

DENSE ACTIVE SYSTEMS : activity and crowding

- Recall Lisa's confluent cell layers
- Show penguin movie

Today's lecture : activity and exclude volume / steric effects

First → SP dynamics vs Brownian dynamics

Overdamped Brownian particle ($d=2$)

$$\frac{d\vec{r}}{dt} = \vec{v} = \vec{\eta}(t)$$

$$\langle \vec{\eta}(t) \rangle = 0$$

$$\langle [\Delta \vec{r}(t)]^2 \rangle = 4Dt$$

$$\langle \eta_\alpha(t) \eta_\beta(t') \rangle = 2D \delta_{\alpha\beta} \delta(t-t')$$

$$D = k_B T / \zeta$$

SPP

- active colloids
- cells on substrate

Fily & MCM PRL 108 235702 (2012)

Fily, Henkes, MCM Soft Matter 10, 2132 (2014)

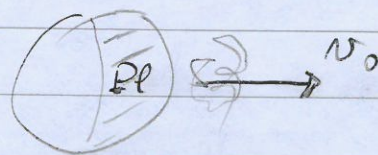
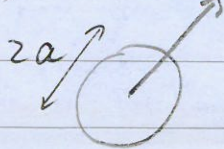
→ Palacci's low density movie + high density

Agusman Sen 2005

$$\frac{d\vec{r}}{dt} = v_0 \hat{e} + \vec{\eta}(t)$$

$$\hat{e} = (\cos\theta, \sin\theta)$$

$$\frac{d\theta}{dt} = \eta_R(t)$$



$$v_0 \sim 1-15 \mu\text{m/s}$$

from different rates of H_2O_2 consumption on two sides

$$\langle \eta_R(t) \rangle = 0$$

$$\langle \eta_R(t) \eta_R(t') \rangle = 2D_r \delta(t-t')$$

$$[D] = [\text{m}^2 \text{s}^{-1}]$$

$$[D_r] = [\text{s}^{-1}]$$

equilibrium : noise $\sim kT$

$$D \sim a^2 D_r$$

HW : calculate MSD

$$\langle [\Delta \vec{r}(t)]^2 \rangle = 4Dt + \frac{2v_0}{D_r} \left[t - \frac{1 - e^{-D_r t}}{D_r} \right]$$

$$t \ll D_r^{-1} \quad \sim v_0^2 t^2$$

$$t \gg D_r^{-1} \quad \sim \frac{v_0^2}{D_r} t$$

$$t \gg D_r^{-1}$$

$$\langle [\Delta \vec{r}(t)]^2 \rangle \approx 4 \left[D + \frac{v_0^2}{2D_r} \right] t$$

persistence length

$$l_p = v_0 / D_r$$

How does this compare to
run-and-tumble? (E. coli)

$$\frac{v_0^2}{2D_r} \sim l_p^2 D_r$$

continuous diffusion
at rate D_r

VS

discrete tumble events
mean-time between tumbles
exponentially distributed
tumble rate α

$$D_{sp} \sim \frac{v_0^2}{d(d-1)D_r}$$

$$(d-1)D_r \rightarrow \alpha$$

$$D_{sp} \sim v_0^2 / d\alpha$$

$$D_{sp} = \frac{v_0^2}{d[\alpha + (d-1)D_r]}$$

(some E. coli mutants
do not tumble)

Differences disappear upon coarse graining.

Apparent only when there is a small-scale structure
in the problem, e.g., traps of size ^{large} comparable to
run length: ABP trapped at walls.

Some numbers

$$D = \frac{k_B T}{6\pi\eta a}$$

$$k_B T \sim 1.38 \times 10^{-23} \frac{\text{J}}{\text{K}} \quad 300 \text{K} \sim 5 \times 10^{-21} \text{J}$$

$$\eta_{\text{H}_2\text{O}} \sim 10^{-3} \text{Pa s}$$

$$a \sim \mu\text{m} \sim 10^{-6} \text{m}$$

$$D \sim 0.2 \times 10^{-12} \text{m}^2/\text{s}$$

$$\sim 0.2 \mu\text{m}^2/\text{s}$$

$$D_{sp} \sim v_0^2 / D_r$$

$$v_0 \sim 10 \mu\text{m}/\text{s}$$

$$D_r \sim 10^{-3} - 10^{-4} \text{s}^{-1}$$

$$D_{sp} \sim 10^2 \mu\text{m}^2/\text{s}$$

$$\alpha \sim 1 \text{s}^{-1}$$

$$D_{sp} \gg D$$

We can neglect translational noise

Both systems:

- particles do not exert torques on each other nor on a surrounding solvent.

