i}=\lim _{T \rightarrow \infty} \frac{1}{T} \sum_{t=1}^{T} E\left(\xi_{i t} \xi_{i t}^{\prime}\right)$ is the contemporaneous covariance among the components of $\xi_{i t}$ for a given cross section i, $\Gamma_{i}=\lim _{T \rightarrow \infty} \frac{1}{T} \sum_{k=1}^{T-1} \sum_{t=k+1}^{T} E\left(\xi_{i t} \xi_{i t-k}^{\prime}\right)$ is the dynamic covariance among the components of $\xi_{i t} . \Omega_{i}$ is permitted to vary across individual sections of the panel. $\Omega_{i}$ can be consistently estimated by:

$$
\hat{\Omega}_{i}=\hat{\Sigma}_{i}+\hat{\Gamma}_{i}+\hat{\Gamma}_{i}^{\prime}
$$

or

$$
\begin{equation*}
\hat{\Omega}_{i}=\frac{1}{T}\left[\sum_{t=1}^{T} \hat{\xi}_{i t} \hat{\xi}_{i t}^{\prime}+\sum_{s=1}^{k_{i}}\left(1-\frac{s}{k_{i}+1}\right) \sum_{t=s+1}^{T}\left(\hat{\xi}_{i t-s} \hat{\xi}_{i t}^{\prime}+\hat{\xi}_{i t} \hat{\xi}_{i t-s}^{\prime}\right)\right] \tag{5}
\end{equation*}
$$

where $\hat{\xi}_{i t}=\left(\hat{v}_{i t}, \hat{\epsilon}_{i t}\right)^{\prime}$ is obtained from autoregressions: $x_{i t}=\rho_{i} x_{i t-1}+\epsilon_{i t}$ and $y_{i t}=\rho_{i} y_{i t-1}+v_{i t}$ for each i. Define $L_{i}$ is the lower triangular decomposition matrix of $\Omega_{i}$ :

$$
\Omega_{i}=L_{i}^{\prime} L_{i}=\left[\begin{array}{cc}
L_{11 i} & L_{21 i} \\
0 & L_{22 i}
\end{array}\right]\left[\begin{array}{cc}
L_{11 i} & 0 \\
L_{21 i} & L_{22 i}
\end{array}\right]
$$

Then

$$
\begin{equation*}
L_{11 i}=\left(\Omega_{11 i}-\Omega_{21 i}^{2} / \Omega_{22 i}\right)^{1 / 2} ; L_{21 i}=\Omega_{21 i} / \Omega_{22 i}^{1 / 2} ; L_{22 i}=\Omega_{22 i}^{1 / 2} \tag{6}
\end{equation*}
$$

Pedroni derived two groups of test statistics. The first group is accounted for in homogeneous panels under the assumption that $\Omega_{i}=\Omega$ for all i. The second groups of test statistics is for heterogeneous panels which allows the cointegration vector to vary across the cross sections and $\Omega_{i}$ are different in each section of panels. We focus on the second group of test statistics. Pedroni constructed the statistics as follows: In the first step one can estimate the proposed cointegrating regression for each individual member of the panel in the form (4) $y_{i t}=\alpha_{i}+x_{i t} \beta_{i}+u_{i t}$. Next, use the original data to estimate $\hat{\xi}_{i t}$ by regressing the levels of $x_{i t}$ and $y_{i t}$ on the lagged levels and use these values of $\hat{\xi}_{i t}$ to estimate the appropriate long run covariances $\hat{\Omega}_{i}$ for each member of the panel as in (5). Then collect the residuals $\hat{u}_{i t}$
from the separate regression for each panel member (4) and compute the lower triangular decomposition of the $\hat{\Omega}_{i}$ given in (5). Finally, run the following regression for each member of the panel:

$$
\begin{equation*}
\hat{u}_{i t}=\hat{\rho}_{i} \hat{u}_{i t-1}+\hat{e}_{i t} \tag{7}
\end{equation*}
$$

and construct the group mean statistics for the null of no cointegration in heterogeneous panels as:

$$
\begin{gather*}
\tilde{Z}_{\hat{\rho}_{N T}-1}=\sum_{i=1}^{N} \frac{\sum_{t=1}^{T}\left(\hat{u}_{i t-1} \Delta \hat{u}_{i t}-\hat{\lambda}_{i}\right)}{\sum_{t=1}^{T} \hat{u}_{i t-1}^{2}}  \tag{8}\\
\tilde{Z}_{t_{N T}}=\sum_{i=1}^{N} \frac{\sum_{t=1}^{T}\left(\hat{u}_{i t-1} \Delta \hat{u}_{i t}-\hat{\lambda}_{i}\right)}{\left[\sum_{t=1}^{T} \frac{1}{\hat{L}_{11 i}^{2}} \hat{u}_{i t-1}^{2}\right]^{1 / 2}} \tag{9}
\end{gather*}
$$

Where $\hat{L}_{11 i}=\left(\hat{\Omega}_{11 i}-\hat{\Omega}_{21 i}^{2} / \hat{\Omega}_{22 i}\right)^{1 / 2} . \hat{\Omega}_{i}$ is estimated as in (5). $\hat{\lambda}_{i}=\frac{1}{2}\left(\hat{\sigma}_{i}^{2}-\hat{s}_{i}^{2}\right)$, for which, $\hat{s}_{i}^{2}$ is the contemporaneous variance of $\hat{e}_{i t}$ and $\hat{\sigma}_{i}^{2}$ is the long-run variance of $\hat{e}_{i t}$, they are consistently estimated by:

$$
\begin{gather*}
\hat{s}_{i}^{2}=\frac{1}{T} \sum_{t=1}^{T} \hat{e}_{i t}^{2}  \tag{10}\\
\hat{\sigma}_{i}^{2}=\frac{1}{T}\left[\sum_{t=1}^{T} \hat{e}_{i t}^{2}+2 \sum_{s=1}^{k_{i}}\left(1-\frac{s}{k_{i}+1}\right) \sum_{t=s+1}^{T} \hat{e}_{i t} \hat{e}_{i t-s}\right] \tag{11}
\end{gather*}
$$

Pedroni showed that under the null of no cointegration $\left(\rho_{i}=1 i=1,2, . ., N\right.$ in the equation $\left.\hat{u}_{i t}=\hat{\rho}_{i} \hat{u}_{i t-1}+\hat{e}_{i t}\right) \cdot \frac{T}{\sqrt{N}} \tilde{Z}_{\hat{\rho}_{N T}-1}$ and $\frac{1}{\sqrt{N}} \tilde{Z}_{\hat{t}_{N T}}$ converge to the normal distributions with both T and $\mathrm{N} \longrightarrow \infty$. With the Monte-Carlo results the asymptotic distributions of these statistics can be written as:

$$
\begin{equation*}
\frac{T}{\sqrt{N}} \tilde{Z}_{\hat{\rho}_{N T}-1}+9.05 \sqrt{N} \xrightarrow{L} N(0,35.98) \tag{12}
\end{equation*}
$$

$$
\begin{equation*}
\frac{1}{\sqrt{N}} \tilde{Z}_{\hat{t}_{N T}}+2.03 \sqrt{N} \xrightarrow{L} N(0,0.66) \tag{13}
\end{equation*}
$$

One can use these results to test the hypothesis of no cointegration in every cross-section of a panel.

### 2.2.2 McCoskey and Kao (1998)

McCoskey and Kao (1998) propose the average Augmented Dickey-Fuller (ADF) test for varying slopes and varying intercepts across all the members of the panel. They consider the model:

$$
\begin{gather*}
y_{i t}=\alpha_{i}+x_{i t} \beta_{i}+u_{i t}  \tag{14}\\
(i=1, \ldots, N, t=1, \ldots, T)
\end{gather*}
$$

Individual cointegrating equation are estimated separately for each cross-section and individual ADF statistics are computed for each cross-section. Each test is constructed such that the cross-sections are assumed independent of each other and heteroskedasticity across the cross-section is allowed. Using an analogous approach of $\operatorname{Im}$ et al. (1995) of average of the ADF statistics of the cross-sections in testing unit roots in panels, McCoskey and Kao computed the panel test statistics in the same way. The individual ADF test can be constructed as:

$$
\begin{equation*}
\hat{u}_{i t}=\rho_{i} \hat{u}_{i t-1}+\sum_{j=1}^{p} \phi_{j} \Delta \hat{u}_{i t-j}+e_{i t p} \tag{15}
\end{equation*}
$$

where $\hat{u}_{i t}$ are OLS residuals from (14). We can write equation (15) as:

$$
\Delta \hat{u}_{i t}=\rho_{i} \hat{u}_{i t-1}+\sum_{j=1}^{p} \phi_{j} \Delta \hat{u}_{i t-j}+e_{i t p}
$$

The null hypothesis is $H_{0}: \rho_{i}=0$ and the t-statistic for each i is constructed:

$$
t_{i A D F}=\frac{\left(\hat{u}_{-1}^{\prime} Q_{X_{p}} \hat{u}_{-1}\right)^{1 / 2} \hat{\rho}_{i}}{s_{e}}
$$

where $\hat{u}_{-1}$ is the vector of observations of $\hat{u}_{i t-1}$, and $Q_{X_{p}}=I-X_{p}\left(X_{p}^{\prime} X_{p}\right)^{-1} X_{p}^{\prime}$ where $X_{p}$ is the matrix of observations on the p regressors $\left(\Delta \hat{u}_{i t-1}, \ldots, \Delta \hat{u}_{i t-p}\right)$ and $s_{e}^{2}=\frac{1}{T} \sum_{t=1}^{T} \hat{e}_{i t p}^{2}$. Phillips and Ouliaris (1990) show that the $t_{i A D F}$ converges to a functional of Brownian motion. Finally, McCoskey and Kao construct the panel statistics as:

$$
\bar{t}_{A D F}=\frac{1}{N} \sum_{i=1}^{N} t_{i A D F}
$$

Define $E\left[t_{i A D F}\right]=\mu_{A D F}$, and $\operatorname{Var}\left[t_{i A D F}\right]=\sigma_{A D F}^{2}$. Then the central limit theorem can be applied to give:

$$
\sqrt{N}\left(\bar{t}_{A D F}-\mu_{A D F}\right) \xrightarrow{L} N\left(0, \sigma_{A D F}^{2}\right)
$$

Phillips and Ouliaris note that the limiting distribution of ADF test statistics in each crosssection is free of nuisance parameters and depends only on the number of regressors in (14). McCoskey and Kao also did a simulation to find the values of $\mu_{A D F}$ and $\sigma_{A D F}$, where they found that in the case of one regressor, $\mu_{A D F}=-2.206$ and $\sigma_{A D F}=.8200$. In their paper, McCoskey and Kao also suggest the average Phillip $Z_{t}$ test statistic based on the result that the $Z_{t}$ statistic in each cross-section converges to the same functional of Brownian motion as that of the $t_{i A D F}$.

## 3 Weighted Symmetric Estimation Method

Weighted Symmetric (WS) estimation was first proposed by Park and Fuller (1993). The use of WS estimation is not widely used in time series applications, although there is evidence
that WS estimation produces test statistic with greater power than those based on simple least squares. In this section, we give the limiting distribution of the WS estimator and the WS pivotal statistics when using WS estimation in testing unit root and cointegration in a single time series.

### 3.1 Alternative Representations of an Autogregressive Process

The following theorem is taken from Fuller (1996).
Theorem 3.0
Let $\left\{X_{t}\right\}$ be a time series defined on the integers with $E\left\{X_{t}^{2}\right\}<K$ for all $t$. Suppose $X_{t}$ satisfies

$$
\begin{gathered}
X_{t}+\sum_{j=1}^{p} \alpha_{j} X_{t-j}=e_{j} \\
t=0, \pm 1, \pm 2, \ldots
\end{gathered}
$$

where $\left\{e_{t}\right\}, t=0, \pm 1, \pm 2, \ldots$, is a sequence of uncorrelated $\left(0, \sigma^{2}\right)$ random variables. Let $m_{1}, m_{2}, \ldots, m_{p}$ be the roots of the characteristic equation

$$
m^{p}+\sum_{j=1}^{p} \alpha_{j} m^{p-j}=0
$$

and assume $\left|m_{i}\right|<1, i=1,2, \ldots, p$. Then $X_{t}$ is covariance stationary. Furthermore, $X_{t}$ is given as a limit in mean square by

$$
X_{t}=\sum_{j=0}^{\infty} w_{j} e_{t-j}
$$

where $\left\{w_{j}\right\}_{j=0}^{\infty}$ is the unique solution of the homogeneous difference equation $w_{j}+\alpha_{1} w_{j-1}+$ $\ldots+\alpha_{p} w_{j-p}=0, j=p, p+1, \ldots$, subject to the boundary conditions $w_{0}=0$ and $w_{j}+$ $\alpha_{1} w_{j-1}+\ldots+\alpha_{p} w_{j-p}=0, j=1,2, \ldots, p-1$

Proof: See Fuller (1996, p.59).
We now know that a time series satisfying a $p$ th order difference has a representations as an infinite moving average.

## Proposition 3.1

If the time series $\left\{X_{t}\right\}, t=0, \pm 1, \pm 2, \ldots$, with zero mean satisfies

$$
X_{t}+\alpha_{1} X_{t-1}+\alpha_{2} X_{t-2}+\ldots+\alpha_{p} X_{t-p}=e_{t}
$$

where $\left\{e_{t}\right\}$ is a sequence of uncorrelated $\left(0, \sigma^{2}\right)$ random variables, and the roots $m_{1}, m_{2}, \ldots, m_{p}$ of the characteristic equation

$$
m^{p}+\alpha_{1} m^{p-1}+\alpha_{2} m^{p-2}+\ldots+\alpha_{p}=0
$$

are less than 1 in absolute value. Then we also have

$$
X_{t}+\alpha_{1} X_{t+1}+\alpha_{2} X_{t+2}+\ldots+\alpha_{p} X_{t+p}=v_{t}
$$

where $\left\{v_{t}\right\}$ is a sequence of uncorrelated $\left(0, \sigma^{2}\right)$ random variables.
Proof: See Appendix

### 3.2 Weighted Symmetric Estimator

Consider the process:

$$
\begin{gather*}
y_{t}=\rho y_{t-1}+\epsilon_{t}  \tag{16}\\
t=2,3, \ldots, T ; \epsilon_{t} \sim N\left(0, \sigma^{2}\right)
\end{gather*}
$$

Following proposition 3.1, if a stationary process satisfies this equation, then it also satisfies the equation:

$$
\begin{gather*}
y_{t}=\rho y_{t+1}+u_{t}  \tag{17}\\
t=1,2, \ldots,(T-1) ; u_{t} \sim N\left(0, \sigma^{2}\right)
\end{gather*}
$$

Consider an estimator of $\rho$ that minimizes:

$$
\begin{equation*}
Q=\sum_{t=2}^{T} w_{t}\left(y_{t}-\rho y_{t-1}\right)^{2}+\sum_{t=1}^{T-1}\left(1-w_{t+1}\right)\left(y_{t}-\rho y_{t+1}\right)^{2} \tag{18}
\end{equation*}
$$

where $w_{t}, \mathrm{t}=2,3, \ldots, \mathrm{~T}$, are weights. The estimator obtained by setting $w_{t}=T^{-1}(t-1)$ is called the weighted symmetric (WS) estimator.

