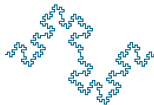


Generative Modeling by Minimizing the Wasserstein-2 Loss

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UNSUPERVISED LEARNING

- ▶ $\mathcal{P}(\mathbb{R}^d)$: the set of probability measures on $\mathbb{R}^d$.
- ▶ $\mu_d \in \mathcal{P}(\mathbb{R}^d)$: the (unknown) data distribution.
- ▶ **Unsupervised Learning:**

$$\min_{\mu \in \mathcal{P}(\mathbb{R}^d)} d(\mu, \mu_d),$$

where $d(\cdot, \cdot)$ is a metric on $\mathcal{P}(\mathbb{R}^d)$.

- ▶ **Traditional method (Statistics):** Parametrize μ_d .
 - ▶ Parameter fitting by maximum likelihood estimations.
 - ▶ What do we get? A formula of μ_d .
- ▶ **Generative modeling:**
 - ▶ What do we get? A random variable X whose law is μ_d .
 - ▶ Usually, $X = G(Z)$, where
 - ▶ Z is a simple r.v. (e.g., Gaussian);
 - ▶ G is a complicated function (process) to be learned.
 - ▶ How to learn G ?
 - ▶ Generative adversarial network, GAN
(a min-max game between *generator* & *discriminator*.)
 - ▶ Diffusion probabilistic model
(forward SDE to add noise, reverse-time SDE to denoise).
 - ▶

► In this talk,

$$\min_{\mu \in \mathcal{P}_2(\mathbb{R}^d)} W_2^2(\mu, \mu_d) \quad (1)$$

- $\mathcal{P}_2(\mathbb{R}^d) := \{\mu \in \mathcal{P}(\mathbb{R}^d) : \int_{\mathbb{R}^d} |y|^2 d\mu(y) < \infty\}.$
- Second-order Wasserstein distance: for any $\mu, \nu \in \mathcal{P}_2(\mathbb{R}^d),$

$$W_2(\mu, \nu) := \inf_{\gamma \in \Gamma(\mu, \nu)} \left(\int_{\mathbb{R}^d \times \mathbb{R}^d} |x - y|^2 d\gamma(x, y) \right)^{1/2} \quad (2)$$

$$= \sup_{\phi \in L^1(\mathbb{R}^d, \mu), (\phi^c)^c = \phi} \left\{ \int_{\mathbb{R}^d} \phi(x) d\mu(x) + \int_{\mathbb{R}^d} \phi^c(y) d\nu(y) \right\} \quad (3)$$

- $\Gamma(\mu, \nu)$: the set of $\gamma \in \mathcal{P}(\mathbb{R}^d \times \mathbb{R}^d)$ with marginals μ and ν .
- $\phi^c(y) := \inf_{x \in \mathbb{R}^d} \{\frac{1}{2}|x - y|^2 - \phi(x)\}, y \in \mathbb{R}^d$ [c -transform of ϕ]
- **Optimizers exist!**
 - $\Gamma_0(\mu, \nu)$: the set of $\gamma \in \Gamma(\mu, \nu)$ that minimizes (2)
 - Kantorovich potential ϕ_μ^ν : a maximizer of (3).

- ▶ Why take W_2^2 in (1) (instead of W_2)?
 - ▶ $\mu \mapsto W_2^2(\mu, \mu_d)$ is strictly convex on $\mathcal{P}_2(\mathbb{R}^d)$.
- ▶ Recall: For a strictly convex $f : \mathbb{R}^d \rightarrow \mathbb{R}$,
 - ▶ **gradient descent** works efficiently.
 - ▶ For any $y \in \mathbb{R}^d$, the ODE

$$dY_t = -\nabla f(Y_t)dt, \quad Y_0 = y \in \mathbb{R}^d, \quad (4)$$

converges to global minimizer $y^* \in \mathbb{R}^d$ as $t \rightarrow \infty$.

- ▶ Question: For the strictly convex

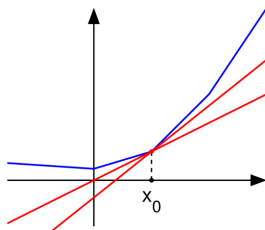
$$J(\cdot) := \frac{1}{2}W_2^2(\cdot, \mu_d) : \mathcal{P}_2(\mathbb{R}^d) \rightarrow \mathbb{R}, \quad (5)$$

can we also do **gradient descent** to find $\mu_d \in \mathcal{P}_2(\mathbb{R}^d)$?

