

The Design and Implementation of an Integrated and Autonomous Fire Detection System (FireBot)

The Problem

There are two main types of household fire: fast flaming fires, and slow smoldering fires. Smoke detectors are typically only optimized for detecting one of these types of fires and perform poorly in detecting the other type. In worst case scenarios, some smoke detectors have been found to only detect fire types they aren't optimized for after upwards of 30 minutes.



Fast Flaming and Slow Smoldering Fires

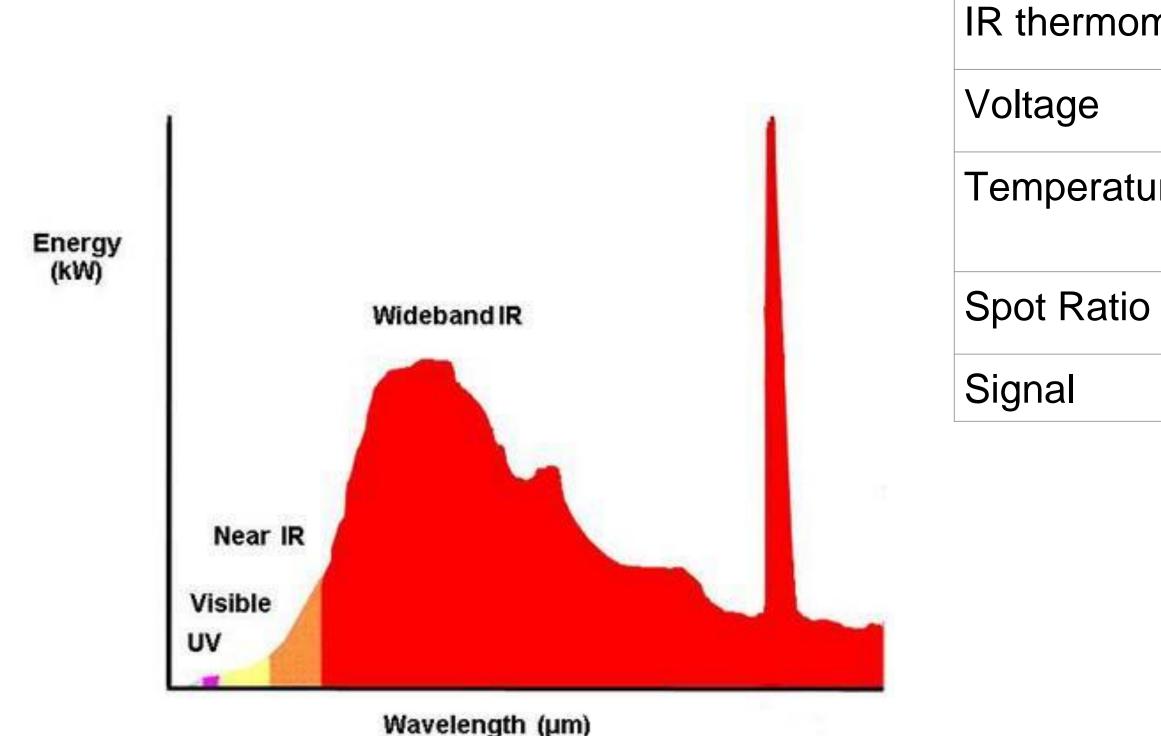
Objectives

Firebot has mainly two objectives:

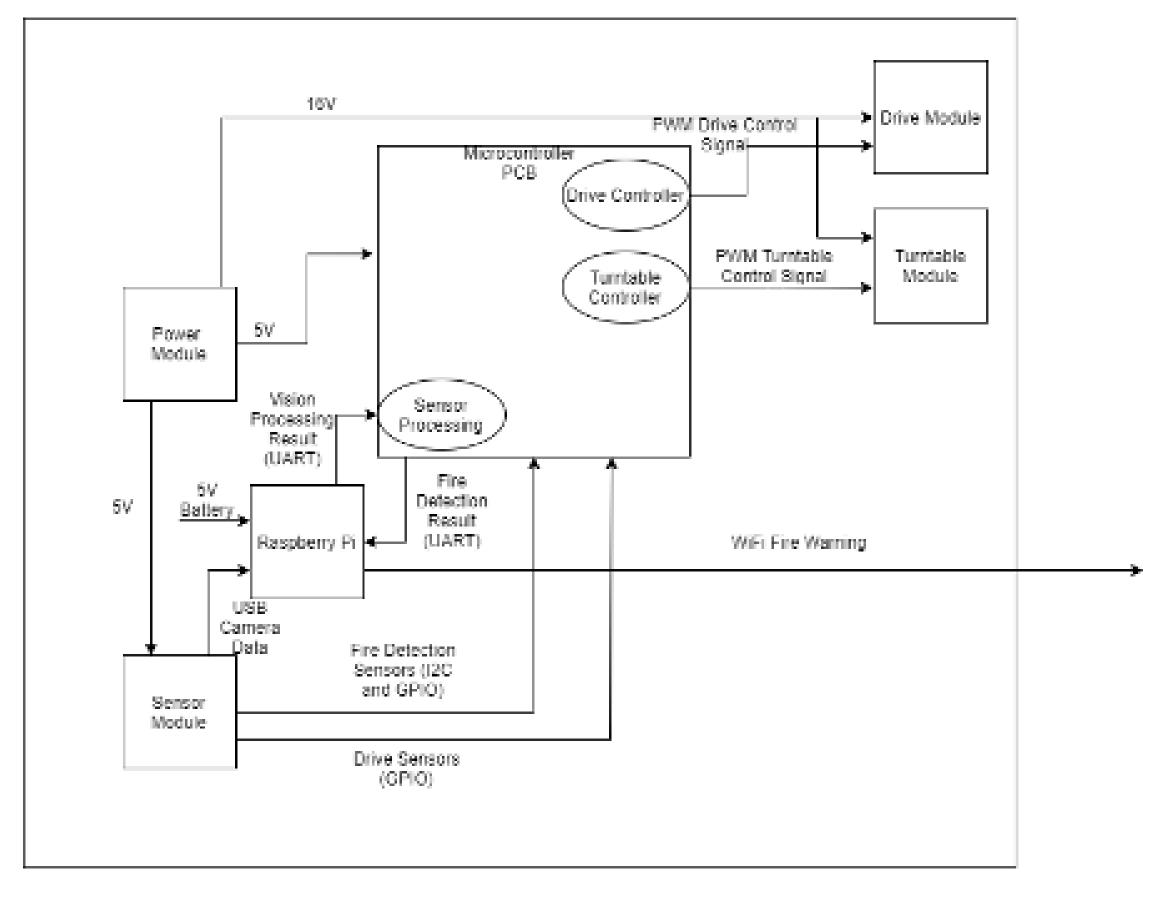
- 1. Detect both fast-flaming fire and slowsmoldering fire using a camera, IR sensors, UV sensors, and a thermometer.
- 1. Notify the user in the case of fire by communicating via WiFi with user's personal device (I.e. PC, laptop, phone), and sending the type of fire and a picture of the fire.

Faisal Almutlq, Hassan Al Bahran, Andrew Zhu, Lisheng Zou, Yibin Xia University of Colorado Boulder, Electrical Engineering Division