## Proposition 3.2

The weighted symmetric estimator of $\rho$ in the (16) process is

$$
\begin{equation*}
\hat{\rho}=\frac{\sum_{t=2}^{T} y_{t} y_{t-1}}{\sum_{t=2}^{T-1} y_{t}^{2}+\frac{1}{T} \sum_{t=1}^{T} y_{t}^{2}} \tag{19}
\end{equation*}
$$

If an intercept $\alpha$ is added in the regression equation as

$$
\begin{equation*}
y_{t}=\hat{\alpha}+\hat{\rho} y_{t-1}+e_{t} \tag{20}
\end{equation*}
$$

then the weighted symmetric estimator of $\rho$ would be

$$
\begin{equation*}
\hat{\rho}=\frac{\sum_{t=2}^{T}\left(y_{t}-\bar{y}\right)\left(y_{t-1}-\bar{y}\right)}{\sum_{t=2}^{T-1}\left(y_{t}-\bar{y}\right)^{2}+\frac{1}{T} \sum_{t=1}^{T}\left(y_{t}-\bar{y}\right)^{2}} \tag{21}
\end{equation*}
$$

with $\bar{y}=T^{-1} \sum_{t=1}^{T} y_{t}$
Proof: See Appendix
It can be extended to find the weighted symmetric estimator for the $p$ th order autore-
gressive time series

$$
\begin{gather*}
Y_{t}=\alpha_{0}+\sum_{i=1}^{p} \alpha_{i} Y_{t-i}+e_{i}  \tag{22}\\
t=p+1, \ldots, T
\end{gather*}
$$

We consider a class of estimators of $\alpha$, obtained by minimizing:

$$
\begin{equation*}
Q=\sum_{t=p+1}^{T} w_{t}\left[Y_{t}-\alpha_{0}-\sum_{i=1}^{p} \alpha_{i} Y_{t-i}\right]^{2}+\sum_{t=1}^{T-p}\left(1-w_{t+1}\right)\left[Y_{t}-\alpha_{0}-\sum_{i=1}^{p} \alpha_{i} Y_{t+i}\right]^{2} \tag{23}
\end{equation*}
$$

where $w_{t}, t=1,2, \ldots, T$ are weights and $0 \leq w_{t} \leq 1$. The value of $\alpha$ that minimizes (23) with:

$$
w_{t}= \begin{cases}0 & t=1,2, \ldots, p  \tag{24}\\ (T-2 p+2)^{-1}(t-p) & t=p+1, p+2, \ldots, T-p+1 \\ 1 & t=T-p+2, T-p+3, \ldots, T\end{cases}
$$

is called the weighed symmetric estimator for the $p$ th order autoregressive time series (22).

### 3.3 Asymptotic Distribution of a Weighted Symmetric Estimator in Testing Unit Roots

## Proposition 3.3

For $\hat{\rho}$ as in (19) then under the hypothesis of $\rho=1$

$$
\begin{gather*}
T(\hat{\rho}-1) \xrightarrow{L} \frac{\frac{1}{2}\left[K^{2}-1\right]-G}{G}  \tag{25}\\
t_{\hat{\rho}} \xrightarrow{L} \xrightarrow[G^{1 / 2}]{\frac{1}{2}\left[K^{2}-1\right]-G} \tag{26}
\end{gather*}
$$

where $K=W(1), G=\int_{0}^{1}[W(r)]^{2} d r . W(r)$ is a standard Wiener process on $[0,1]$.
Proof: See Appendix

## Proposition 3.4

For $\hat{\rho}$ as in (21) then under the hypothesis of $\rho=1$

$$
\begin{gather*}
T(\hat{\rho}-1) \xrightarrow{L} \frac{\left(\frac{1}{2}\left[K^{2}-1\right]-G-K H+2 H^{2}\right)}{\left[G-H^{2}\right]}  \tag{27}\\
t_{\hat{\rho}} \xrightarrow{L} \frac{\left(\frac{1}{2}\left[K^{2}-1\right]-G-K H+2 H^{2}\right)}{\left[G-H^{2}\right]^{1 / 2}} \tag{28}
\end{gather*}
$$

where $K=W(1), G=\int_{0}^{1}[W(r)]^{2} d r, H=\int_{0}^{1} W(r) d r . W(r)$ is a standard Wiener process on $[0,1]$.

Proof: See Appendix
Notes: The propositions 3.3 and 3.4 are asserted in Fuller (1996) without proofs. We found the proofs and present them in the Appendix.

### 3.4 Asymptotic Distribution of Cointegration Test Statistics Using Weighted Symmetric Estimators

Consider two processes $\left\{x_{t}\right\}$ and $\left\{y_{t}\right\}$, suppose that they are both $\mathrm{I}(1)$ processes and are totally independent random walks:

$$
\begin{cases}x_{t}=x_{t-1}+\epsilon_{t} & t=1,2, \ldots, T  \tag{29}\\ y_{t}=y_{t-1}+v_{t} & t=1,2, \ldots, T\end{cases}
$$

where both $\left\{\epsilon_{t}\right\}$ and $\left\{v_{t}\right\}$ are $\left(0, \sigma^{2}\right)$ processes. Consider the regression

$$
\begin{equation*}
y_{t}=\alpha+\beta x_{t}+u_{t}, t=1,2, \ldots, T \tag{30}
\end{equation*}
$$

Run the regression (30) and get the residual $\hat{u}_{t}$. We apply the weighted symmetric unit root test on $\hat{u}_{t}$. The estimation equation is

$$
\begin{equation*}
\hat{u}_{t}=\rho \hat{u}_{t-1}+e_{t}, t=1,2, \ldots, T \tag{31}
\end{equation*}
$$

The weighted symmetric estimator of $\rho$ is the one to minimize

$$
\begin{gather*}
Q=\sum_{t=2}^{T} w_{t}\left(\hat{u}_{t}-\rho \hat{u}_{t-1}\right)^{2}+\sum_{t=1}^{T-1}\left(1-w_{t+1}\right)\left(\hat{u}_{t}-\rho \hat{u}_{t+1}\right)^{2}  \tag{32}\\
w_{t}=\frac{t-1}{T}, t=2,3, \ldots, T
\end{gather*}
$$

Following proposition 3.2 , the weighted symmetric estimator of $\rho$ is

$$
\begin{equation*}
\hat{\rho}=\frac{\sum_{t=2}^{T} \hat{u}_{t} \hat{u}_{t-1}}{\sum_{t=2}^{T-1} \hat{u}_{t}^{2}+\frac{1}{T} \sum_{t=1}^{T} \hat{u}_{t}^{2}} \tag{33}
\end{equation*}
$$

We find the distribution of $T(\hat{\rho}-1)$, $t_{\hat{\rho}}$ under the null hypothesis of no cointegration $\rho=1$, implies $\left\{x_{t}\right\}$ and $\left\{y_{t}\right\}$ are independent random walks as in (29)

## Proposition 3.5

Under the null hypothesis of no cointegration $H_{0}: \rho=1$ in (31)

$$
\begin{gather*}
T(\hat{\rho}-1) \xrightarrow{L} \frac{\left[\frac{1}{2}\left(B_{v}-2 \zeta A+\zeta^{2} B_{w}\right)+\frac{1}{2} D-C-\frac{1}{2}\left(1+\zeta^{2}\right)\right]}{[C]}  \tag{34}\\
t_{\hat{\rho}} \xrightarrow{L} \xrightarrow{\left[\frac{1}{2}\left(B_{v}-2 \zeta A+\zeta^{2} B_{w}\right)+\frac{1}{2} D-C-\frac{1}{2}\left(1+\zeta^{2}\right)\right]}  \tag{35}\\
{\left[\left(1+\zeta^{2}\right) C\right]^{1 / 2}}
\end{gather*}
$$

where

$$
A=V(1) W(1)-W(1) \int_{0}^{1} V(r) d r-V(1) \int_{0}^{1} W(r) d r-\int_{0}^{1} V(r) d r \int_{0}^{1} W(r) d r
$$

$$
\begin{gathered}
B_{v}=\left[\int_{0}^{1} V(r) d r\right]^{2}-2 V(1) \int_{0}^{1} V(r) d r+[V(1)]^{2} \\
B_{w}=\left[\int_{0}^{1} W(r) d r\right]^{2}-2 W(1) \int_{0}^{1} W(r) d r+[W(1)]^{2} \\
C=\int_{0}^{1}[V(r)]^{2} d r-\left(\int_{0}^{1} V(r) d r\right)^{2}-\zeta^{2}\left[\int_{0}^{1}[W(r)]^{2} d r-\left(\int_{0}^{1} W(r) d r\right)^{2}\right] \\
D=\left[\int_{0}^{1} V(r) d r\right]^{2}+\zeta^{2}\left[\int_{0}^{1} W(r) d r\right]^{2}-2 \zeta \int_{0}^{1} V(r) d r \int_{0}^{1} W(r) d r \\
\zeta=\frac{\int_{0}^{1} V(r) W(r) d r-\int_{0}^{1} V(r) d r \int_{0}^{1} W(r) d r}{\int_{0}^{1}[W(r)]^{2} d r-\left[\int_{0}^{1} W(r) d r\right]^{2}}
\end{gathered}
$$

$V(r)$ and $W(r)$ are the standard Wiener processes on $[0,1]$.
Proof: See Appendix
The limiting distribution of WS test statistics for cointegration in single set of time series is free of nuisance parameters and depends only on the number of regressors. A simulation can provide the values of moments of the distribution which can be used to test for cointegration in heterogeneous panels.

## 4 New Tests for Cointegration in Heterogeneous

## Panels

In this section, new tests are presented that are based on the idea of average test statistics for each member of a panel, used in Im et al.(2003) to test for unit roots in panels, and Fisher's approach to combine p-values from individual test in each cross-section which is introduced in Maddala and Wu (1999). We introduce the use of three new tests for testing cointegration in heterogeneous panels.

First we briefly recall the Im et al. and Fisher tests. The Im et al. statistic is based on
the average individual Dickey-Fuller unit root tests as

$$
t_{I P S}=\frac{\sqrt{N}\left(\bar{t}-E\left[t_{i} \mid \rho_{i}=1\right]\right)}{\sqrt{\operatorname{Var}\left[t_{i} \mid \rho_{i}=1\right]}} \xrightarrow{L} N(0,1)
$$

where $\bar{t}=N^{-1} \sum_{i=1}^{N} t_{i}$. The moments of $E\left[t_{i} \mid \rho_{i}=1\right]$ and $\operatorname{Var}\left[t_{i} \mid \rho_{i}=1\right]$ are obtained by Monte Carlo simulation. Fisher shows that the statistic is given by $P=-2 \sum_{i=1}^{N} \log _{e} \pi_{i}$, where $\pi_{i}$ is the p-value of a test in cross-section i , is distributed as $\chi^{2}$ with degrees of freedom $2 N$ under the null hypothesis (See Im et al. (2003) and Maddala and Wu (1999) for more details).

### 4.1 Average Weighted Symmetric Test (AWS)

The average weighted symmetric (AWS) procedure is similar to the McCoskey and Kao (1998) test, but instead of using the ADF equation in each cross-section, we use the weighted symmetric estimation for each cross-section. This test is based on the result in proposition 3.5 that the WS t-statistics for testing cointegration in single time series will converge to a function of standard Wiener processes with no nuisance parameter. The WS panel statistics can be constructed as: run the following regression for each member i of the panel

$$
\begin{equation*}
y_{i t}=\alpha_{i}+\beta x_{i t} t+u_{i t}, t=1,2, \ldots, T \tag{36}
\end{equation*}
$$

and get the residual $\hat{u}_{i t}$. The estimation equation is

$$
\begin{equation*}
\hat{u}_{i t}=\rho \hat{u}_{i t-1}+e_{i t}, t=1,2, \ldots, T \tag{37}
\end{equation*}
$$

Obtain the WS estimator of (37) and then compute the WS t-statistics $t_{i W S}$ for (37) in each cross-section i. Finally, compute the WS panel statistic

$$
\bar{t}_{W S}=\frac{1}{N} \sum_{i=1}^{N} t_{i W S}
$$

Define $E\left[t_{i W S}\right]=\mu_{W S}$, and $\operatorname{Var}\left[t_{i W S}\right]=\sigma_{W S}^{2}$. Then the central limit theorem can be applied to give:

$$
\sqrt{N} \frac{\left(\bar{t}_{W S}-\mu_{W S}\right)}{\sigma_{W S}} \xrightarrow{L} N(0,1)
$$

In the case that $\left\{e_{i t}\right\}$ are correlated, instead of using (37), we can use the augmented equation to account for the correlation between $\left\{e_{t}\right\}$

$$
\begin{equation*}
\hat{u}_{i t}=\rho \hat{u}_{i t-1}+\sum_{j=1}^{p} \phi_{j} \Delta \hat{u}_{i t-j}+e_{i t p} \tag{38}
\end{equation*}
$$

$\mu_{W S}$ and $\sigma_{W S}^{2}$ values are found through a simulation as shown in table 1.