SUBDIFFERENTIAL CALCULUS

- For a convex $f : \mathbb{R}^d \rightarrow \mathbb{R}$,
 - $\xi \in \mathbb{R}^d$ is called a **subgradient** of f at $x_0 \in \mathbb{R}^d$ if

$$f(y) \geq f(x_0) + \xi \cdot (y - x_0) \quad \forall y \in \mathbb{R}^d.$$



- The **subdifferential** of f at $x_0 \in \mathbb{R}^d$ (written $\partial f(x_0)$):
the set of all such $\xi \in \mathbb{R}^d$

Consider a convex $G : \mathcal{P}_2(\mathbb{R}^d) \rightarrow \mathbb{R}$.

Definition

$\xi : \mathbb{R}^d \rightarrow \mathbb{R}^d$ is called a **subgradient** of G at $\mu \in \mathcal{P}_2(\mathbb{R}^d)$ if $\xi \in L^2(\mathbb{R}^d, \mu)$ and

$$G(\nu) \geq G(\mu) + \inf_{\gamma \in \Gamma_0(\mu, \nu)} \int_{\mathbb{R}^d} \xi(x) \cdot (y - x) d\gamma(x, y) + o(W_2(\mu, \nu)), \quad \forall \nu \in \mathcal{P}_2(\mathbb{R}^d).$$

- The **subdifferential** of G at $\mu \in \mathcal{P}_2(\mathbb{R}^d)$ (written $\partial G(\mu)$): the set of all such $\xi \in \mathbb{R}^d \rightarrow \mathbb{R}^d$.

For $J(\cdot) := \frac{1}{2}W_2^2(\cdot, \mu_d) : \mathcal{P}_2(\mathbb{R}^d) \rightarrow \mathbb{R}$,

- **Gradient descent** in $\mathcal{P}_2(\mathbb{R}^d)$:

$$\frac{dY_t}{dt} \in -\partial J(\mu^{Y_t}), \quad \rho^{Y_0} = \mu_0 \in \mathcal{P}_2(\mathbb{R}^d). \quad (6)$$

- μ^{Y_t} : the law of r.v. Y_t .
- AMBROSIO ET AL. (2008): $\xi \in \partial J(\mu)$ generally exists, but...
not unique and no explicit construction.
- **Special case**: if $\mu \ll \mathcal{L}^d$, $\partial J(\mu) = \{\nabla \phi_\mu^{\mu_d}\}$ is a singleton!

- **Assuming** $\mu^{Y_t} \ll \mathcal{L}^d$ for all $t \geq 0$, (6) becomes

$$dY_t = -\nabla \phi_{\mu^{Y_t}}^{\mu_d}(Y_t)dt, \quad \mu^{Y_0} = \mu_0 \in \mathcal{P}_2^r(\mathbb{R}^d),$$

where $\mathcal{P}_2^r(\mathbb{R}^d) := \{\mu \in \mathcal{P}_2(\mathbb{R}^d) : \mu \ll \mathcal{L}^d\}$.

Our **gradient-descent** ODE:

$$dY_t = -\nabla \phi_{\mu^{Y_t}}^{\mu_d}(Y_t) dt, \quad \mu^{Y_0} = \mu_0 \in \mathcal{P}_2^r(\mathbb{R}^d). \quad (7)$$

- ▶ This ODE is *distribution-dependent*.
 - ▶ Y_t is a random variable, whose law is $\mu^{Y_t} \in \mathcal{P}_2(\mathbb{R}^d)$.
 - ▶ “ $-\nabla \phi_{\mu^{Y_t}}^{\mu_d}(\cdot) : \mathbb{R}^d \rightarrow \mathbb{R}^d$ ” is a vector field at time t :
it dictates how each $y \in \mathbb{R}^d$, a sample of Y_t , moves forward.

Our Goal:

There exists a unique solution Y to ODE (7). Moreover,

$$W_2(\mu^{Y_t}, \mu_d) \rightarrow 0, \quad \text{as } t \rightarrow \infty.$$

- ▶ Challenge: How to find a solution Y to (7)?
 - ▶ The regularity of $(y, \mu) \mapsto \nabla \phi_{\mu}^{\mu_d}(y)$ is obscure
 $\implies$ results for McKean-Vlasov SDEs cannot be applied.
 - ▶ The solution Y needs to fulfill $\mu^{Y_t} \ll \mathcal{L}^d$ for all $t \geq 0$.

Our Strategy:

Don't work with ODE (7) directly.

Work with its **Fokker-Planck equation**.