The angular dynamics of each particle is unaffected by that of the others or by interactions

Key simplification

Peclet number

$$Pe = v_0 / a D_r = \ell_p / a$$

Effective temperature

tempting, but...

$$\left. \begin{aligned} \frac{d\vec{r}}{dt} &= \dot{\epsilon}(t) v_0 \\ \frac{d\theta}{dt} &= \gamma_R(t) \end{aligned} \right\}$$

$$\frac{d\vec{r}}{dt} = \vec{\xi}_{\text{eff}}(t)$$

$$\langle \xi_{\alpha}(t) \xi_{\beta}(t') \rangle = v_0^2 e^{-D_R |t-t'|}$$

Non-Markovian noise

$$\rightarrow \frac{v_0^2}{D_R} \delta(t-t') \quad D_R \rightarrow \infty$$

$$k_B T_{\text{eff}} = \frac{v_0^2}{2\mu D_R}$$

$$\boxed{P_{\text{ideal}} = \rho k_B T_{\text{eff}}} \quad [D_R] = t^{-1} \\ [M] = [m^{-1} t^{-1}]$$

skip

Equilibrium: linear response $R = \left(\frac{\partial \langle v \rangle}{\partial f} \right)_{f=0} = \mu = \frac{1}{\zeta}$

$$\text{FD: } \frac{C}{R} = k_B T$$

$$\text{correlation function } C = D = \int_0^\infty dt \langle \vec{v}(t) \cdot \vec{v}(0) \rangle$$

Glassy systems: $\frac{C}{R} = k_B T_{\text{eff}}$ a useful concept
sometimes $T_{\text{eff}}(\omega)$

Here:

- Single active particle in an external force, e.g.,
~~confining potential~~ V_{ext} : equilibrium notion effective only if

$$D V_{\text{ext}} \ll F_{\text{SP}} = v_0 / \zeta$$

or characteristic length set by balance of external
and SP force $\sim V_{\text{ext}} \zeta / v_0 \gg l_p$

••

Most striking phenomenon $\rightarrow$ MIPS = motility-induced
phase separation

many particles

$$1/D_R \ll \tau_{\text{coll}} \sim 1/2\alpha v_0 \rho$$

Interacting SPP : only repulsion

$$\frac{d\vec{r}_i}{dt} = v_0 \hat{e}_{\theta_i} + \mu \sum_j \vec{f}_{ij}$$

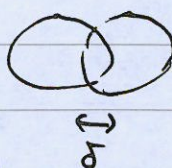
$$\frac{d\theta_i}{dt} = \eta_{r_i}(t)$$

Repulsive forces :

• soft $\vec{f}_{ij} = -\delta K \hat{r}_{ij}$

• hard spheres

• WCA, LJ, ...



$$2d + 3d$$

Time scales

$$1/D_r$$

$$a/v_0$$

$$1/\mu K$$

$$\tau_c = 1/2 a v_0 \rho$$

$$v_0/a \gg \mu K \text{ pass through}$$

$$v_0/a \mu K \rightarrow 0 \text{ athermal packing}$$

$$D_r \rightarrow \infty \text{ thermal}$$

Phase separation with no attraction $\rightarrow$ MIPS motility-induced

$\rightarrow$ movies : • our simulations
• Palacci clusters

phase separation if $\tau_r > \tau_c$

$$Pe \gg 1$$

MIPS :

- mean speed of particles along propulsion direction decreases with increasing density ($\neq$ equipartition)
- particles accumulate where they move slowly (not possible in equilibrium systems because speed distribution does not depend on position)

$$v_0 \rightarrow v(\rho) \approx v_0(1 - \lambda \rho) \quad \text{numerical fits to MSD}$$

Schnitzer, PRE 48, 2553 (1993)

1d run-and-tumble w/ spatially varying speed

 $V(x)$ speed of run α tumble rate $R(x)/L(x)$ = density of right/left moving particles

$$\begin{cases} \dot{R} = -\partial_x (vR) - \frac{\alpha}{2} R + \frac{\alpha}{2} L \\ \dot{L} = \partial_x (vR) + \frac{\alpha}{2} R - \frac{\alpha}{2} L \end{cases}$$

factor of $1/2$ because $1/2$ of tumbles are $R \rightarrow R$ or $L \rightarrow L$

direction switches at

rate $\alpha/2$ $\rho = R + L$ = density $\sigma = R - L$ = polarization $J = v\sigma$ = current