### 4.2 Fisher Augmented Dickey-Fuller Test (FADF)

The FADF test procedures are similar to the Maddala-Wu Fisher test for panel unit roots. This test is based on the results from Phillips and Ouliaris (1990) that the ADF t-statistics in testing cointegration converge to a function of standard Wiener processes. Run the following regression for each member i of the panel

$$
\begin{equation*}
y_{i t}=\alpha_{i}+\beta x_{i t} t+u_{i t}, t=1,2, \ldots, T \tag{39}
\end{equation*}
$$

and get the residual $\hat{u}_{i t}$. The estimation equation is

$$
\begin{equation*}
\hat{u}_{i t}=\rho \hat{u}_{i t-1}+\sum_{j=1}^{p} \phi_{j} \Delta \hat{u}_{i t-j}+e_{i t p} \tag{40}
\end{equation*}
$$

The FADF test requires deriving the distribution of the Dickey-Fuller t-statistic, for which the simulated values were generated for different $T$ and $p$. Then the p-values $\pi_{i a d f}$ for each ADF t-statistic could be derived. Consequently, the panel FADF statistic $P_{F A D F}$ is calculated as: $P_{F A D F}=-2 \sum_{i=1}^{N} \log _{e} \pi_{i a d f} \sim \chi_{2 N}^{2}$. For the critical values of the FADF statistic we use the $\chi^{2}$ table.

### 4.3 Fisher Weighted Symmetric Test (FWS)

The FWS test is the same as the FADF test except here we use the WS estimation procedure for each cross section rather than the ADF estimation procedure. The FWS test is based on the proposition 3.5 that the WS t-statistics for testing cointegration in single time series will converge to a function of standard Wiener processes with no nuisance parameters. The FWS test also requires deriving the distribution of the WS t-statistic, for which simulations were generated and the p-values $\pi_{i w s}$ for each WS t-statistic could be computed. The panel FWS statistic $P_{F W S}$ is calculated as: $P_{F W S}=-2 \sum_{i=1}^{N} l o g_{e} \pi_{i w s} \sim \chi_{2 N}^{2}$. For the critical values of FWS statistics $P_{F W S}$ for each N, we use the $\chi^{2}$ table. The advantage of the Fisher test is that it does not require a balanced panel as the average test does.

## 5 Monte-Carlo Investigation

### 5.1 Test statistics

Pedroni- $\rho$

$$
\tilde{Z}_{\hat{\rho}_{N T}-1}=\sum_{i=1}^{N} \frac{\sum_{t=1}^{T}\left(\hat{u}_{i t-1} \Delta \hat{u}_{i t}-\hat{\lambda}_{i}\right)}{\sum_{t=1}^{T} \hat{u}_{i t-1}^{2}}
$$

Pedroni- $t_{\rho}$

$$
\tilde{Z}_{t_{N T}}=\sum_{i=1}^{N} \frac{\sum_{t=1}^{T}\left(\hat{u}_{i t-1} \Delta \hat{u}_{i t}-\hat{\lambda}_{i}\right)}{\left[\sum_{t=1}^{T} \frac{1}{\hat{L}_{11 i}^{2}} \hat{u}_{i t-1}^{2}\right]^{1 / 2}}
$$

McCoskey \& Kao

$$
\begin{gathered}
\bar{t}_{A D F}=\frac{1}{N} \sum_{i=1}^{N} t_{i A D F} \\
t_{A D F}=\sqrt{N} \frac{\left(\bar{t}_{A D F}-\mu_{A D F}\right)}{\sigma_{A D F}}
\end{gathered}
$$

AWS

$$
\begin{gathered}
\bar{t}_{W S}=\frac{1}{N} \sum_{i=1}^{N} t_{i W S} \\
t_{W S}=\sqrt{N} \frac{\left(\bar{t}_{W S}-\mu_{W S}\right)}{\sigma_{W S}}
\end{gathered}
$$

FADF

$$
P_{F A D F}=-2 \sum_{i=1}^{N} l o g_{e} \pi_{i a d f} \sim \chi_{2 N}^{2}
$$

FWS

$$
P_{F W S}=-2 \sum_{i=1}^{N} \log _{e} \pi_{i w s} \sim \chi_{2 N}^{2}
$$

### 5.2 Data Generation Processes

The DGP for all six tests based on the null hypothesis of no cointegration is as follows:

$$
\begin{gather*}
y_{i t}=\alpha_{i}+\beta_{i} x_{i t}+u_{i t}  \tag{41}\\
(i=1, \ldots, N, t=1, \ldots, T)
\end{gather*}
$$

and

$$
u_{i t}=\rho u_{i t-1}+v_{i t}
$$

It is also assumed that

$$
x_{i t}=x_{i t-1}+\epsilon_{i t}
$$

where $\epsilon_{i t} \sim N\left(0, \sigma_{i}^{2}\right)$, so we have that $y_{i t}$ and $x_{i t}$ are random walks, so they are cointegrated series if $|\rho|<1$ but are not cointegrated, implying (41) is a spurious regression, if $\rho=1$. The size of the tests are investigated under the null hypothesis $\rho=1$. For studying the power of tests we set $\rho=0.9$. The autocorrelation in $v_{i t}$ takes the form of moving average component as

$$
v_{i t}=v_{i t}^{*}+\theta_{i} v_{i t-1}^{*}
$$

where $v_{i t}^{*} \sim N(0,1)$ and

$$
\left[\begin{array}{c}
v_{i t}^{*} \\
\epsilon_{i t}
\end{array}\right] \sim \mathrm{N}\left(\left[\begin{array}{l}
0 \\
0
\end{array}\right],\left[\begin{array}{cc}
1 & \delta \sigma_{i} \\
\delta \sigma_{i} & \sigma_{i}^{2}
\end{array}\right]\right)
$$

$\alpha_{i}, \beta_{i}$ and $\sigma_{i}$ are generated using the uniform distribution as: $\alpha_{i} \sim U[0,10], \beta_{i} \sim U[0,2]$ and $\sigma_{i} \sim U[0.5,1.5] . \alpha_{i}, \beta_{i}$ and $\sigma_{i}$ are generated once and fixed in all replications. The choice of N and T for the experiment is : $N \in\{5,10,25,50\}$ and $T \in\{10,25,50,100\}$.

We examine four groups of DGPs by controlling the values of $\delta$ and $\theta_{i}$
(1)-There is no endogeneity between $x_{i t}$ and $u_{i t}$ and no autocorrelation in $v_{i t}: \delta=0$ and $\theta_{i}=0$
(2)-There is endogeneity between $x_{i t}$ and $u_{i t}$ but no autocorrelation in $v_{i t}: \delta=0.5$ and $\theta_{i}=0$
(3)-There is no endogeneity between $x_{i t}$ and $u_{i t}$ but autocorrelation in $v_{i t}: \delta=0$ and $\theta_{i} \sim U[-0.4,0.4]$
(4)-There is both endogeneity between $x_{i t}$ and $u_{i t}$ and autocorrelation in $v_{i t}: \delta=0.5$ and $\theta_{i} \sim U[-0.4,0.4]$

To reduce the effect of initial conditions, $T+50$ observations are generated and the first 50 observations are eliminated, using only last $T$ observations. The number of replications is set to 3,000 for computing the empirical size and power of all five tests. The size and power of tests are computed at the $5 \%$ nominal level.

The data generating processes here is adopted similarly to the DGP used in the McCoskey and Kao (1998) paper.

### 5.3 Size and Power of Tests

The results of the simulation experiments are reported in Tables 2-5. In all cases, 3000 trials are used to examine the size and power properties. Table $2^{1}$ presents the first set of experiments when there is no endogeneity between $x_{i t}$ and $u_{i t}$ and also no autocorrelation in $v_{i t}$. The critical value of the $5 \%$ significance level is used to calculate the size and power of the tests. The Pedroni-t test has a strong size distortion, growing large when T or N increases. This size distortion makes the test impractical with large probability of a type I error. The Pedroni- $\rho$ test has a little size distortion also, the size of this test is slightly under the significance level of $5 \%$ when T is small. It becomes larger when T increases, so at

[^1]$\mathrm{T}=100$, the size is around $10 \%$. It is noted that the size does not change when N increases. The size of the McCoskey and Kao test is under $5 \%$ also, and it is smaller when both N and T are larger, and it decreases faster when N increases compared to when T increases. Although the Pedroni- $\rho$ and McCoskey and Kao tests are undersized, they are still acceptable, as it would lower the chance one could commit a type I error in testing a hypothesis. For all three proposed tests, AWS, FADF and FWS, the size is good, mostly lying between $4 \%$ and $6 \%$. In terms of the power of tests, all five tests have good power when T is large. The power increases when N increases, but the speed of the increase is slower compared to the case when T increases. Overall the two tests AWS and FWS have more power which dominates those of other four tests, especially when T is less than 50 . For instance, when $\mathrm{N}=25$ and $\mathrm{T}=25$, the powers of AWS and FWS are $50 \%$ and $35 \%$ compared to the power of other four tests. ( $14 \%$ (Pedroni-t), $10 \%$ (Pedroni- $\rho$ ), $6 \%$ (McCoskey \& Kao) and $17 \%$ (FADF)). When both N and T are large, AWS and FWS are still the most powerful tests. In the first set of experiments all three tests AWS, FADF, FWS have good size and the tests AWS and FWS have the highest power. The FADF test does not have as good power as the AWS and FWS tests when N is small, but when N is larger than 25 its power is also good. In this case the Pedroni-t test should not be used in practice because of serious size distortion. In both size and power the performances of AWS and FWS dominate the other tests. The AWS test has slightly more power than the FWS, so in this case AWS is the best choice. However, it should be noted that AWS is only for balanced panels, so in the case when we have an unbalanced panel, the FWS would be of first choice.

Table 3 reports the size and power of tests when there is endogeneity between $x_{i t}$ and $u_{i t}$ but there is no autocorrelation in $v_{i t}$. The Pedroni-t test has size distortion, most of them are close to zero, unlike the environment of table 2. Here the correction for endogeneity of the t -statistics of the Pedroni-t test through the term $L_{11 i}^{-2}$ helps to reduce the size if endogeneity really exists. The fact that the size is almost zero is acceptable in practice because it will help
to reduce the chance of type I error. The size of the Pedroni- $\rho$ test tends to under $5 \%$ when T is small and become a little over $5 \%$ when T is larger than 50 , and when $\mathrm{N}=50, \mathrm{~T}=100$, it gets to a maximum of $13 \%$. The McCoskey \& Kao test's size is a bit under the nominal size of $5 \%$, and it does not change much when N or T changes. All three new tests, AWS, FADF, FWS, have good size, all falling between $4 \%$ to $6 \%$. The power of the Pedroni-t test is low when T and N are small, especially when T is less than 50 , and the power decreases even when N increases. When $\mathrm{T}=100$, the power increases as N increase. The cause of the low power of the Pedroni-t test when T is small could be from adding the correction term $L_{11 i}^{-2}$. The power of the Pedroni- $\rho$ test is better: it is powerful when $\mathrm{N} \geq 25$ and $\mathrm{T} \geq 50$ but it is poor when $\mathrm{N}<25$ or $\mathrm{T}<50$. Again, the two test AWS and FWS are the most powerful tests. The AWS is a little more powerful than the FWS, but they both dominate other four tests in terms of power. When both N and T are large, the power of those two tests approaches $100 \%$ quickly, where the speed of increase is the same with respect to T or to N . The McCoskey and Kao test has good power when $\mathrm{T}=100$, but when $\mathrm{T} \leq 50$ this test is not a powerful one. Compared to table 2, we see that the effect of endogeneity is strong on the Pedroni tests, but it does not affect the AWS and the FWS tests very much, these two tests still perform well under endogeneous data. It also should be mentioned here that the AWS and FWS tests do not have any procedure that correct for the endogeneity but they both have the best size and are the most powerful tests compare with the rest.

Table 4 summarizes the size and power of tests in the case when there is autocorrelation in $v_{i t}$ but no endogeneity between $x_{i t}$ and $u_{i t}$. We see here again, as in table 2 , the Pedroni-t test has serious size distortion especially when T is large. The reason for this, as we observe in table 2, may be the over-correction for endogeneity when it does not exist. This makes the Pedroni-t test unusable in practice. The Pedroni- $\rho$ test has better size, but it is still strongly distorted upward, with the size is getting worse for large T . At $\mathrm{N}=25$, the size seems to be good, but for $\mathrm{N}=5,10,50$, the size is bad. This may be because the difference in magnitude
of the correlation coefficient $\theta_{i}$ that is randomly set as $\theta_{i} \sim[-0.4,0.4]$. Apparently when the correlation coefficient $\theta_{i}$ in the moving average term is large, the correction for this in the Pedroni- $\rho$ test through the term $\hat{\lambda}_{i}$ does not work well. The McCoskey and Kao test has a small (under-size) distortion, which is acceptable as it reduces the chance to get type I error in testing a hypothesis. For all three of the proposed tests, AWS, FWS, FADF, the size is good, lying close to the nominal size of $5 \%$ for every value of N and T . This simulation evidence confirms that the limiting distributions of all these three tests are approximated well by the standard normal and Chi-squared distributions, based on the fact that they exhibit good and stable size under different panel dimensions. In terms of power the Pedroni-t test perform well but because it has serious size distortion its strong power in this case is not useful. The Pedroni- $\rho$ test is less powerful when $\mathrm{T} \leq 25$ and has good power when $\mathrm{T} \geq 50$, but when $\mathrm{T} \geq 50$ its size is small. In general, the Pedroni- $\rho$ test in this case is unreliable, requiring a trade off between good power and bad size or good size and bad power. The tests with the most power are still the AWS and FWS, while the third best is FADF which is a little more powerful than the McCoskey and Kao test. Compared to table 2 and table 3, they are even more powerful in the presence of moving average correlation in $v_{i t}$. So in this case, both Pedroni tests are unreliable, while the McCoskey and Kao test has an acceptable size but low power when $\mathrm{T} \leq 50$. The AWS and FWS tests turn out to be the best in this experiment, with the third choice being the FADF test.

The last set of experiments is shown in table 5, where in the DGP, both endogeneity and moving average autocorrelation are allowed. We see the size of the Pedroni- $\rho$ test is worse, compared with table 3 , and we see that combining both endogeneity and moving average make the Pedroni- $\rho$ test perform badly in size, but if there is only endogeneity then this test performs satisfatory. The size of the Pedroni-t test is much better compared with the table 4, as we discussed before, so when there is endogeneity between $x_{i t}$ and $u_{i t}$ the Pedroni-t test will have acceptable size. The McCoskey and Kao test is a little under-sized. The three
tests, AWS, FWS, FADF, consistently have good size as they do in the three previous tables. For power, the two Pedroni-t and McCoskey and Kao tests have low power when $\mathrm{T} \leq 50$ and the Pedroni- $\rho$ test has good power when $\mathrm{T} \geq 50$, but when $\mathrm{T} \geq 50$ this test has serious size distortion. The AWS and FWS are the most powerful tests in all cases of N and T . The FADF test has less power compared to AWS and FWS tests but is more powerful than the McCoskey and Kao test.