If Y is a solution to ODE (7), $\mu_t := \mu^{Y_t} \in \mathcal{P}_2(\mathbb{R}^d)$ heuristically satisfies **(nonlinear) Fokker-Planck equation**

$$\partial_t \mu_t - \text{Div}(\nabla \phi_{\mu_t}^{\mu_d} \mu_t) = 0, \quad \mu_0 = \mu_0 \in \mathcal{P}_2^r(\mathbb{R}^d) \quad (8)$$

in the sense of distributions, i.e., $\forall \varphi \in C_c^\infty((0, \infty) \times \mathbb{R}^d)$,

$$\int_0^\infty \int_{\mathbb{R}^d} \left(\partial_t \varphi(t, x) - \nabla \phi_{\mu_t}^{\mu_d}(x) \cdot \nabla \varphi(t, x) \right) d\mu_t(x) dt = 0.$$

► **Our Plan:**

- 1) Find a solution $\{\mu_t\}_{t \geq 0}$ to (8) with $\mu_t \ll \mathcal{L}^d \forall t \geq 0$.
 - 2) Construct a solution Y to ODE (7) with $\mu^{Y_t} = \mu_t \forall t \geq 0$.
- This plan, introduced in BARBU & RÖCKNER (2020), was also used in HUANG & ZHANG (2023, JMLR).

OPTIMAL TRANSPORT MAP

- ▶ Given $f : \mathbb{R}^d \rightarrow \mathbb{R}^d$ and $\mu \in \mathcal{P}(\mathbb{R}^d)$, define $f_{\#}\mu \in \mathcal{P}(\mathbb{R}^d)$ by

$$f_{\#}\mu(B) := \mu(f^{-1}(B)), \quad \forall \text{ Borel } B \subseteq \mathbb{R}^d.$$

- ▶ Given $\mu, \nu \in \mathcal{P}_2(\mathbb{R}^d)$,
 - ▶ $t : \mathbb{R}^d \rightarrow \mathbb{R}^d$ is a *transport map* from μ to ν if $t_{\#}\mu = \nu$. Note

$$W_2(\mu, \nu) = \inf_{t: \mathbb{R}^d \rightarrow \mathbb{R}^d, t_{\#}\mu = \nu} \int_{\mathbb{R}^d} |x - t(x)|^2 d\mu(x).$$

- ▶ A transport map t_{μ}^{ν} is *optimal* if it attains the infimum.
- ▶ AMBROSIO ET AL. (2008): if $\mu \ll \mathcal{L}^d$ then

$$t_{\mu}^{\nu}(x) = x - \nabla \phi_{\mu}^{\nu}(x) = (i - \nabla \phi_{\mu}^{\nu})(x) \quad \text{for } \mu\text{-a.e. } x \in \mathbb{R}^d, \quad (9)$$

where $i : \mathbb{R}^d \rightarrow \mathbb{R}^d$ is the identity map.

CONSTANT-SPEED GEODESIC

Given $\mu_0 \in \mathcal{P}_2^r(\mathbb{R}^d)$ and $\mu_d \in \mathcal{P}_2(\mathbb{R}^d)$, define

$$\beta_s := \left((1-s)\mathbf{i} + st_{\mu_0}^{\mu_d} \right)_{\#} \mu_0 \in \mathcal{P}_2(\mathbb{R}^d), \quad s \in [0, 1]. \quad (10)$$

► $\beta_0 = \mathbf{i}_{\#} \mu_0 = \mu_0, \quad \beta_1 = t_{\mu_0}^{\mu_d}_{\#} \mu_0 = \mu_d.$

► THEOREM 7.2.2, AMBROSIO ET AL. (2008):

$\{\beta_s\}_{s \in [0,1]}$ is a **constant-speed geodesic**, i.e.,

$$W_2(\beta_{s_1}, \beta_{s_2}) = (s_2 - s_1)W_2(\mu_0, \mu_d), \quad \forall 0 \leq s_1 \leq s_2 \leq 1. \quad (11)$$

- $\beta_s \ll \mathcal{L}^d$ for all $s \in [0, 1)$.

Proof Sketch:

- For any $s \in (0, 1)$, by (10) and (9),

$$\begin{aligned}
 \beta_s &= (\mathbf{i} + s(\mathbf{t}_{\mu_0}^{\mu_d} - \mathbf{i}))_{\#} \mu_0 \\
 &= (\mathbf{i} - s \nabla \phi_{\mu_0}^{\mu_d})_{\#} \mu_0 \\
 &= (\nabla f_s)_{\#} \mu_0, \quad \text{with } f_s(x) := \frac{1}{2}|x|^2 - s\phi_{\mu_0}^{\mu_d}(x). \quad (12)
 \end{aligned}$$

- LEMMA 5.5.3, AMBROSIO ET AL. (2008):

$$\left\{ \begin{array}{l} \mu \ll \mathcal{L}^d \\ g : \mathbb{R}^d \rightarrow \mathbb{R} \text{ uniformly convex} \end{array} \right. \implies (\nabla g)_{\#} \mu \ll \mathcal{L}^d.$$