Example Fire Emission Spect



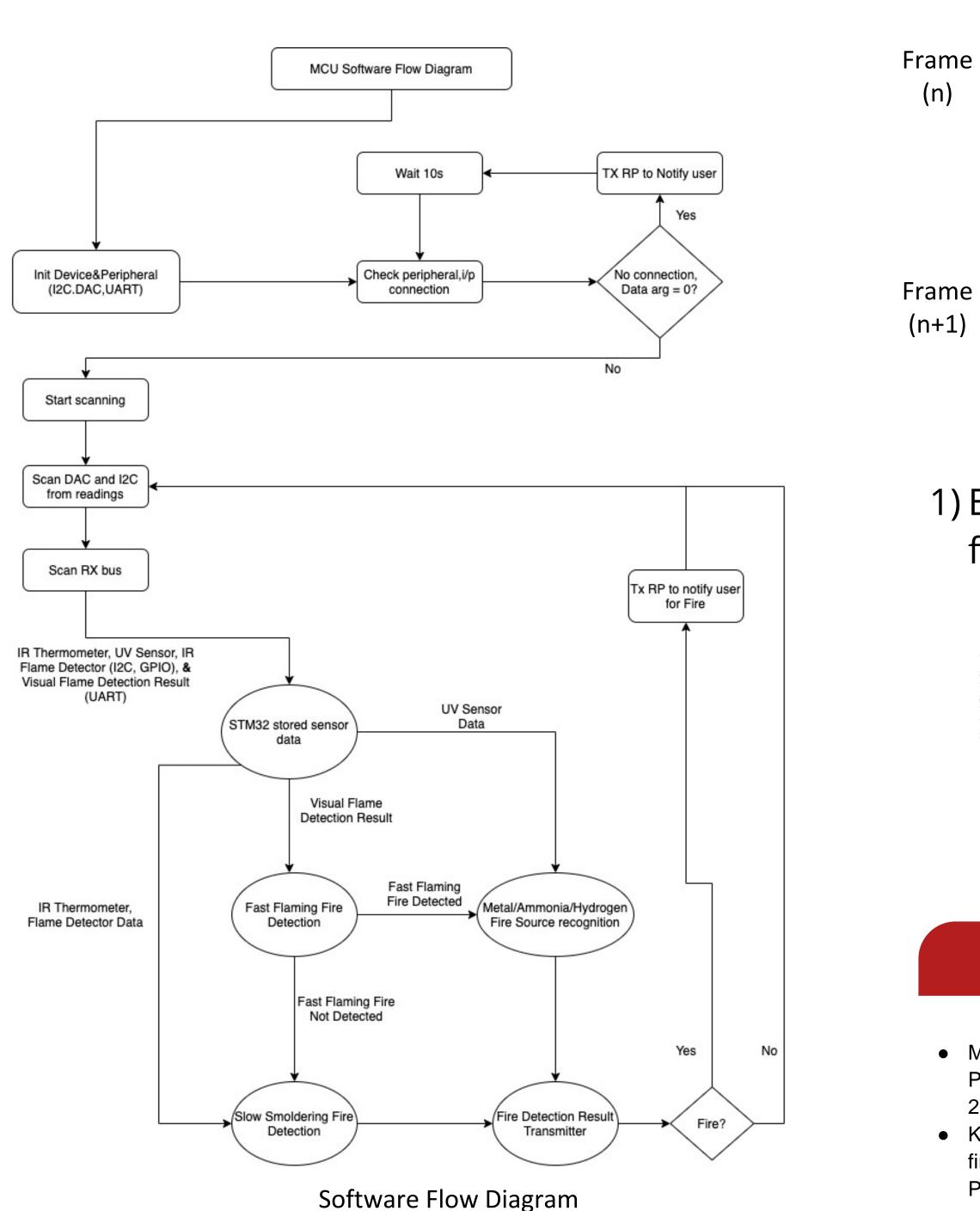
Functional and Software Diagrams



Functional Decomposition Diagram

| ometer: MLX90614 | | IR Flame Detector | |
|------------------|---------------|-------------------|----------------|
| | 4.5V - 5.5V | Voltage | 3.3V - 9V |
| | | Wavelength | 700nm - 1100nm |
| ture | -70C - 382.2C | | |
| | 4.05 | Distance | 0.70m - 1.20m |
| 0 | 1.25 | | |
| | I2C | Signal | Analog/Digital |

| UV Sensor: GUVA-S12SD | | |
|-----------------------|---------------|--|
| Voltage | 3.3V - 5V | |
| Wavelength | 200nm - 370nm | |
| Signal | Analog | |



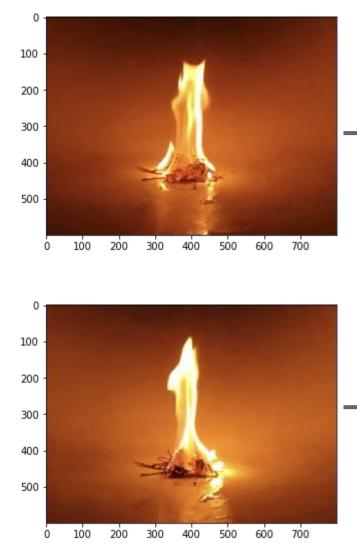
We implement the visual fire detection algorithm by Processing RGB pixel images to identify points of intensities and motion. This approach utilizes the YUV spectrum of an image to determine intensities, and threshold them to eliminate noise. We may, then, measure the motion in frame to evaluate the difference between different bright objects and distinguish fire. This can be summarized into two main steps:

1) Process two consecutive frames (n and n+1) into intencity points:

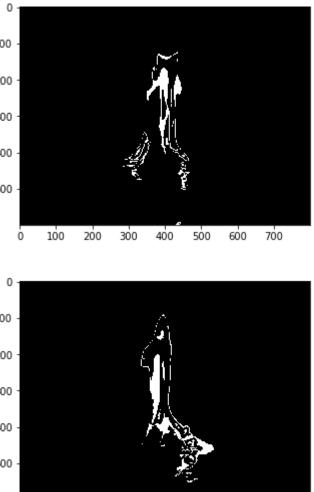
Acknowledgements

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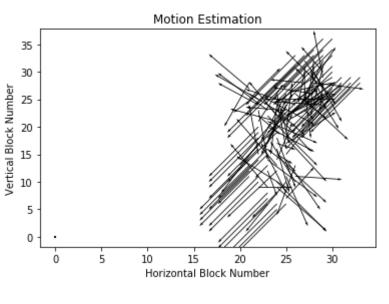
Visual Fire Detection



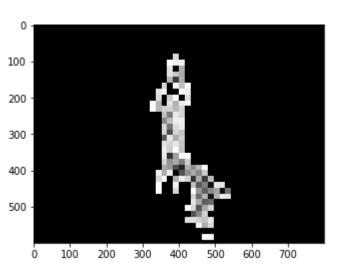
0 100 200 300 400 500 600



frames:



1) Estimate motion between both processed



References

• Mahmoud, M. A. I., & Ren, H. (2018). Forest Fire Detection Using a Rule-Based Image Processing Algorithm and Temporal Variation. Mathematical Problems in Engineering, 2018, 1–8. doi: 10.1155/2018/7612487

• Kalpana, Y., & Padmaa, M. (2014). An efficient edge detection algorithm for flame and fire image processing. 2014 International Conference on Communication and Signal Processing. doi: 10.1109/iccsp.2014.6949932