Overall, for all four sets of experiments, the AWS, FWS, FADF tests consistently have good size, close to the $5 \%$ nominal size. The AWS and FWS are also consistently the most powerful tests in all data environments. They dominate the four tests in every aspect of performance. The AWS has a bit more power than the FWS, but the AWS test only works with a balanced panel while the FWS can be applied to any kind of panel, balanced or unbalanced.

## 6 Conclusion

In this paper, we propose three new tests for cointegration in heterogeneous panels, the AWS, FWS and FADF tests. The limiting distributions of weighted symmetric statistics in testing cointegration in a single set of time series are derived, and it is shown that the weighted symmetric limiting distribution is a functional of standard Wiener processes and free of nuisance parameters. The AWS and FWS are based on this result. The Monte-Carlo investigation is also conducted with different data generation environments and we found that, in every panel dimension and data characteristic, the AWS and FWS tests are the most powerful, strongly dominating the other four tests in terms of power . All three new tests also have appropriate size in all DGPs. In the previous literature, the Pedroni tests and the McCoskey and Kao tests are the only tests available for testing cointegration in heterogeneous panel. This Monte-Carlo study shows that the AWS and FWS usually perform much better
in terms of size and power compared to the Pedroni tests and the McCoskey and Kao test, in every combination of endogeneity or moving average autocorrelation considered in this study. We propose that in practice, if the data is a balanced panel, the AWS test should be used and if the panel is unbalanced the FWS should be the first choice. The programs for these two tests are available from the author and make it easy to use in empirical work. An important extension for future study would be the effect of cross-section correlation on testing cointegration of these tests in panels.

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TABLE 1: Moments of t-statistics of the Weighted Symmetric Estimator in Testing Cointegration in a Single Equation

| $p$ | T | MEAN | VARIANCE |
| :--- | :--- | :--- | :--- |
| 2 | 7 | -1.1343 | 1.1680 |
| 2 | 8 | -1.1953 | 1.1649 |
| 2 | 9 | -1.2412 | 1.1263 |
| 2 | 10 | -1.2802 | 1.1084 |
| 2 | 15 | -1.4039 | 1.0750 |
| 2 | 20 | -1.5117 | 1.0439 |
| 2 | 25 | -1.5494 | 1.0154 |
| 2 | 30 | -1.5513 | 0.9866 |
| 3 | 40 | -1.5784 | 0.9713 |
| 3 | 50 | -1.6083 | 0.9515 |
| 3 | 60 | -1.6202 | 0.9398 |
| 3 | 70 | -1.6392 | 0.9231 |
| 3 | 80 | -1.6454 | 0.9095 |
| 3 | 90 | -1.6137 | 0.9034 |
| 4 | 100 | -1.6510 | 0.8966 |
| 4 | 150 | -1.6657 | 0.8855 |
| 4 | 200 |  | 0.8761 |

NOTES: means and variances in this table are computed by stochastic simulations with 100,000 replications. The underlying data is generated by:

$$
\begin{gathered}
y_{t}=\alpha+\beta x_{t}+u_{t} \\
\quad(t=1, \ldots, T)
\end{gathered}
$$

and

$$
\begin{aligned}
& x_{t}=x_{t-1}+\epsilon_{t} \\
& u_{t}=u_{t-1}+v_{t}
\end{aligned}
$$

where

$$
\begin{aligned}
v_{t} & \sim N(0,1) \\
\epsilon_{t} & \sim N\left(0, \sigma^{2}\right)
\end{aligned}
$$

$\alpha, \beta$ and $\sigma$ are generated using the uniform distribution as: $\alpha_{i} \sim U[0,10], \beta \sim$ $U[0,2]$ and $\sigma \sim U[0.5,1.5]$. $T+50$ observations are generated and the first 50 observations are eliminated, using only the last $T$ observations. $p$ is decided by $p=\operatorname{Int}\left[c(T / 100)^{1 / d}\right]$ with $\mathrm{c}=4, \mathrm{~d}=4$.

TABLE 2: Size and Power of Tests for Cointegration in the Panels with
Heterogeneity of the Intercepts and Slopes: $\left(\delta=0 ; \theta_{i}=0\right)$

| N | T | PEDRONI- $t_{\rho}$ | $\begin{aligned} & \text { PEDRONI- } \\ & \rho \end{aligned}$ | $\begin{aligned} & \text { MCCOSKEY } \\ & \& \text { KAO- } t_{A D F} \end{aligned}$ | AVERAGE$t_{W S}$ | $\begin{aligned} & \text { FISHER- } \\ & t_{A D F} \end{aligned}$ | $\begin{aligned} & \hline \text { FISHER- } \\ & t_{W S} \end{aligned}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | SIZE |  |  |  |  |  |
| 5 | 10 | 0.000 | 0.000 | 0.032 | 0.051 | 0.050 | 0.047 |
|  | 25 | 0.058 | 0.012 | 0.028 | 0.049 | 0.053 | 0.054 |
|  | 50 | 0.216 | 0.044 | 0.032 | 0.045 | 0.055 | 0.049 |
|  | 100 | 0.315 | 0.072 | 0.025 | 0.042 | 0.045 | 0.045 |
| 10 | 10 | 0.000 | 0.000 | 0.013 | 0.048 | 0.040 | 0.045 |
|  | 25 | 0.066 | 0.010 | 0.016 | 0.047 | 0.042 | 0.050 |
|  | 50 | 0.268 | 0.044 | 0.021 | 0.044 | 0.043 | 0.038 |
|  | 100 | 0.463 | 0.093 | 0.025 | 0.053 | 0.052 | 0.050 |
| 25 | 10 | 0.000 | 0.000 | 0.003 | 0.052 | 0.047 | 0.049 |
|  | 25 | 0.039 | 0.006 | 0.008 | 0.055 | 0.052 | 0.062 |
|  | 50 | 0.445 | 0.052 | 0.010 | 0.057 | 0.044 | 0.052 |
|  | 100 | 0.709 | 0.102 | 0.020 | 0.059 | 0.055 | 0.052 |
| 50 | 10 | 0.000 | 0.000 | 0.000 | 0.055 | 0.047 | 0.052 |
|  | 25 | 0.024 | 0.003 | 0.002 | 0.052 | 0.043 | 0.054 |
|  | 50 | 0.640 | 0.056 | 0.005 | 0.052 | 0.040 | 0.047 |
|  | 100 | 0.913 | 0.131 | 0.007 | 0.062 | 0.045 | 0.053 |
|  |  | POWER |  |  |  |  |  |
| 5 | 10 | 0.001 | 0.000 | 0.030 | 0.077 | 0.052 | 0.067 |
|  | 25 | 0.093 | 0.042 | 0.062 | 0.147 | 0.092 | 0.132 |
|  | 50 | 0.425 | 0.316 | 0.151 | 0.353 | 0.173 | 0.296 |
|  | 100 | 0.884 | 0.913 | 0.545 | 0.826 | 0.534 | 0.739 |
| 10 | 10 | 0.000 | 0.000 | 0.019 | 0.098 | 0.055 | 0.078 |
|  | 25 | 0.118 | 0.063 | 0.058 | 0.246 | 0.109 | 0.193 |
|  | 50 | 0.655 | 0.552 | 0.252 | 0.630 | 0.284 | 0.477 |
|  | 100 | 0.992 | 0.998 | 0.848 | 0.988 | 0.828 | 0.957 |
| 25 | 10 | 0.000 | 0.000 | 0.008 | 0.136 | 0.061 | 0.108 |
|  | 25 | 0.137 | 0.102 | 0.064 | 0.501 | 0.165 | 0.346 |
|  | 50 | 0.935 | 0.914 | 0.487 | 0.954 | 0.534 | 0.832 |
|  | 100 | 1.000 | 1.000 | 0.997 | 1.000 | 0.996 | 1.000 |
| 50 | 10 | 0.000 | 0.000 | 0.002 | 0.215 | 0.071 | 0.151 |
|  | 25 | 0.184 | 0.173 | 0.069 | 0.775 | 0.273 | 0.573 |
|  | 50 | 0.997 | 0.998 | 0.788 | 1.000 | 0.822 | 0.985 |
|  | 100 | 1.000 | 1.000 | 1.000 | 1.000 | 1.000 | 1.000 |

NOTES: Data Generating Processes for all six tests based on the null hypothesis of no cointegration as following: $y_{i t}=\alpha_{i}+\beta_{i} x_{i t}+u_{i t}(i=1, \ldots, N, t=1, \ldots, T)$ and $x_{i t}=x_{i t-1}+\epsilon_{i t} ; u_{i t}=\rho u_{i t-1}+v_{i t}$; $v_{i t}=v_{i t}^{*}+\theta_{i} v_{i t-1}^{*}$ with:

$$
\left[\begin{array}{c}
v_{i t}^{*} \\
\epsilon_{i t}
\end{array}\right] \sim \mathrm{N}\left(\left[\begin{array}{l}
0 \\
0
\end{array}\right],\left[\begin{array}{cc}
1 & \delta \sigma_{i} \\
\delta \sigma_{i} & \sigma_{i}^{2}
\end{array}\right]\right)
$$

where $v_{i t}^{*} \sim N(0,1), \epsilon_{i t} \sim N\left(0, \sigma_{i}^{2}\right) . \alpha_{i}, \beta_{i}$ and $\sigma_{i}$ are generated using the uniform distribution as: $\alpha_{i} \sim U[0,10], \beta_{i} \sim U[0,2]$ and $\sigma_{i} \sim U[0.5,1.5] . \alpha_{i}, \beta_{i}$ and $\sigma_{i}$ are generated once and fixed in all replications. $\rho=1$ for size and $\rho=0.9$ for power. $T+50$ observations are generated and the first 50 observations are eliminated, using only last $T$ observations. Number of replications is set to 3,000 for computing the empirical size and power of all five tests. The size and power of tests are computed at the $5 \%$ nominal level.
$\delta=0$ and $\theta_{i}=0$ is set in this table, so there is no endogeneity between $x_{i t}$ and $u_{i t}$ and no serial correlation in $v_{i t}$.

TABLE 3: Size and Power of Tests for Cointegration in the Panels with
Heterogeneity of the Intercepts and Slopes: $\left(\delta=0.5 ; \theta_{i}=0\right)$

| N | T | PEDRONI- <br> $t_{\rho}$ | PEDRONI$\rho$ | MCCOSKEY <br> $\& \mathrm{KAO}^{-t_{A D F}}$ | AVERAGE$t_{W S}$ | $\begin{aligned} & \text { FISHER- } \\ & t_{A D F} \end{aligned}$ | $\begin{aligned} & \text { FISHER- } \\ & t_{W S} \end{aligned}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | SIZE |  |  |  |  |  |
| 5 | 10 | 0.000 | 0.000 | 0.031 | 0.054 | 0.051 | 0.053 |
|  | 25 | 0.002 | 0.009 | 0.028 | 0.046 | 0.053 | 0.051 |
|  | 50 | 0.009 | 0.050 | 0.029 | 0.042 | 0.044 | 0.052 |
|  | 100 | 0.021 | 0.073 | 0.027 | 0.043 | 0.047 | 0.046 |
| 10 | 10 | 0.000 | 0.000 | 0.020 | 0.053 | 0.055 | 0.048 |
|  | 25 | 0.000 | 0.012 | 0.019 | 0.042 | 0.050 | 0.038 |
|  | 50 | 0.003 | 0.051 | 0.024 | 0.053 | 0.050 | 0.058 |
|  | 100 | 0.013 | 0.075 | 0.023 | 0.046 | 0.047 | 0.045 |
| 25 | 10 | 0.000 | 0.000 | 0.004 | 0.059 | 0.048 | 0.052 |
|  | 25 | 0.000 | 0.006 | 0.005 | 0.050 | 0.049 | 0.060 |
|  | 50 | 0.001 | 0.055 | 0.015 | 0.050 | 0.052 | 0.051 |
|  | 100 | 0.004 | 0.095 | 0.015 | 0.051 | 0.044 | 0.050 |
| 50 | 10 | 0.000 | 0.000 | 0.000 | 0.056 | 0.046 | 0.053 |
|  | 25 | 0.000 | 0.002 | 0.002 | 0.047 | 0.049 | 0.055 |
|  | 50 | 0.000 | 0.058 | 0.008 | 0.057 | 0.052 | 0.054 |
|  | 100 | 0.001 | 0.126 | 0.015 | 0.054 | 0.056 | 0.051 |
|  |  | POWER |  |  |  |  |  |
| 5 | 10 | 0.000 | 0.000 | 0.036 | 0.069 | 0.056 | 0.063 |
|  | 25 | 0.004 | 0.035 | 0.049 | 0.121 | 0.075 | 0.109 |
|  | 50 | 0.027 | 0.234 | 0.110 | 0.253 | 0.133 | 0.202 |
|  | 100 | 0.213 | 0.839 | 0.414 | 0.723 | 0.415 | 0.619 |
| 10 | 10 | 0.000 | 0.000 | 0.019 | 0.077 | 0.051 | 0.067 |
|  | 25 | 0.001 | 0.035 | 0.043 | 0.151 | 0.087 | 0.127 |
|  | 50 | 0.017 | 0.390 | 0.153 | 0.451 | 0.190 | 0.323 |
|  | 100 | 0.363 | 0.983 | 0.711 | 0.954 | 0.688 | 0.883 |
| 25 | 10 | 0.000 | 0.000 | 0.007 | 0.117 | 0.063 | 0.090 |
|  | 25 | 0.000 | 0.049 | 0.035 | 0.310 | 0.117 | 0.232 |
|  | 50 | 0.008 | 0.767 | 0.303 | 0.831 | 0.365 | 0.629 |
|  | 100 | 0.702 | 1.000 | 0.985 | 1.000 | 0.970 | 0.998 |
| 50 | 10 | 0.000 | 0.000 | 0.001 | 0.137 | 0.062 | 0.098 |
|  | 25 | 0.000 | 0.081 | 0.032 | 0.521 | 0.174 | 0.358 |
|  | 50 | 0.002 | 0.967 | 0.510 | 0.986 | 0.609 | 0.892 |
|  | 100 | 0.944 | 1.000 | 1.000 | 1.000 | 0.999 | 1.000 |

NOTES: Data Generating Processes for all six tests based on the null hypothesis of no cointegration as following: $y_{i t}=\alpha_{i}+\beta_{i} x_{i t}+u_{i t}(i=1, \ldots, N, t=1, \ldots, T)$ and $x_{i t}=x_{i t-1}+\epsilon_{i t} ; u_{i t}=\rho u_{i t-1}+v_{i t}$; $v_{i t}=v_{i t}^{*}+\theta_{i} v_{i t-1}^{*}$ with:

$$
\left[\begin{array}{l}
v_{i t}^{*} \\
\epsilon_{i t}
\end{array}\right] \sim \mathrm{N}\left(\left[\begin{array}{l}
0 \\
0
\end{array}\right],\left[\begin{array}{cc}
1 & \delta \sigma_{i} \\
\delta \sigma_{i} & \sigma_{i}^{2}
\end{array}\right]\right)
$$

where $v_{i t}^{*} \sim N(0,1), \epsilon_{i t} \sim N\left(0, \sigma_{i}^{2}\right) . \alpha_{i}, \beta_{i}$ and $\sigma_{i}$ are generated using the uniform distribution as: $\alpha_{i} \sim U[0,10], \beta_{i} \sim U[0,2]$ and $\sigma_{i} \sim U[0.5,1.5] . \alpha_{i}, \beta_{i}$ and $\sigma_{i}$ are generated once and fixed in all replications. $\rho=1$ for size and $\rho=0.9$ for power. $T+50$ observations are generated and the first 50 observations are eliminated, using only last $T$ observations. Number of replications is set to 3,000 for computing the empirical size and power of all five tests. The size and power of tests are computed at the $5 \%$ nominal level.
$\delta=0.5$ and $\theta_{i}=0$ is set in this table, so there is endogeneity between $x_{i t}$ and $u_{i t}$ but no serial correlation in $v_{i t}$.