- Recall from (3) that $((\phi_{\mu_0}^{\mu_d})^c)^c = \phi_{\mu_0}^{\mu_d}$
- $$\implies f(x) := \frac{1}{2}|x|^2 - \phi_{\mu_0}^{\mu_d}(x) \text{ is convex}$$
- $$\implies f_s(x) = \frac{1}{2}|x|^2 - s\phi_{\mu_0}^{\mu_d}(x) \text{ is uniformly convex.}$$

CHANGE OF SPEED

Consider *time-changed* constant-speed geodesic

$$\mu_t^* = \beta_{1-e^{-t}} = (e^{-t}\mathbf{i} + (1 - e^{-t})\mathbf{t}_{\mu_0}^{\mu_d})_{\#} \mu_0, \quad t \in [0, \infty). \quad (13)$$

- ▶ $\mu_0^* = \beta_0 = \mu_0, \lim_{t \rightarrow \infty} \mu_t^* = \beta_1 = \mu_d.$
- ▶ $\mu_t^* \ll \mathcal{L}^d$ for all $t \geq 0$.
- ▶ $\mu^* \in AC^p((0, \infty); \mathcal{P}_2(\mathbb{R}^d))$ for all $p \geq 1$.
- ▶ **Exponential convergence to μ_d :**

$$W_2(\mu_t^*, \mu_d) = \underbrace{W_2(\beta_{1-e^{-t}}, \beta_1)}_{\text{blue wavy line}} = e^{-t} W_2(\mu_0, \mu_d), \quad t \geq 0. \quad (14)$$

Question: Does μ^* satisfy Fokker-Planck equation (8)?

- For any $\mu = \{\mu_t\}_{t \geq 0} \in AC_{\text{loc}}^2((0, \infty); \mathcal{P}_2(\mathbb{R}^d))$,

$$\begin{aligned} \left| \frac{d}{dt} J(\mu_t) \right| &= \lim_{h \rightarrow 0} \left| \frac{J(\mu_{t+h}) - J(\mu_t)}{h} \right| \\ &= \lim_{h \rightarrow 0} \left| \frac{J(\mu_{t+h}) - J(\mu_t)}{W_2(\mu_{t+h}, \mu_t)} \frac{W_2(\mu_{t+h}, \mu_t)}{h} \right| \\ &\leq \limsup_{\nu \rightarrow \mu_t} \left| \frac{J(\nu) - J(\mu_t)}{W_2(\nu, \mu_t)} \right| \lim_{h \rightarrow 0} \frac{W_2(\mu_{t+h}, \mu_t)}{h} := M(t) < \infty. \end{aligned}$$

- By (11)-(13), $\frac{d}{dt} J(\mu_t^*) = -M(t) \forall t \geq 0$. [steepest descent!!]

- Idea: (a) $\implies$ (b), where

(a) Steepest descent of $t \mapsto J(\mu_t^*)$

(b) μ_t^* evolves along “negative gradient of J at μ_t^* ”

[cf. THEOREM 11.1.3, AMBROSIO ET AL. (2008)]

- **Conclusion**: the vector field of μ^* is “ $-\nabla \phi_{\mu_t^*}^{\mu_d}$ ”.

Proposition

$\{\mu_t^*\}_{t \geq 0}$ in (13) is a solution to the **F-P equation** (8), i.e.,

$$\partial_t \mu_t^* - \text{Div}(\nabla \phi_{\mu_t^*}^{\mu_d} \mu_t^*) = 0, \quad \mu_0^* = \mu_0 \in \mathcal{P}_2^r(\mathbb{R}^d). \quad (15)$$

Moreover, for $\mathcal{L}^1$ -a.e. $t > 0$,

$$\|\nabla \phi_{\mu_t^*}^{\mu_d}\|_{L^2(\mathbb{R}^d, \mu_t^*)} = \lim_{s \rightarrow t} \frac{W_2(\mu_s^*, \mu_t^*)}{|s - t|} < \infty. \quad (16)$$

If μ is a solution to (8) s.t. $\mu \in AC_{\text{loc}}^2((0, \infty), \mathcal{P}_2(\mathbb{R}^d))$ and (16) holds, then

$$W_2(\mu_t, \mu_t^*) = 0, \quad \forall t \geq 0.$$

► **Note:** By (11), (16) becomes

$$\|\nabla \phi_{\mu_t^*}^{\mu_d}\|_{L^2(\mathbb{R}^d, \mu_t^*)} = e^{-t} W_2(\mu_0, \mu_d). \quad (17)$$

SOLVING ODE (7)

- Replace μ^{Y_t} in ODE (7) by μ_t^* in (13)

$$dY_t = -\nabla \phi_{\mu_t^*}^{\mu_d}(Y_t) dt, \quad \mu^{Y_0} = \mu_0 \in \mathcal{P}_2^r(\mathbb{R}^d). \quad (18)$$