$$\begin{cases} \partial_t \rho = -\partial_x J & \text{conserved} \end{cases}$$

$$\begin{cases} \partial_t \sigma = -\partial_x (v\rho) - \alpha\sigma & \text{relaxational} \end{cases}$$

time $\gg 1/\alpha$

$$\sigma \approx -\frac{1}{\alpha} \partial_x (v\rho)$$

"adiabatic"

approximation

$$\partial_t \rho = -\partial_x \left[-\frac{v}{\alpha} \partial_x v \rho \right]$$

$$\partial_t \rho = -\partial_x \left[\underbrace{-\frac{v^2}{\alpha} \partial_x \rho + \frac{vv'}{\alpha} \rho}_{\text{current}} \right]$$

cf convection - diffusion

current

$$J = v\rho - D\partial_x \rho$$

~~$$\partial_t \rho = -\partial_x \left[v(x)\rho \right] + \partial_x \left[D(x)\partial_x \rho \right]$$~~

$$D(x) = v^2(x)/\alpha$$

$$V(x) = - \frac{v(x)v'(x)}{\alpha}$$

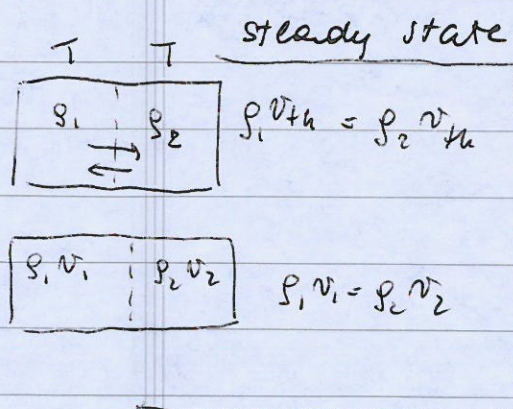
drift towards regions
of smaller v (- sign)

• $v(x) = \text{constant}$

$$\partial_t \rho = D \partial_x^2 \rho$$

only stationary solution is $\rho = \rho_0$

• $v(x) \neq \text{constant}$



$$J(x) \equiv \text{const} = 0 \quad \text{no flux}$$

$$\frac{1}{\rho} \partial_x \rho = - \frac{1}{v} \partial_x v$$

$$\left\{ \rho(x) = \rho_0 \frac{v(0)}{v(x)} \right\}$$

This result depends critically on having an upper bound for speed, as opposed to a speed distribution (e.g. M-B) that allows (even if with small probability) arbitrarily large speeds.

Many interacting particles

$$v \rightarrow v(\rho)$$

$$\rho \sim \frac{1}{v(\rho)}$$

feedback yields
phase separation

Continuum Model

ρ conserved

$\vec{p}$ no phase transition

Non interacting particles

$$\frac{d\vec{r}_i}{dt} = v_0 \hat{e}_i + \vec{\eta}_i(t)$$

$$\frac{d\theta_i}{dt} = \eta_i(t)$$

$$\partial_t \psi(r, \theta, t) = - \vec{\nabla} [v_0 \hat{e}_\psi - D \vec{\nabla} \psi] + D_r \partial_\theta^2 \psi$$

$$\partial_t \rho = - \vec{\nabla} \cdot [v_0 \rho \vec{p} - D \vec{\nabla} \rho]$$

$$\partial_t \vec{p} = - D_r \vec{p} - \frac{v_0}{2} \vec{\nabla} \rho + \kappa (\nabla^2 \vec{p})$$

interactions here are repulsive steric effect.

do not yield alignment, but reduce motility

$$v_0 \rightarrow v(\rho) = v_0 (1 - \lambda \rho)$$

λ depends on pair correlation function

higher probability of finding particles ahead of you than behind

Clustering of inelastic systems arise from combining the dynamics of a conserved field (density) with non-conserving noise. This gives $S(k) \sim 1/k^2$, like GNF in ordered state

$$\partial_t \rho = - \vec{\nabla} \cdot [v(\rho) \rho \vec{p}] + D \nabla^2 \rho$$

$$\partial_t \vec{p} = -D_r \vec{p} - \frac{1}{2} \vec{\nabla} [\rho v(\rho)] + O(\nabla^2)$$