TABLE 4: Size and Power of Tests for Cointegration in the Panels with
Heterogeneity of the Intercepts and Slopes: $\left(\delta=0 ; \theta_{i} \sim U[-0.4,0.4]\right)$

| N | T | PEDRONI$t_{\rho}$ | PEDRONI- | MCCOSKEY <br> \& KAO- $t_{A D F}$ | AVERAGE$t_{W S}$ | FISHER$t_{A D F}$ | $\begin{aligned} & \text { FISHER- } \\ & t_{W S} \end{aligned}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | SIZE |  |  |  |  |  |
| 5 | 10 | 0.001 | 0.000 | 0.035 | 0.057 | 0.054 | 0.053 |
|  | 25 | 0.090 | 0.077 | 0.029 | 0.055 | 0.057 | 0.066 |
|  | 50 | 0.342 | 0.053 | 0.026 | 0.043 | 0.047 | 0.048 |
|  | 100 | 0.625 | 0.176 | 0.029 | 0.047 | 0.054 | 0.054 |
| 10 | 10 | 0.000 | 0.000 | 0.016 | 0.054 | 0.051 | 0.049 |
|  | 25 | 0.154 | 0.025 | 0.020 | 0.059 | 0.056 | 0.059 |
|  | 50 | 0.435 | 0.153 | 0.022 | 0.052 | 0.048 | 0.055 |
|  | 100 | 0.802 | 0.273 | 0.024 | 0.049 | 0.055 | 0.052 |
| 25 | 10 | 0.000 | 0.000 | 0.004 | 0.067 | 0.050 | 0.056 |
|  | 25 | 0.264 | 0.017 | 0.011 | 0.052 | 0.055 | 0.055 |
|  | 50 | 0.848 | 0.070 | 0.013 | 0.049 | 0.044 | 0.048 |
|  | 100 | 0.973 | 0.075 | 0.020 | 0.053 | 0.051 | 0.049 |
| 50 | 10 | 0.000 | 0.000 | 0.001 | 0.048 | 0.040 | 0.047 |
|  | 25 | 0.376 | 0.030 | 0.003 | 0.060 | 0.056 | 0.068 |
|  | 50 | 0.963 | 0.369 | 0.010 | 0.059 | 0.059 | 0.056 |
|  | 100 | 0.995 | 0.662 | 0.006 | 0.056 | 0.049 | 0.053 |
|  |  | POWER |  |  |  |  |  |
| 5 | 10 | 0.002 | 0.000 | 0.037 | 0.104 | 0.060 | 0.095 |
|  | 25 | 0.238 | 0.007 | 0.049 | 0.139 | 0.073 | 0.125 |
|  | 50 | 0.785 | 0.734 | 0.170 | 0.382 | 0.201 | 0.322 |
|  | 100 | 0.982 | 0.997 | 0.557 | 0.852 | 0.554 | 0.762 |
| 10 | 10 | 0.000 | 0.000 | 0.025 | 0.119 | 0.066 | 0.105 |
|  | 25 | 0.307 | 0.035 | 0.053 | 0.240 | 0.101 | 0.187 |
|  | 50 | 0.897 | 0.723 | 0.253 | 0.641 | 0.287 | 0.492 |
|  | 100 | 1.000 | 1.000 | 0.861 | 0.990 | 0.828 | 0.952 |
| 25 | 10 | 0.000 | 0.000 | 0.008 | 0.161 | 0.071 | 0.119 |
|  | 25 | 0.461 | 0.035 | 0.060 | 0.453 | 0.155 | 0.314 |
|  | 50 | 0.996 | 0.993 | 0.525 | 0.970 | 0.567 | 0.861 |
|  | 100 | 1.000 | 1.000 | 0.998 | 1.000 | 0.996 | 1.000 |
| 50 | 10 | 0.000 | 0.000 | 0.002 | 0.218 | 0.078 | 0.157 |
|  | 25 | 0.623 | 0.536 | 0.084 | 0.810 | 0.297 | 0.616 |
|  | 50 | 1.000 | 1.000 | 0.809 | 0.999 | 0.836 | 0.989 |
|  | 100 | 1.000 | 1.000 | 1.000 | 1.000 | 1.000 | 1.000 |

NOTES: Data Generating Processes for all six tests based on the null hypothesis of no cointegration as following: $y_{i t}=\alpha_{i}+\beta_{i} x_{i t}+u_{i t}(i=1, \ldots, N, t=1, \ldots, T)$ and $x_{i t}=x_{i t-1}+\epsilon_{i t} ; u_{i t}=\rho u_{i t-1}+v_{i t}$; $v_{i t}=v_{i t}^{*}+\theta_{i} v_{i t-1}^{*}$ with:

$$
\left[\begin{array}{l}
v_{i t}^{*} \\
\epsilon_{i t}
\end{array}\right] \sim \mathrm{N}\left(\left[\begin{array}{l}
0 \\
0
\end{array}\right],\left[\begin{array}{cc}
1 & \delta \sigma_{i} \\
\delta \sigma_{i} & \sigma_{i}^{2}
\end{array}\right]\right)
$$

where $v_{i t}^{*} \sim N(0,1), \epsilon_{i t} \sim N\left(0, \sigma_{i}^{2}\right) . \alpha_{i}, \beta_{i}$ and $\sigma_{i}$ are generated using the uniform distribution as: $\alpha_{i} \sim U[0,10], \beta_{i} \sim U[0,2]$ and $\sigma_{i} \sim U[0.5,1.5] . \alpha_{i}, \beta_{i}$ and $\sigma_{i}$ are generated once and fixed in all replications. $\rho=1$ for size and $\rho=0.9$ for power. $T+50$ observations are generated and the first 50 observations are eliminated, using only last $T$ observations. Number of replications is set to 3,000 for computing the empirical size and power of all five tests. The size and power of tests are computed at the $5 \%$ nominal level.
$\delta=0$ and $\theta_{i}=0 \sim U[-0.4,0.4]$ is set in this table, so there is no endogeneity between $x_{i t}$ and $u_{i t}$ but there is serial correlation in $v_{i t}$.

TABLE 5: Size and Power of Tests for Cointegration in the Panels with
Heterogeneity of the Intercepts and Slopes: $\left(\delta=0.5 ; \theta_{i} \sim U[-0.4,0.4]\right)$

| N | T | PEDRONI- <br> $t_{\rho}$ | PEDRONI- <br> $\rho$ | MCCOSKEY <br> \& KAO- $t_{A D F}$ | AVERAGE$t_{W S}$ | FISHER- $t_{A D F}$ | FISHER- <br> $t_{W S}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | SIZE |  |  |  |  |  |
| 5 | 10 | 0.000 | 0.000 | 0.030 | 0.041 | 0.051 | 0.038 |
|  | 25 | 0.027 | 0.082 | 0.033 | 0.058 | 0.057 | 0.064 |
|  | 50 | 0.099 | 0.053 | 0.031 | 0.049 | 0.049 | 0.051 |
|  | 100 | 0.048 | 0.354 | 0.031 | 0.047 | 0.050 | 0.050 |
| 10 | 10 | 0.000 | 0.000 | 0.017 | 0.050 | 0.052 | 0.043 |
|  | 25 | 0.000 | 0.038 | 0.018 | 0.049 | 0.045 | 0.051 |
|  | 50 | 0.039 | 0.532 | 0.029 | 0.055 | 0.057 | 0.059 |
|  | 100 | 0.081 | 0.497 | 0.023 | 0.048 | 0.046 | 0.049 |
| 25 | 10 | 0.000 | 0.000 | 0.004 | 0.066 | 0.050 | 0.057 |
|  | 25 | 0.000 | 0.069 | 0.010 | 0.063 | 0.059 | 0.062 |
|  | 50 | 0.037 | 0.394 | 0.015 | 0.066 | 0.049 | 0.062 |
|  | 100 | 0.348 | 0.306 | 0.017 | 0.054 | 0.052 | 0.052 |
| 50 | 10 | 0.000 | 0.000 | 0.000 | 0.057 | 0.052 | 0.050 |
|  | 25 | 0.000 | 0.030 | 0.003 | 0.067 | 0.060 | 0.068 |
|  | 50 | 0.033 | 0.368 | 0.005 | 0.052 | 0.043 | 0.051 |
|  | 100 | 0.062 | 0.630 | 0.010 | 0.053 | 0.047 | 0.048 |
|  |  | POWER |  |  |  |  |  |
| 5 | 10 | 0.000 | 0.000 | 0.040 | 0.064 | 0.060 | 0.057 |
|  | 25 | 0.040 | 0.155 | 0.044 | 0.121 | 0.074 | 0.112 |
|  | 50 | 0.143 | 0.232 | 0.108 | 0.252 | 0.133 | 0.212 |
|  | 100 | 0.695 | 0.994 | 0.433 | 0.742 | 0.438 | 0.646 |
| 10 | 10 | 0.000 | 0.000 | 0.023 | 0.083 | 0.051 | 0.068 |
|  | 25 | 0.001 | 0.119 | 0.038 | 0.180 | 0.084 | 0.143 |
|  | 50 | 0.369 | 0.974 | 0.193 | 0.523 | 0.237 | 0.390 |
|  | 100 | 0.964 | 1.000 | 0.752 | 0.968 | 0.716 | 0.901 |
| 25 | 10 | 0.000 | 0.000 | 0.006 | 0.120 | 0.063 | 0.091 |
|  | 25 | 0.000 | 0.312 | 0.040 | 0.356 | 0.135 | 0.248 |
|  | 50 | 0.382 | 0.990 | 0.327 | 0.864 | 0.402 | 0.688 |
|  | 100 | 0.999 | 1.000 | 0.980 | 1.000 | 0.968 | 0.998 |
| 50 | 10 | 0.000 | 0.000 | 0.001 | 0.153 | 0.064 | 0.104 |
|  | 25 | 0.000 | 0.253 | 0.035 | 0.568 | 0.187 | 0.382 |
|  | 50 | 0.535 | 0.999 | 0.541 | 0.984 | 0.630 | 0.909 |
|  | 100 | 1.000 | 1.000 | 1.000 | 1.000 | 1.000 | 1.000 |

NOTES: Data Generating Processes for all six tests based on the null hypothesis of no cointegration as following: $y_{i t}=\alpha_{i}+\beta_{i} x_{i t}+u_{i t}(i=1, \ldots, N, t=1, \ldots, T)$ and $x_{i t}=x_{i t-1}+\epsilon_{i t} ; u_{i t}=\rho u_{i t-1}+v_{i t}$; $v_{i t}=v_{i t}^{*}+\theta_{i} v_{i t-1}^{*}$ with:

$$
\left[\begin{array}{l}
v_{i t}^{*} \\
\epsilon_{i t}
\end{array}\right] \sim \mathrm{N}\left(\left[\begin{array}{l}
0 \\
0
\end{array}\right],\left[\begin{array}{cc}
1 & \delta \sigma_{i} \\
\delta \sigma_{i} & \sigma_{i}^{2}
\end{array}\right]\right)
$$

where $v_{i t}^{*} \sim N(0,1), \epsilon_{i t} \sim N\left(0, \sigma_{i}^{2}\right) . \alpha_{i}, \beta_{i}$ and $\sigma_{i}$ are generated using the uniform distribution as: $\alpha_{i} \sim U[0,10], \beta_{i} \sim U[0,2]$ and $\sigma_{i} \sim U[0.5,1.5] . \alpha_{i}, \beta_{i}$ and $\sigma_{i}$ are generated once and fixed in all replications. $\rho=1$ for size and $\rho=0.9$ for power. $T+50$ observations are generated and the first 50 observations are eliminated, using only last $T$ observations. Number of replications is set to 3,000 for computing the empirical size and power of all five tests. The size and power of tests are computed at the $5 \%$ nominal level.
$\delta=0.5$ and $\theta_{i}=0 \sim U[-0.4,0.4]$ is set in this table, so there is endogeneity between $x_{i t}$ and $u_{i t}$ and serial correlation in $v_{i t}$.