- An ODE of standard form—*no* distribution dependence!
- Look for a solution Y to (18) such that

$$\mu^{Y_t} = \mu_t^* \quad \forall t \geq 0.$$

Consider an SDE

$$dX_t = b(t, X_t)dt + \sigma(t, X_t)dW_t. \quad (19)$$

Superposition Principle [TREVISAN (2016)]:

- If $\{\nu_t\}_{t \geq 0}$ is a solution to **Fokker-Planck eqn.** associated with (19) s.t.

$$\int_0^T \int_{\mathbb{R}^d} (|b(t, x)| + |\sigma \sigma^T(t, x)|) d\nu_t dt < \infty \quad T > 0, \quad (20)$$

there exists $\mathbb{P}$ on $(\Omega, \mathcal{F}) = (C([0, \infty); \mathbb{R}^d), \mathcal{B}(C([0, \infty); \mathbb{R}^d)))$ such that

- (i) $\mathbb{P}$ is a solution to local martingale problem for (19)
(i.e., $X_t(\omega) := \omega(t)$, $t \geq 0$, satisfies (19) under $\mathbb{P}$);
- (ii) $\mathbb{P} \circ (X_t)^{-1} = \nu_t$ for all $t \geq 0$.

To check condition (20) in our case,

$$\begin{aligned}
 \int_0^T \int_{\mathbb{R}^d} \left| \nabla \phi_{\mu_t^*}^{\mu_d}(y) \right| d\mu_t^*(y) dt &= \int_0^T \|\nabla \phi_{\mu_t^*}^{\mu_d}\|_{L^1(\mathbb{R}^d, \mu_t^*)} dt \\
 &\leq \int_0^T \|\nabla \phi_{\mu_t^*}^{\mu_d}\|_{L^2(\mathbb{R}^d, \mu_t^*)} dt \\
 &= \int_0^T e^{-t} W_2(\mu_0, \mu_d) dt < \infty \quad \forall T > 0,
 \end{aligned}$$

where the last equality follows from (17).

MAIN RESULTS

Theorem

There is a solution Y to ODE (7) s.t. $\mu^{Y_t} = \mu_t^*$ for all $t \geq 0$. Thus,

$$W_2(\mu^{Y_t}, \mu_d) = W_2(\mu_t^*, \mu_d) = e^{-t} W_2(\mu_0, \mu_d), \quad \forall t \geq 0.$$

- The last equality is due to (14).

Proposition

Let Y be a solution to ODE (7) s.t. $\mu_t := \mu^{Y_t} \in \mathcal{P}_2^r(\mathbb{R}^d)$ satisfies $\mu \in AC((0, \infty); \mathcal{P}_2(\mathbb{R}^d)) \cap AC_{\text{loc}}^2((0, \infty); \mathcal{P}_2(\mathbb{R}^d))$ and (16). Then,

$$W_2(\mu_t, \mu_t^*) = 0 \quad \forall t \geq 0.$$

FORWARD EULER SCHEME

Fix a time step $0 < \varepsilon < 1$. Let's discretize ODE

$$dY_t = -\nabla \phi_{\mu^{Y_t}}^{\mu_d}(Y_t) dt, \quad \mu^{Y_0} = \mu_0 \in \mathcal{P}_2^r(\mathbb{R}^d).$$

- Time 0: Simulate r.v. Y_0^ε following μ_0 , so that

$$\mu^{Y_0^\varepsilon} = \mu_{0,\varepsilon} := \mu_0 \in \mathcal{P}_2^r(\mathbb{R}^d)$$

- Time ε : Simulate r.v. $Y_1^\varepsilon := Y_0^\varepsilon - \varepsilon \nabla \phi_{\mu_0}^{\mu_d}(Y_0^\varepsilon)$, so that

$$\mu^{Y_1^\varepsilon} = \mu_{1,\varepsilon} := (\mathbf{i} - \varepsilon \nabla \phi_{\mu_0}^{\mu_d})_{\#} \mu_0.$$

- Time 2ε : Simulate r.v. $Y_2^\varepsilon := Y_1^\varepsilon - \varepsilon \nabla \phi_{\mu_{1,\varepsilon}}^{\mu_d}(Y_1^\varepsilon)$, so that

$$\mu^{Y_2^\varepsilon} = \mu_{2,\varepsilon} := (\mathbf{i} - \varepsilon \nabla \phi_{\mu_{1,\varepsilon}}^{\mu_d})_{\#} \mu_{1,\varepsilon}.$$