$$t \gg 1/D_r$$

$$\vec{p} \approx - \frac{1}{2D_r} \vec{\nabla} [\rho v(\rho)]$$

quasi-thermal limit

$$\partial_t \rho = \vec{\nabla} \cdot \mathcal{D}(\rho) \vec{\nabla} \rho$$

$$\mathcal{D}(\rho) = D + \frac{v^2(\rho)}{2D_r} + \frac{v \rho v'}{2D_r}$$

$$v(\rho) = v_0(1 - \lambda \rho)$$

minimum Pe required for phase separation

$$D_{eff} = D + \frac{v_0^2}{2D_r} (1 - \lambda \rho)(1 - 2\lambda \rho)$$

$D_{eff} < 0$ spinodal phase separation

Kinetic estimate of λ

$$\tau_c \sim (2a n_0 \rho)^{-1} \quad \text{mean free time}$$

$$v(\rho) \sim v_0 (1 - \tau/\tau_c)$$

τ ~ mean delay caused by collisions

- $\tau_1 \sim a/v_0$ escape by traveling a while maintaining orientation
- $\tau_2 \sim 1/D_r$ must rotate to escape

$$\frac{1}{\tau} = \frac{1}{\tau_1} + \frac{1}{\tau_2} \quad \text{faster mechanisms wins (back)}$$

Finite D_r: retain dynamics of $\vec{p}$ and examine stability of homogeneous state $\rho = \rho_0, \vec{p} = 0$ by letting $\rho = \rho_0 + \delta\rho$

$$\vec{p} = \delta\vec{p}$$

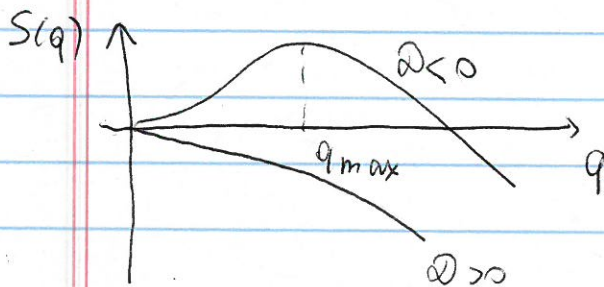
$$\delta\rho(\vec{r}, t), \delta\vec{p}(\vec{r}, t) \sim e^{s(q)t + i\vec{q} \cdot \vec{r}}$$

$$(\partial_t + Dq^2) \delta\rho + i v(\rho_0) \vec{q} \cdot \vec{p} = 0$$

$$(\partial_t + D_r \overset{+kq^2}{q^2}) \delta\vec{p} + \frac{1}{2} (v + \rho_0 v') i \vec{q} \delta\rho = 0$$

small q : mode

$$s(q) = -q^2 D(\rho_0) + q^4 B$$



$$q_{\max} \sim \sqrt{\frac{-D}{2kB}}$$

This result can also be interpreted in the context of a Landau-type HFT (ignoring gradient terms, i.e., $v(\rho(r))$ is local).

In fact one can map ^{repulsive} SPP with $v(\rho)$ onto a Landau-like HFT of a system of attractive particles undergoing liquid gas phase separation.

Pressure

- force/area on walls of container
- thermodynamics: $p = - \left(\frac{\partial F}{\partial V} \right)_N \Rightarrow$ eqn. of state
- hydrodynamics: $p = \rho kT + \frac{1}{6V} \left\langle \sum_{i \neq j} \vec{r}_{ij} \cdot \vec{F}_{ij} \right\rangle$
or virial

trace of stress tensor

Ideal gas of SP particles:

or $\frac{1}{3V} \left\langle \sum_i \vec{r}_i \cdot \vec{f}_i \right\rangle$
virial

$$\sum \dot{\vec{r}}_i = \sum v_0 \hat{e}_i$$

$$\dot{\theta}_i = \eta_i(t) \rightarrow \text{SP force } \vec{f}_i^{\text{SP}}$$

$$P_{\text{act/swim}} = \frac{1}{2A} \left\langle \sum_i \vec{r}_i \cdot \vec{f}_i^{\text{SP}} \right\rangle$$

$$= \frac{1}{2A} \int_{-\infty}^t dt' \left\langle v_0 \hat{e}_i(t') \cdot \sum v_0 \hat{e}_i(t) \right\rangle$$

$$P_{\text{act/swim}} = \frac{\rho v_0^2}{2\mu D_r} (1 - e^{-D_r t}) \xrightarrow{t \rightarrow \infty} \frac{\rho v_0^2}{2\mu D_r} = \rho kT_{\text{eff}}$$

in a container

$$t \sim L/v_0$$

$$P_{\text{swim}}(t \sim L/v_0) \sim \begin{cases} \rho kT_{\text{eff}} & \text{if } L \gg l_p \\ \frac{\rho v_0 L}{2\mu} & L \ll l_p \end{cases}$$

Detailed calculations have shown

$$P_{\text{swire}} = \frac{g v_0 v(g)}{2\mu D_r}$$