## APPENDIX

## Proof of Proposition 3.1:

$$
X_{t}+\alpha_{1} X_{t-1}+\alpha_{2} X_{t-2}+\ldots+\alpha_{p} X_{t-p}=e_{t}
$$

Multiply both side by $X_{t-h} \Longleftrightarrow$

$$
\begin{gathered}
X_{t-h} X_{t}+\alpha_{1} X_{t-h} X_{t-1}+\ldots+\alpha_{p} X_{t-h} X_{t-p}=X_{t-h} e_{t} \\
\Longleftrightarrow \quad E\left[X_{t-h} X_{t}\right]+\alpha_{1} E\left[X_{t-h} X_{t-1}\right]+\ldots+\alpha_{p} E\left[X_{t-h} X_{t-p}\right]=E\left[X_{t-h} e_{t}\right] \\
\Longleftrightarrow \quad \gamma(h)+\alpha_{1} \gamma(h-1)+\ldots+\alpha_{p} \gamma(h-p)=E\left[X_{t-h} e_{t}\right]
\end{gathered}
$$

with $\gamma(h-p)=E\left[X_{t-h} X_{t-p}\right]$ and $h=1,2, \ldots$.
From the theorem 3.0 we have that $X_{t-h}$ can be expressed as a weighted average if $e_{t-h}$ and previous $e^{\prime} s$ then $X_{t-h}$ and $e_{t}$ are uncorrelated $\longrightarrow \operatorname{Cov}\left(X_{t-h}, e_{t}\right)=E\left[X_{t-h} e_{t}\right]=0$ with $h=1,2, \ldots$. If $h=0$ then

$$
X_{t}=e_{t}+w_{1} e_{t-1}+w_{2} e_{t-2}+\ldots+\ldots
$$

$\longrightarrow$

$$
E\left[X_{t} e_{t}\right]=E\left[e_{t}^{2}\right]+w_{1} E\left[e_{t} e_{t-1}\right]+w_{2} E\left[e_{t} e_{t-2}\right]+\ldots+\ldots=E\left[e_{t}^{2}\right]=\sigma^{2}
$$

So we have

$$
\gamma(h)+\alpha_{1} \gamma(h-1)+\ldots+\alpha_{p} \gamma(h-p)=\left\{\begin{array}{cl}
0 & h=1,2, \ldots  \tag{42}\\
\sigma^{2} & h=0
\end{array}\right.
$$

note that, from the theorem 3.0, $\left\{X_{t}\right\}$ is a covariance stationary series, then:

$$
\gamma(h)=E\left[X_{t-h} X_{t}\right]=E\left[X_{t+h} X_{t}\right]=\gamma(-h)
$$

and

$$
\begin{aligned}
E\left[X_{t-h} X_{t}\right] & =E\left[X_{t+h} X_{t}\right] \\
E\left[X_{t-h} X_{t-1}\right] & =E\left[X_{t+h} X_{t+1}\right] \\
& \vdots \\
E\left[X_{t-h} X_{t-p}\right] & =E\left[X_{t+h} X_{t+p}\right]
\end{aligned}
$$

adding up and combine to (42)

$$
E\left[X_{t+h}\left(X_{t}+\alpha_{1} X_{t+1}+\alpha_{2} X_{t+2}+\ldots+\alpha_{p} X_{t+p}\right)\right]=\left\{\begin{array}{cl}
0 & h=1,2, \ldots \\
\sigma^{2} & h=0
\end{array}\right.
$$

or

$$
E\left[X_{t+h} v_{t}\right]=\left\{\begin{array}{cl}
0 & h=1,2, \ldots  \tag{43}\\
\sigma^{2} & h=0
\end{array}\right.
$$

To prove the proposition, we need to prove: $\left\{v_{t}\right\}$ is an un correlated $\left(0, \sigma^{2}\right)$ random variables, this means: $E\left(v_{t}\right)=0 ; E\left[v_{t}^{2}\right]=\sigma^{2}$ and $E\left[v_{t+j} v_{t}\right]=0 ; j=1,2, \ldots$

$$
\left.E\left(v_{t}\right)=E\left[X_{t}+\alpha_{1} X_{t+1}+\ldots+\alpha_{p} X_{t+p}\right]=E\left[X_{t}\right]+\alpha_{1} E\left[X_{t+1}\right]+\ldots+\alpha_{p} E\left[X_{t+p}\right]\right)=0
$$

remember that $X_{t}=e_{t}+w_{1} e_{t-1}+\ldots+\ldots$ then $E\left[X_{t}\right]=E\left[e_{t}\right]+w_{1} E\left[e_{t-1}\right]+\ldots+\ldots=0$

$$
\begin{gathered}
E\left[v_{t}^{2}\right]=E\left[\left(X_{t}+\alpha_{1} X_{t+1}+\ldots+\alpha_{p} X_{t+p}\right) v_{t}\right]=E\left[X_{t} v_{t}+\alpha_{1} X_{t+1} v_{t}+\ldots+\alpha_{p} X_{t+p} v_{t}\right]= \\
=E\left[X_{t} v_{t}\right]+\alpha_{1} E\left[X_{t+1} v_{t}\right]+\ldots+\alpha_{p} E\left[X_{t+p} v_{t}\right]=\sigma^{2}
\end{gathered}
$$

because of (43)

$$
\begin{aligned}
& E\left[v_{t+j} v_{t}\right]=E\left[v_{t}\left(X_{t+j}+\alpha_{1} X_{t+j+1}+\ldots+\alpha_{p} X_{t+j+p}\right)\right]= \\
& =e\left[X_{t+j} v_{t}\right]+\alpha_{1} E\left[X_{t+j+1} v_{t}\right]+\ldots+\alpha_{p} E\left[X_{t+j+p} v_{t}\right]=0
\end{aligned}
$$

with $j=1,2, \ldots$ because of (43)

## Proof of Proposition 3.2:

Weighed symmetric estimator of $\rho$ in (16) is a $\hat{\rho}$ which minimizes:

$$
Q=\sum_{t=2}^{T} w_{t}\left(y_{t}-\rho y_{t-1}\right)^{2}+\sum_{t=1}^{T-1}\left(1-w_{t+1}\right)\left(y_{t}-\rho y_{t+1}\right)^{2}
$$

$\Longleftrightarrow$

$$
\begin{equation*}
Q=\sum_{t=2}^{T}\left[\left(\sqrt{w_{t}}\right) y_{t}-\rho\left(\sqrt{w_{t}}\right) y_{t-1}\right]^{2}+\sum_{t=1}^{T-1}\left[\left(\sqrt{1-w_{t+1}}\right) y_{t}-\rho\left(\sqrt{1-w_{t+1}}\right) y_{t+1}\right]^{2} \tag{44}
\end{equation*}
$$

if we denote: $X=\left[\begin{array}{c}\left(\sqrt{w_{2}}\right) y_{1} \\ \vdots \\ \left(\sqrt{w_{T}}\right) y_{T-1} \\ \left(\sqrt{1-w_{2}}\right) y_{2} \\ \vdots \\ \left(\sqrt{1-w_{T}}\right) y_{T}\end{array}\right] ; Y=\left[\begin{array}{c}\left(\sqrt{w_{2}}\right) y_{2} \\ \vdots \\ \left(\sqrt{w_{T}}\right) y_{T} \\ \left(\sqrt{1-w_{2}}\right) y_{1} \\ \vdots \\ \left(\sqrt{1-w_{T}}\right) y_{T-1}\end{array}\right]$ and estimate (44) by
normal OLS method, we get

$$
\hat{\rho}=\left[X^{\prime} X\right]^{-1} X^{\prime} Y=\frac{\sum_{t=2}^{T} w_{t}\left(y_{t} y_{t-1}\right)+\sum_{t=1}^{T-1} y_{t} y_{t+1}-\sum_{t=1}^{T-1} w_{t+1}\left(y_{t} y_{t+1}\right)}{\sum_{t=2}^{T} w_{t} y_{t-1}^{2}+\sum_{t=1}^{T-1} y_{t+1}^{2}-\sum_{t=1}^{T-1} w_{t+1} y_{t+1}^{2}}
$$

put $w_{t}=T^{-1}(t-1)$, then simplify the expressions, we have:

$$
\begin{gathered}
\text { Numerator }=T^{-1} \sum_{t=2}^{T}(t-1) y_{t} y_{t-1}+\sum_{t=1}^{T-1} y_{t} y_{t+1}-T^{-1} \sum_{t=1}^{T-1} t\left(y_{t} y_{t+1}\right)=\sum_{t=2}^{T} y_{t} y_{t-1} \\
\text { Denominator }=T^{-1} \sum_{t=2}^{T}(t-1) y_{t-1}^{2}+\sum_{t=1}^{T-1} y_{t+1}^{2}-T^{-1} \sum_{t=1}^{T-1} t\left(y_{t+1}^{2}\right)=\sum_{t=2}^{T} y_{t}^{2}+\frac{1}{T} \sum_{t=1}^{T} y_{t}^{2}
\end{gathered}
$$

If an intercept $\alpha$ is added in (16), then we can demean (16) as: $\left(y_{t}-\bar{y}\right)=\rho\left(y_{t-1}-\bar{y}\right)+\epsilon_{t}$ with $\bar{y}=T^{-1} \sum_{t=1}^{T} y_{t}$ and the same result of $\hat{\rho}$ is derived as in (21)

## Proof of Proposition 3.3:

$\underline{(\hat{\rho}-1) \text { distribution: }}$

$$
(\hat{\rho}-1)=\frac{\sum_{t=2}^{T} y_{t} y_{t-1}-\sum_{t=2}^{T-1} y_{t}^{2}-\frac{1}{T} \sum_{t=1}^{T} y_{t}^{2}}{\sum_{t=2}^{T-1} y_{t}^{2}+\frac{1}{T} \sum_{t=1}^{T} y_{t}^{2}}
$$

Numerator:

$$
\begin{gathered}
\sum_{t=2}^{T} y_{t-1}\left(y_{t-1}+\epsilon_{t}\right)-\sum_{t=2}^{T-1} y_{t}^{2}-\frac{1}{T} \sum_{t=1}^{T} y_{t}^{2}= \\
=\sum_{t=2}^{T} y_{t-1}^{2}+\sum_{t=2}^{T} y_{t-1} \epsilon_{t}-\sum_{t=2}^{T-1} y_{t}^{2}-\frac{1}{T} \sum_{t=1}^{T} y_{t}^{2}= \\
=\sum_{t=2}^{T} y_{t-1} \epsilon_{t}+y_{1}^{2}-\frac{1}{T} \sum_{t=1}^{T} y_{t-1}^{2}+\frac{y_{T}^{2}}{T}
\end{gathered}
$$

then

$$
\frac{1}{T}(\text { numerator })=\frac{1}{T} \sum_{t=2}^{T} y_{t-1} \epsilon_{t}+\frac{y_{1}^{2}}{T}-\frac{1}{T^{2}} \sum_{t=1}^{T} y_{t-1}^{2}-\frac{1}{T}\left(\frac{y_{T}}{\sqrt{T}}\right)^{2} \xrightarrow{L} \frac{1}{2} \sigma^{2}\left[W^{2}(1)-1\right]-\sigma^{2} \int_{0}^{1}[W(r)]^{2} d r
$$

Denominator:

$$
\begin{aligned}
& \sum_{t=2}^{T-1} y_{t}^{2}+\frac{1}{T} \sum_{t=1}^{T} y_{t}^{2}=\sum_{t=2}^{T} y_{t}^{2}-y_{T}^{2}+\frac{1}{T} \sum_{t=1}^{T} y_{t}^{2}=\left(1+\frac{1}{T}\right) \sum_{t=1}^{T} y_{t}^{2}-\left(y_{1}^{2}+y_{T}^{2}\right)= \\
& =\left(1+\frac{1}{T}\right) \sum_{t=1}^{T} y_{t-1}^{2}-\left(y_{1}^{2}+y_{T}^{2}\right)+\left(1+\frac{1}{T}\right) y_{T}^{2}=\left(1+\frac{1}{T}\right) \sum_{t=1}^{T} y_{t-1}^{2}-y_{1}^{2}+\frac{1}{T} y_{T}^{2}
\end{aligned}
$$

then

$$
\frac{1}{T^{2}}(\text { denominator })=\left(1+\frac{1}{T}\right) \sum_{t=1}^{T} y_{t-1}^{2}-\frac{y_{1}^{2}}{T}+\frac{y_{T}^{2}}{T^{2}} \xrightarrow{L} \sigma^{2} \int_{0}^{1}[W(r)]^{2} d r
$$

finally:

$$
T(\hat{\rho}-1) \xrightarrow{L} \frac{\frac{1}{2}\left[W^{2}(1)-1\right]-\int_{0}^{1}[W(r)]^{2} d r}{\int_{0}^{1}[W(r)]^{2} d r}=\frac{\frac{1}{2}\left[K^{2}-1\right]-G}{G}
$$

with $K=W(1)$ and $G=\int_{0}^{1}[W(r)]^{2} d r$
$\underline{t_{\hat{\rho}} \text { distribution: }}$

$$
t_{\hat{\rho}}=\left[\hat{\sigma}^{2}\left(\sum_{t=2}^{T-1} y_{t}^{2}+\frac{1}{T} \sum_{t=1}^{T} y_{t}^{2}\right)^{-1}\right]^{-1 / 2}(\hat{\rho}-1)
$$

where $\hat{\sigma}^{2}$ is the estimation of $\sigma^{2}$ by: $\hat{\sigma}^{2}=\frac{Q(\hat{\rho})}{T-2} \xrightarrow{p} \sigma^{2}$, then:

$$
t_{\hat{\rho}}=\frac{T(\hat{\rho}-1)}{\left[\frac{\hat{\sigma}^{2}}{\frac{1}{T}\left(\sum_{t=2}^{T-1} y_{t}^{2}+\frac{1}{T} \sum_{t=1}^{T} y_{t}^{2}\right)}\right]^{-1 / 2}} \xrightarrow{L} \frac{\frac{1}{2}\left[W^{2}(1)-1\right]-\int_{0}^{1}[W(r)]^{2} d r}{\left(\int_{0}^{1}[W(r)]^{2} d r\right)^{1 / 2}}=\frac{\frac{1}{2}\left[K^{2}-1\right]-G}{G^{1 / 2}}
$$