- That is, we simulate recursively the r.v.'s

$$Y_n^\varepsilon := Y_{n-1}^\varepsilon - \varepsilon \nabla \phi_{\mu_{n-1}, \varepsilon}^{\mu_d}(Y_{n-1}^\varepsilon) \quad n \in \mathbb{N},$$

which have the distributions

$$\mu^{Y_n^\varepsilon} = \mu_{n, \varepsilon} := (i - \varepsilon \nabla \phi_{\mu_{n-1}, \varepsilon}^{\mu_d})_{\#} \mu_{n-1, \varepsilon} \quad n \in \mathbb{N}.$$

- This yields flow of measures $\mu^\varepsilon : [0, \infty) \rightarrow \mathcal{P}_2(\mathbb{R}^d)$ given by

$$\mu_t^\varepsilon := \mu_{n, \varepsilon} \quad \text{if} \quad t \in [n\varepsilon, (n+1)\varepsilon), \quad \forall n \in \mathbb{N} \cup \{0\}.$$

Theorem

For any $t \in [0, \infty)$, $\lim_{\varepsilon \downarrow 0} W_2(\mu_t^\varepsilon, \mu_t^*) = 0$.

- Euler scheme does converge to **the right limit!**

SIMULATION OF ODE (7)

Now, we set out to simulate

$$dY_t = -\nabla \phi_{\mu^{Y_t}}^{\mu_d}(Y_t)dt, \quad \mu^{Y_0} = \mu_0 \in \mathcal{P}_2^r(\mathbb{R}^d).$$

Challenge: The dynamics involves *unknown* μ_d !

SIMULATION OF ODE (7)

1. Approximate Y_t by $G_\theta(Z)$

- ▶ Z is a simple r.v. (e.g., Gaussian), fixed over time.
- ▶ $G_\theta : \mathbb{R}^d \rightarrow \mathbb{R}^d$ is complicated and updated over time.

2. Substituting $\mu^{G_\theta(Z)}$ for μ^{Y_t} in ODE (7) $\implies$

$$dY_t = -\nabla \phi_{\mu^{G_\theta(Z)}}^{\mu_d}(Y_t) dt, \quad \mu^{Y_0} = \mu_0 \in \mathcal{P}_2^r(\mathbb{R}^d). \quad (21)$$

- ▶ With G_θ given (i.e., $G_\theta(Z)$ represents Y_t),
 - ▶ estimate $(\phi_{\mu^{G_\theta(Z)}}^{\mu_d}, (\phi_{\mu^{G_\theta(Z)}}^{\mu_d})^c)$ by two neural networks (ϕ_w, ψ_v) , following ALGORITHM 1, SEGUY ET AL. (2018).
- ▶ Once $\phi_{\mu^{G_\theta(Z)}}^{\mu_d}$ is known, move along ODE (21) to time $t + \varepsilon$.
- ▶ Update G_θ such that $G_\theta(Z)$ can suitably represent $Y_{t+\varepsilon}$.

Algorithm 1 W2-FE

- 1: **for** number of training iterations **do**
- 2: **for** number of updates **do**
- 3: • Sample $\{z_i\}_{i=1}^m$ from μ^Z , and $\{x_i\}_{i=1}^m$ from μ_d .
- 4: • $w \leftarrow w + \gamma_d \nabla_w L_D$ and $v \leftarrow v + \gamma_d \nabla_v L_D$, with

$$L_D = \frac{1}{m} \sum_{i=1}^m \left[\phi_w(G_\theta(z_i)) + \psi_v(x_i) - \lambda(\phi_w(G_\theta(z_i)) + \psi_v(x_i) - \|G_\theta(z_i) - x_i\|_2^2/2)_+ \right].$$

- 5: **end for**
 - 6: • Sample $\{z_i\}_{i=1}^m$ from μ^Z .
 - 7: • $y_i \leftarrow G_\theta(z_i)$ [Samples of Y_t]
 - 8: • $\zeta_i \leftarrow y_i - \varepsilon \nabla \phi_w(y_i)$ [Samples of $Y_{t+\varepsilon}$]
 - 9: **for** K generator updates **do**
 - 10: • $\theta \leftarrow \theta - \frac{\gamma_g}{m} \nabla_\theta \sum_{i=1}^m |\zeta_i - G_\theta(z_i)|^2$
 - 11: **end for**
 - 12: **end for**
-

PERSISTENT TRAINING

To update the “generator” G_θ ,

- ▶ Reduce **mean squared error** between $\{G_\theta(z_i)\}$ and $\{\zeta_i\}$.
 - ▶ Idea: Want $G_\theta(Z)$ to *learn* the distribution of $Y_{t+\epsilon}$.
- ▶ Do stochastic gradient descent (SGD) $K \in \mathbb{N}$ times *with same minibatch!*
 - ▶ $K = 1$: standard SGD.
 - ▶ $K > 1$: **persistent training** (FISCHETTI ET AL. (2018)).
 - ▶ *Conceptually*
—ideal for our differential equation approach.
 - ▶ *Numerically*
—speeds up training and achieves better results.

CONNECTIONS TO GANs

Generative adversarial networks (GANs) also solves

$$\min_{\mu \in \mathcal{P}(\mathbb{R}^d)} d(\mu, \mu_d),$$

by a min-max game (between *generator* and *discriminator*).

- ▶ GOODFELLOW ET AL. (2014) (**vanilla GAN**):
 - ▶ d = Jensen-Shannon divergence
 - ▶ highly unstable...
- ▶ ARJOVSKY ET AL. (2017) (**WGAN**):
 - ▶ d = Wasserstein-1 distance
 - ▶ Stable, one of the most popular GANs.
- ▶ LEYGONIE ET AL. (2019) (**W2GAN**):
 - ▶ d = Wasserstein-2 distance
 - ▶ Performs similarly to WGAN, receives little attention...

Proposition

Algorithm 1 (with $K = 1$) is equivalent to **W2GAN algorithm** (LEYGONIE ET AL. (2019)), up to adjustment of learning rates.

- This is because

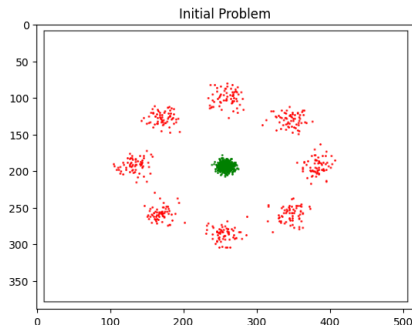
$$\begin{aligned}\nabla_{\theta} \frac{1}{m} \sum_{i=1}^m |G_{\theta}(z_i) - \zeta_i|^2 &= \frac{2}{m} \sum_{i=1}^m \underbrace{(G_{\theta}(z_i) - \zeta_i)} \cdot \nabla_{\theta} G_{\theta}(z_i) \\ &= \frac{2}{m} \sum_{i=1}^m \varepsilon \nabla \phi \left(\underbrace{G_{\theta}(z_i)} \right) \cdot \nabla_{\theta} G_{\theta}(z_i) \\ &= \varepsilon \nabla_{\theta} \frac{1}{m} \sum_{i=1}^m \phi(G_{\theta}(z_i))\end{aligned}$$

- Equivalence *fails* for $K > 1$!

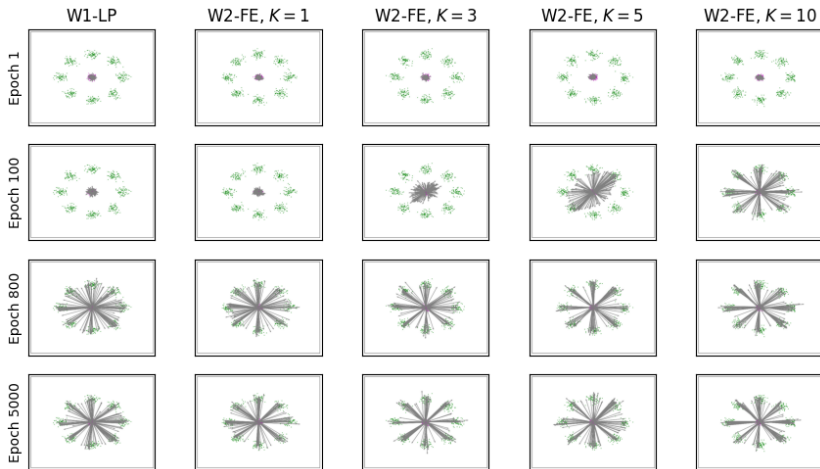
EXPERIMENT 1

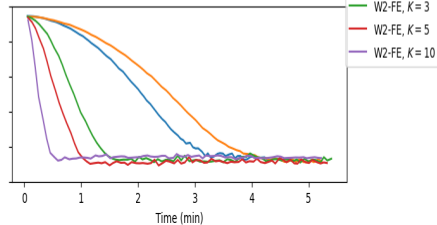
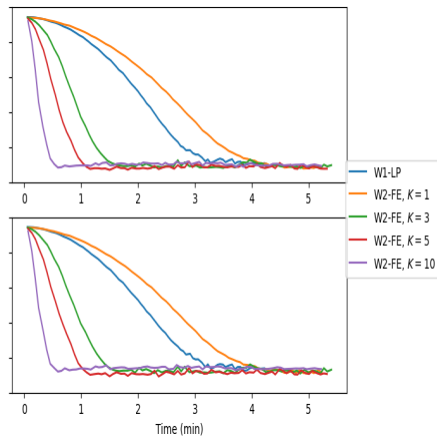
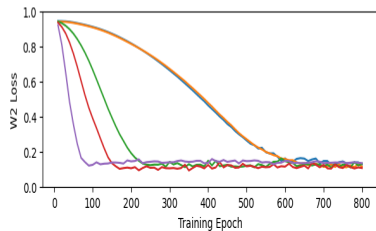
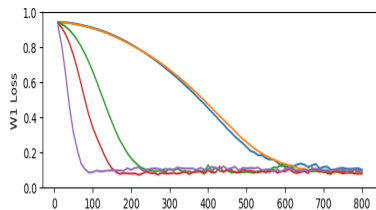
The Ring Example (METZ ET AL. (2017, ICLR)):