## Proof of Proposition 3.4:

Before proving the proposition, we prove the following results:
Lemma 1: Under the null hypothesis of $\rho=1$
i) $\frac{1}{T}\left(y_{1}-\bar{y}\right)^{2} \xrightarrow{L} H^{2}$
ii) $\frac{1}{T}\left(y_{T}-\bar{y}\right)^{2} \xrightarrow{L} H^{2}-2 K H+K^{2}$
iii) $\bar{y} \cdot \bar{\epsilon} \xrightarrow{L} K H$
iv) $\frac{1}{T} \sum_{t=1}^{T} y_{t} \epsilon_{t} \xrightarrow{L} \frac{1}{2}\left[K^{2}-1\right]+1$
v) $\frac{1}{T^{2}} \sum_{t=1}^{T}\left(y_{t}-\bar{y}\right)^{2} \xrightarrow{L} G-H^{2}$
where $\bar{y}=\frac{1}{T} \sum_{t=1}^{T} y_{t} ; K=W(1) ; H=\int_{0}^{1} W(r) d r ; G=\int_{0}^{1}[W(r)]^{2} d r ;$ and assume $\sigma=1$; $y_{0}=0$

Proof:
i) $T^{-1}\left(y_{1}-\bar{y}\right)^{2}=T^{-1}\left(y_{1}^{2}-2 \bar{y} y_{1}+(\bar{y})^{2}\right)=T^{-1}\left[y_{1}^{2}-2 y_{1}\left(T^{-1} \sum_{t=1}^{T} y_{t}\right)+T^{-2}\left(\sum_{t=1}^{T} y_{t}\right)^{2}\right]=$

$$
\begin{gathered}
=T^{-1}\left[y_{1}^{2}-2 y_{1} T^{-1}\left(\sum_{t=1}^{T} y_{t-1}+y_{T}\right)+T^{-2}\left(\sum_{t=1}^{T} y_{t-1}+y_{T}\right)^{2}\right]= \\
=\frac{y_{1}^{2}}{T}-\left(\frac{2 y_{1}}{\sqrt{T}}\right)\left(\frac{1}{T^{3 / 2}} \sum_{t=1}^{T} y_{t-1}\right)-\left(\frac{2 y_{1}}{T^{3 / 2}}\right)\left(\frac{y_{T}}{\sqrt{T}}\right)+\left(\frac{1}{T^{3 / 2}} \sum_{t=1}^{T} y_{t-1}\right)^{2}+ \\
+2\left(\frac{1}{T}\right)\left(\frac{y_{T}}{\sqrt{T}}\right)\left(\frac{1}{T^{3 / 2}} \sum_{t=1}^{T} y_{t-1}\right)+\left(\frac{1}{T}\right)\left(\frac{y_{T}}{\sqrt{T}}\right)^{2} \xrightarrow{L}\left[\int_{0}^{1} W(r) d r\right]^{2}=H^{2}
\end{gathered}
$$

$$
\begin{aligned}
& \text { ii) } T^{-1}\left(y_{T}-\bar{y}\right)^{2}=T^{-1}\left(y_{T}^{2}-2 \bar{y} y_{T}+(\bar{y})^{2}\right)=T^{-1}\left[y_{T}^{2}-2 y_{T}\left(T^{-1} \sum_{t=1}^{T} y_{t}\right)+T^{-2}\left(\sum_{t=1}^{T} y_{t}\right)^{2}\right]= \\
& =T^{-1}\left[y_{T}^{2}-2 y_{T} T^{-1}\left(\sum_{t=1}^{T} y_{t-1}+y_{T}\right)+T^{-2}\left(\sum_{t=1}^{T} y_{t-1}+y_{T}\right)^{2}\right]= \\
& =\left(\frac{y_{T}}{\sqrt{T}}\right)^{2}-2\left(\frac{y_{T}}{\sqrt{T}}\right)\left(\frac{1}{T^{3 / 2}} \sum_{t=1}^{T} y_{t-1}\right)-2\left(\frac{1}{T}\right)\left(\frac{y_{T}}{\sqrt{T}}\right)^{2}\left(\frac{y_{T}}{\sqrt{T}}\right)+\left(\frac{1}{T^{3 / 2}} \sum_{t=1}^{T} y_{t-1}\right)^{2}+ \\
& +2\left(\frac{1}{T}\right)\left(\frac{y_{T}}{\sqrt{T}}\right)\left(\frac{1}{T^{3 / 2}} \sum_{t=1}^{T} y_{t-1}\right)+\left(\frac{1}{T}\right)\left(\frac{y_{T}}{\sqrt{T}}\right)^{2} \xrightarrow[\longrightarrow]{L}\left[\int_{0}^{1} W(r) d r\right]^{2}-2 W(1) \int_{0}^{1} W(r) d r+ \\
& +[W(1)]^{2}=H^{2}-2 K H+K^{2} \\
& \quad \text { iii) } \bar{y} \cdot \bar{\epsilon}=T^{-2} \sum_{t=1}^{T} y_{t} \sum_{t=1}^{T} \epsilon_{t}=\frac{1}{T^{2}}\left(\sum_{t=1}^{T} y_{t-1}+y_{T}\right) \sum_{t=1}^{T} \epsilon_{t}=
\end{aligned}
$$

$$
=\left(\frac{1}{T^{3 / 2}} \sum_{t=1}^{T}+\frac{1}{T}\left(\frac{y_{T}}{\sqrt{T}}\right)\right)\left(\frac{1}{\sqrt{T}} \sum_{t=1}^{T} \epsilon_{t}\right) \xrightarrow{L} W(1) \int_{0}^{1} W(r) d r=K H
$$

iv) $\frac{1}{T} \sum_{t=1}^{T} y_{t} \epsilon_{t}=\frac{1}{T} \sum_{t=1}^{T}\left(y_{t-1}+\epsilon_{t}\right) \epsilon_{t}=\frac{1}{T} \sum_{t=1}^{T} y_{t-1} \epsilon_{t}+\frac{1}{T} \sum_{t=1}^{T} \epsilon_{t}^{2} \xrightarrow{L} \frac{1}{2}\left[K^{2}-1\right]+1$
v) $\frac{1}{T^{2}} \sum_{t=1}^{T}\left(y_{t}-\bar{y}\right)^{2}=\frac{1}{T^{2}}\left(\sum_{t=2}^{T} y_{t}^{2}-2 \bar{y} \sum_{t=2}^{T} y_{t}+(T-2) \bar{y}^{2}\right)=$

$$
\begin{gathered}
=\frac{1}{T^{2}} \sum_{t=2}^{T} y_{t}^{2}-\frac{2}{T^{3}} \sum_{t=1}^{T} y_{t} \sum_{t=2}^{T} y_{t}+\frac{T-2}{T^{4}}\left(\sum_{t=1}^{T} y_{t}\right)^{2}= \\
=\frac{1}{T^{2}} \sum_{t=2}^{T} y_{t}^{2}-2\left(\frac{1}{T^{3 / 2}} \sum_{t=1}^{T} y_{t}\right)\left(\frac{1}{T^{3 / 2}} \sum_{t=2}^{T} y_{t}\right)+\left(\frac{T-2}{T}\right)\left(\frac{1}{T^{3 / 2}} \sum_{t=1}^{T} y_{t}\right)^{2} \xrightarrow{L} \\
\xrightarrow{L} G-2 H \cdot H+H^{2}=G-H^{2}
\end{gathered}
$$

$\underline{(\hat{\rho}-1) \text { distribution: }}$

$$
(\hat{\rho}-1)=\frac{\sum_{t=2}^{T}\left(y_{t}-\bar{y}\right)\left(y_{t-1}-\bar{y}\right)-\sum_{t=2}^{T-1}\left(y_{t}-\bar{y}\right)^{2}-\frac{1}{T} \sum_{t=1}^{T}\left(y_{t}-\bar{y}\right)^{2}}{\sum_{t=2}^{T-1}\left(y_{t}-\bar{y}\right)^{2}+\frac{1}{T} \sum_{t=1}^{T}\left(y_{t}-\bar{y}\right)^{2}}
$$

because of: $\sum_{t=2}^{T}\left(y_{t}-\bar{y}\right)\left(y_{t-1}-\bar{y}\right)=\sum_{t=2}^{T}\left(y_{t}-\bar{y}\right)\left(y_{t}-\bar{y}-y_{t}+y_{t-1}\right)=$

$$
=\sum_{t=2}^{T}\left[\left(y_{t}-\bar{y}\right)^{2}-\left(y_{t}-\bar{y}\right) \epsilon_{t}\right]
$$

so,

$$
\text { Numerator }=\left(y_{T}-\bar{y}\right)^{2}-\sum_{t=2}^{T} y_{t} \epsilon_{t}+\bar{y} \sum_{t=2}^{T} \epsilon_{t}-\frac{1}{T} \sum_{t=1}^{T}\left(y_{t}-\bar{y}\right)^{2}
$$

and
$\frac{1}{T}($ numerator $)=\frac{1}{T}\left(y_{T}-\bar{y}\right)^{2}-\frac{1}{T} \sum_{t=2}^{T} y_{t} \epsilon_{t}+\bar{y} \cdot \bar{\epsilon}-\frac{1}{T^{2}} \sum_{t=1}^{T}\left(y_{t}-\bar{y}\right)^{2} \xrightarrow{L}$ follow lemma 1
$\xrightarrow{L}\left(H^{2}-2 K H+K^{2}\right)-\left(\frac{1}{2}\left[K^{2}-1\right]+1\right)+K H-\left(G-H^{2}\right)=\frac{1}{2}\left[K^{2}-1\right]-G-K H+2 H^{2}$
$\frac{1}{T^{2}}($ denominator $)=\frac{1}{T^{2}} \sum_{t=2}^{T-1}\left(y_{t}-\bar{y}\right)^{2}+\frac{1}{T}\left(\frac{1}{T^{2}} \sum_{t=1}^{T}\left(y_{t}-\bar{y}\right)^{2}\right) \xrightarrow{L}$ follow lemma $1 \xrightarrow{L}\left(G-H^{2}\right)$
finally:

$$
T(\hat{\rho}-1) \xrightarrow{L} \frac{\left(\frac{1}{2}\left[K^{2}-1\right]-G-K H+2 H^{2}\right)}{\left[G-H^{2}\right]}
$$

$\underline{t_{\hat{\rho}} \text { distribution: }}$

$$
t_{\hat{\rho}}=\left[\hat{\sigma}^{2}\left(\sum_{t=2}^{T-1}\left(y_{t}-\bar{y}\right)^{2}+\frac{1}{T} \sum_{t=1}^{T}\left(y_{t}-\bar{y}\right)^{2}\right)^{-1}\right]^{-1 / 2}(\hat{\rho}-1)
$$

where $\hat{\sigma}^{2}$ is the estimation of $\sigma^{2}$ by: $\hat{\sigma}^{2}=\frac{Q(\hat{\rho})}{T-2} \xrightarrow{p} \sigma^{2}$, then:

$$
t_{\hat{\rho}}=\frac{T(\hat{\rho}-1)}{\left[\frac{\hat{\sigma}^{2}}{\frac{1}{T}\left(\sum_{t=2}^{T-1}\left(y_{t}-\bar{y}\right)^{2}+\frac{1}{T} \sum_{t=1}^{T}\left(y_{t}-\bar{y}\right)^{2}\right)}\right]^{-1 / 2}} \xrightarrow{L}=\frac{\left(\frac{1}{2}\left[K^{2}-1\right]-G-K H+2 H^{2}\right)}{\left[G-H^{2}\right]^{1 / 2}}
$$

## Proof of proposition 3.5:

The following result is taken from Phillips (1986)
Lemma 2: Under the null hypothesis of no cointegration $H_{0}: \rho=1$ in (31)
i)

$$
\hat{\beta} \xrightarrow{L} \frac{\int_{0}^{1} V(r) W(r) d r-\int_{0}^{1} V(r) d r \int_{0}^{1} W(r) d r}{\int_{0}^{1}[W(r)]^{2} d r-\left[\int_{0}^{1} W(r) d r\right]^{2}}=\zeta
$$

ii)

$$
\frac{1}{T} \sum_{t=2}^{T}\left(\hat{u}_{t}-\hat{u}_{t-1}\right)^{2}=\frac{1}{T} \sum_{t=2}^{T}\left(v_{t}-\hat{\beta} \epsilon_{t}\right)^{2} \xrightarrow{L}\left(1+\zeta^{2}\right) \sigma^{2}
$$

Proof: see Phillips (1986)
$\underline{(\hat{\rho}-1) \text { distribution: }}$

$$
(\hat{\rho}-1)=\frac{\sum_{t=2}^{T} \hat{u}_{t} \hat{u}_{t-1}-\sum_{t=2}^{T-1} \hat{u}_{t}^{2}-\frac{1}{T} \sum_{t=1}^{T} \hat{u}_{t}^{2}}{\sum_{t=2}^{T-1} \hat{u}_{t}^{2}+\frac{1}{T} \sum_{t=1}^{T} \hat{u}_{t}^{2}}
$$

we have

$$
\begin{aligned}
& \sum_{t=2}^{T}\left(\hat{u}_{t}-\hat{u}_{t-1}\right)^{2}=\sum_{t=2}^{T} \hat{u}_{t}^{2}-2 \sum_{t=2}^{T} \hat{u}_{t} \hat{u}_{t-1}+\sum_{t=2}^{T} \hat{u}_{t-1}^{2} \\
\longrightarrow & \sum_{t=2}^{T} \hat{u}_{t} \hat{u}_{t-1}=\frac{1}{2} \sum_{t=2}^{T} \hat{u}_{t}^{2}+\frac{1}{2} \sum_{t=2}^{T} \hat{u}_{t-1}^{2}-\frac{1}{2} \sum_{t=2}^{T}\left(\hat{u}_{t}-\hat{u}_{t-1}\right)^{2}
\end{aligned}
$$

then

$$
\begin{gathered}
\text { Numerator }=\sum_{t=2}^{T} \hat{u}_{t} \hat{u}_{t-1}-\sum_{t=2}^{T-1} \hat{u}_{t}^{2}-\frac{1}{T} \sum_{t=1}^{T} \hat{u}_{t}^{2}= \\
=\frac{1}{2} \sum_{t=2}^{T} \hat{u}_{t}^{2}+\frac{1}{2} \sum_{t=2}^{T} \hat{u}_{t-1}^{2}-\frac{1}{2} \sum_{t=2}^{T}\left(\hat{u}_{t}-\hat{u}_{t-1}\right)^{2}-\sum_{t=2}^{T-1} \hat{u}_{t}^{2}-\frac{1}{T} \sum_{t=1}^{T} \hat{u}_{t}^{2}= \\
=\frac{1}{2} \hat{u}_{T}^{2}+\frac{1}{2} \hat{u}_{1}^{2}-\frac{1}{T} \sum_{t=1}^{T} \hat{u}_{t}^{2}-\frac{1}{2} \sum_{t=2}^{T}\left(\hat{u}_{t}-\hat{u}_{t-1}\right)^{2}
\end{gathered}
$$

so

$$
\frac{1}{T}(\text { numerator })=\frac{1}{2}\left(\frac{\hat{u}_{T}^{2}}{T}\right)+\frac{1}{2}\left(\frac{\hat{u}_{1}^{2}}{T}\right)-\frac{1}{T^{2}} \sum_{t=1}^{T} \hat{u}_{t}^{2}-\frac{1}{2}\left(\frac{1}{T} \sum_{t=2}^{T}\left(\hat{u}_{t}-\hat{u}_{t-1}\right)^{2}\right)
$$

(a)

$$
\begin{aligned}
& \frac{1}{T} \hat{u}_{T}^{2}=\frac{1}{T}\left(y_{T}-\hat{\alpha}-\hat{\beta} x_{T}\right)^{2}=\frac{1}{T}\left[\left(y_{T}-\bar{y}\right)-\hat{\beta}\left(x_{T}-\bar{x}\right)\right]^{2} \\
& =\frac{1}{T}\left(y_{T}-\bar{y}\right)^{2}-2 \frac{1}{T} \hat{\beta}\left(x_{T}-\bar{x}\right)\left(y_{T}-\bar{y}\right)+\frac{1}{T} \hat{\beta}^{2}\left(x_{T}-\bar{x}\right)^{2}
\end{aligned}
$$

we have

$$
\begin{gathered}
\quad \frac{1}{T}\left(x_{T}-\bar{x}\right)\left(y_{T}-\bar{y}\right)=\frac{1}{T}\left[x_{T} y_{T}-x_{T} \frac{1}{T} \sum_{t=1}^{T} y_{t}-y_{T} \frac{1}{T} \sum_{t=1}^{T} x_{t}+\frac{1}{T^{2}} \sum_{t=1}^{T} x_{t} \sum_{t=1}^{T} y_{t}\right]= \\
=\frac{x_{T}}{\sqrt{T}} \frac{y_{T}}{\sqrt{T}}-\frac{x_{T}}{\sqrt{T}}\left(\frac{1}{T^{3 / 2}} \sum_{t=1}^{T} y_{t}\right)-\frac{y_{T}}{\sqrt{T}}\left(\frac{1}{T^{3 / 2}} \sum_{t=1}^{T} x_{t}\right)+\left(\frac{1}{T^{3 / 2}} \sum_{t=1}^{T} x_{t}\right)\left(\frac{1}{T^{3 / 2}} \sum_{t=1}^{T} y_{t}\right) \xrightarrow{L} \\
\xrightarrow{L} \sigma^{2}\left[V(1) W(1)-W(1) \int_{0}^{1} V(r) d r-V(1) \int_{0}^{1} W(r) d r-\int_{0}^{1} W(r) d r \int_{0}^{1} V(r) d r\right]=\sigma^{2} A
\end{gathered}
$$

$$
\begin{equation*}
2 \frac{1}{T} \hat{\beta}\left(x_{T}-\bar{x}\right)\left(y_{T}-\bar{y}\right) \xrightarrow{L} 2 \sigma^{2} \zeta A \tag{45}
\end{equation*}
$$

From lemma 1:

$$
\begin{array}{r}
\frac{1}{T}\left(y_{T}-\bar{y}\right)^{2} \xrightarrow{L} \sigma^{2}\left(\left[\int_{0}^{1} V(r) d r\right]^{2}-2 V(1) \int_{0}^{1} V(r) d r+[V(1)]^{2}\right)=\sigma^{2} B_{v} \\
\frac{1}{T} \hat{\beta}^{2}\left(x_{T}-\bar{x}\right)^{2} \xrightarrow{L} \sigma^{2} \zeta^{2}\left(\left[\int_{0}^{1} W(r) d r\right]^{2}-2 W(1) \int_{0}^{1} W(r) d r+[W(1)]^{2}\right)=\sigma^{2} \zeta^{2} B_{w} \tag{47}
\end{array}
$$

From (45), (46), (47):

$$
\begin{align*}
\frac{1}{T} \hat{u}_{T}^{2}=\frac{1}{T}\left(y_{T}-\bar{y}\right)^{2} & -2 \frac{1}{T} \hat{\beta}\left(x_{T}-\bar{x}\right)\left(y_{T}-\bar{y}\right)+\frac{1}{T} \hat{\beta}^{2}\left(x_{T}-\bar{x}\right)^{2} \xrightarrow{L} \\
\xrightarrow{L} & \sigma^{2}\left(B_{v}-2 \zeta A+\zeta^{2} B_{w}\right) \tag{48}
\end{align*}
$$

(b)

$$
\begin{gathered}
\frac{1}{T^{2}} \sum_{t=1}^{T} \hat{u}_{t}^{2}=\frac{1}{T^{2}} \sum_{t=1}^{T}\left(y_{t}-\hat{\alpha}-\hat{\beta} x_{t}\right)^{2}=\frac{1}{T^{2}} \sum_{t=1}^{T}\left[\left(y_{t}-\bar{y}\right)-\hat{\beta}\left(x_{t}-\bar{x}\right)\right]^{2} \\
=\frac{1}{T^{2}} \sum_{t=1}^{T}\left(y_{t}-\bar{y}\right)^{2}-2 \frac{1}{T^{2}} \sum_{t=1}^{T} \hat{\beta}\left(x_{t}-\bar{x}\right)\left(y_{t}-\bar{y}\right)+\frac{1}{T^{2}} \sum_{t=1}^{T} \hat{\beta}^{2}\left(x_{t}-\bar{x}\right)^{2} \\
=\frac{1}{T^{2}} \sum_{t=1}^{T}\left(y_{t}-\bar{y}\right)^{2}-\hat{\beta}^{2} \frac{1}{T^{2}} \sum_{t=1}^{T}\left(x_{t}-\bar{x}\right)^{2} \xrightarrow{L} \text { follow lemma } 1 \xrightarrow{L} \\
\xrightarrow[\longrightarrow]{L} \sigma^{2}\left\{\int_{0}^{1}[V(r)]^{2} d r-\left(\int_{0}^{1} V(r) d r\right)^{2}-\zeta^{2}\left[\int_{0}^{1}[W(r)]^{2} d r-\left(\int_{0}^{1} W(r) d r\right)^{2}\right]\right\}=\sigma^{2} C \\
(\mathrm{c}) \\
\frac{1}{T} \hat{u}_{1}^{2}=\frac{1}{T}\left(y_{1}-\hat{\alpha}-\hat{\beta} x_{1}\right)^{2}=\frac{1}{T}\left[\left(y_{1}-\bar{y}\right)-\hat{\beta}\left(x_{1}-\bar{x}\right)\right]^{2} \\
=\frac{1}{T}\left(y_{1}-\bar{y}\right)^{2}-2 \frac{1}{T} \hat{\beta}\left(x_{1}-\bar{x}\right)\left(y_{1}-\bar{y}\right)+\frac{1}{T} \hat{\beta}^{2}\left(x_{1}-\bar{x}\right)^{2}
\end{gathered}
$$

with

$$
\frac{1}{T}\left(x_{1}-\bar{x}\right)\left(y_{1}-\bar{y}\right)=\frac{1}{T}\left[x_{1} y_{1}-x_{T} \frac{1}{T} \sum_{t=1}^{T} y_{t}-y_{1} \frac{1}{T} \sum_{t=1}^{T} x_{t}+\frac{1}{T^{2}} \sum_{t=1}^{T} x_{t} \sum_{t=1}^{T} y_{t}\right]=
$$

$$
\begin{aligned}
&=\frac{x_{1}}{\sqrt{T}} \frac{y_{1}}{\sqrt{T}}-\frac{x_{1}}{\sqrt{T}}\left(\frac{1}{T^{3 / 2}} \sum_{t=1}^{T} y_{t}\right)-\frac{y_{1}}{\sqrt{T}}\left(\frac{1}{T^{3 / 2}} \sum_{t=1}^{T} x_{t}\right)+\left(\frac{1}{T^{3 / 2}} \sum_{t=1}^{T} x_{t}\right)\left(\frac{1}{T^{3 / 2}} \sum_{t=1}^{T} y_{t}\right) \xrightarrow{L} \\
& \xrightarrow{L} \sigma^{2}\left[\int_{0}^{1} W(r) d r \int_{0}^{1} V(r) d r\right]
\end{aligned}
$$

From lemma 1:

$$
\begin{aligned}
& \frac{1}{T}\left(y_{1}-\bar{y}\right)^{2} \xrightarrow{L} \sigma^{2}\left[\int_{0}^{1} V(r) d r\right]^{2} \\
& \frac{1}{T}\left(x_{1}-\bar{x}\right)^{2} \xrightarrow{L} \sigma^{2}\left[\int_{0}^{1} W(r) d r\right]^{2}
\end{aligned}
$$

so

$$
\frac{1}{T} \hat{u}_{1}^{2} \xrightarrow{L} \sigma^{2}\left[\left(\int_{0}^{1} V(r) d r\right)^{2}+\zeta^{2}\left(\int_{0}^{1} W(r) d r\right)^{2}-2 \zeta \int_{0}^{1} V(r) d r \int_{0}^{1} W(r) d r\right]=\sigma^{2} D
$$

combine (a),(b),(c) and lemma 2, we have:

$$
\begin{gathered}
\left.\frac{1}{T} \text { (numerator }\right) \xrightarrow{L} \frac{1}{2} \sigma^{2}\left(B_{v}-2 \zeta A+\zeta^{2} B_{w}\right)+\frac{1}{2} \sigma^{2} D-\sigma^{2} C-\frac{1}{2} \sigma^{2}\left(1+\zeta^{2}\right) \\
\frac{1}{T^{2}}(\text { denominator })=\frac{1}{T^{2}}\left(\sum_{t=2}^{T-1} \hat{u}_{t}^{2}+\frac{1}{T} \sum_{t=1}^{T} \hat{u}_{t}^{2}\right)=\frac{1}{T^{2}} \sum_{t=1}^{T} \hat{u}_{t}^{2}-\frac{\hat{u}_{1}^{2}}{T^{2}}-\frac{\hat{u}_{T}^{2}}{T^{2}}-\frac{1}{T^{3}} \sum_{t=1}^{T} \hat{u}_{t}^{2} \xrightarrow{L} \sigma^{2} C
\end{gathered}
$$

finally:

$$
T(\hat{\rho}-1) \xrightarrow{L} \frac{\left[\frac{1}{2}\left(B_{v}-2 \zeta A+\zeta^{2} B_{w}\right)+\frac{1}{2} D-C-\frac{1}{2}\left(1+\zeta^{2}\right)\right]}{[C]}
$$

$t_{\hat{\rho}}$ distribution:

$$
t_{\hat{\rho}}=\left[\hat{\sigma}_{e}^{2}\left(\sum_{t=2}^{T-1} \hat{u}_{t}^{2}+\frac{1}{T} \sum_{t=1}^{T} \hat{u}_{t}^{2}\right)^{-1}\right]^{-1 / 2}(\hat{\rho}-1)
$$

where $\hat{\sigma}_{e}^{2}$ is the estimation of variance of $e_{t}$ in (31), under the hypothesis of no cointegration, the estimation of variance of $e_{t}$ in (31) is $\frac{1}{T} \sum_{t=2}^{T}\left(\hat{u}_{t}-\hat{u}_{t-1}\right)^{2}$, then

$$
\hat{\sigma}_{e}^{2}=\frac{1}{T} \sum_{t=2}^{T}\left(\hat{u}_{t}-\hat{u}_{t-1}\right)^{2} \xrightarrow{L}\left(1+\zeta^{2}\right)^{2} \sigma^{2}
$$

then:

$$
t_{\hat{\rho}}=\frac{T(\hat{\rho}-1)}{\left[\frac{\hat{\sigma}_{e}^{2}}{\frac{1}{T}\left(\sum_{t=2}^{T-1} \hat{u}_{t}^{2}+\frac{1}{T} \sum_{t=1}^{T} \hat{u}_{t}^{2}\right)}\right]^{-1 / 2}} \xrightarrow{L} \frac{\left[\frac{1}{2}\left(B_{v}-2 \zeta A+\zeta^{2} B_{w}\right)+\frac{1}{2} D-C-\frac{1}{2}\left(1+\zeta^{2}\right)\right]}{\left[\left(1+\zeta^{2}\right) C\right]^{1 / 2}}
$$

where

$$
\begin{gathered}
A=V(1) W(1)-W(1) \int_{0}^{1} V(r) d r-V(1) \int_{0}^{1} W(r) d r-\int_{0}^{1} V(r) d r \int_{0}^{1} W(r) d r \\
B_{v}=\left[\int_{0}^{1} V(r) d r\right]^{2}-2 V(1) \int_{0}^{1} V(r) d r+[V(1)]^{2} \\
B_{w}=\left[\int_{0}^{1} W(r) d r\right]^{2}-2 W(1) \int_{0}^{1} W(r) d r+[W(1)]^{2} \\
C=\int_{0}^{1}[V(r)]^{2} d r-\left(\int_{0}^{1} V(r) d r\right)^{2}-\zeta^{2}\left[\int_{0}^{1}[W(r)]^{2} d r-\left(\int_{0}^{1} W(r) d r\right)^{2}\right] \\
D=\left[\int_{0}^{1} V(r) d r\right]^{2}+\zeta^{2}\left[\int_{0}^{1} W(r) d r\right]^{2}-2 \zeta \int_{0}^{1} V(r) d r \int_{0}^{1} W(r) d r \\
\zeta=\frac{\int_{0}^{1} V(r) W(r) d r-\int_{0}^{1} V(r) d r \int_{0}^{1} W(r) d r}{\int_{0}^{1}[W(r)]^{2} d r-\left[\int_{0}^{1} W(r) d r\right]^{2}}
\end{gathered}
$$

$V(r)$ and $W(r)$ are the standard Wiener processes on $[0,1]$.


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[^1]:    ${ }^{1}$ All simulations are performed using Matlab 7.0 on a $3.44 \mathrm{GHz}, 2 \mathrm{~GB}$ Ram PC. The programs are available upon requested.