- ▶ **True data distribution:** 8 Gaussians arranged on a circle
- ▶ **Initial distribution:** 1 Gaussian at the center



- ▶ In the literature:
 - ▶ **(Vanilla) GAN:** Extreme mode collapse!!
 - ▶ **WGAN:** No obvious mode collapse, but low resolution
 - ▶ **Refined WGAN (W1-LP)** in PETZKA ET AL. (2018):
No mode collapse, high resolution.
- ▶ What we will do:
 - ▶ Implement **Algorithm 1 (W2-FE)** with varying K values.
 - ▶ Compare its performance with **W1-LP**.

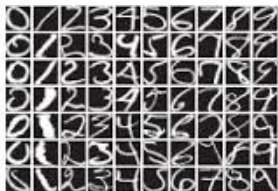




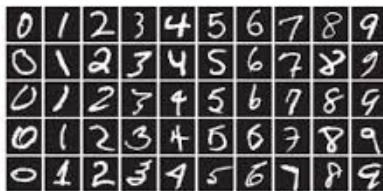
EXPERIMENT 2

Domain Adaptation

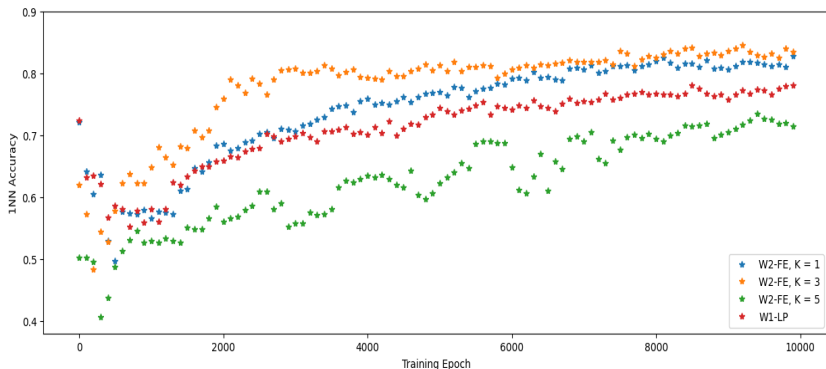
- ▶ **True data distribution:** MNIST dataset
- ▶ **Initial distribution:** USPS dataset



(a) USPS



(b) MNIST



- **Accuracy measure:** 1-nearest neighbor (1-NN) classifier.
 - evaluated every 100 epochs.
- Performance deteriorates at $K = 5$ (due to overfitting).

SUMMARY

- ▶ We solve the problem

$$\min_{\mu \in \mathcal{P}_2(\mathbb{R}^d)} W_2^2(\mu, \mu_d)$$

through a *distribution-dependent* ODE

$$dY_t = -\nabla \phi_{\mu^{Y_t}}^{\mu_d}(Y_t) dt, \quad \mu^{Y_0} = \mu_0 \in \mathcal{P}_2^r(\mathbb{R}^d).$$

- ▶ A **generative model** is built by simulating the ODE.
It combines:
 - ▶ A forward Euler scheme for the ODE,
 - ▶ *Persistent training* to learn μ^{Y_t} .
- ▶ Our algorithm outperforms typical Wasserstein GAN algorithms.

EXTENSION TO W_1

- Consider

$$\min_{\mu \in \mathcal{P}_1(\mathbb{R}^d)} W_1(\mu, \mu_d) \quad (22)$$

- $\mathcal{P}_1(\mathbb{R}^d) := \{\mu \in \mathcal{P}(\mathbb{R}^d) : \int_{\mathbb{R}^d} |y| d\mu(y) < \infty\}$.
► W_1 is the *first-order Wasserstein distance*

$$\begin{aligned} W_1(\mu, \nu) &:= \inf_{\gamma \in \Gamma(\mu, \nu)} \int_{\mathbb{R}^d \times \mathbb{R}^d} |x - y| d\gamma(x, y) \\ &= \sup_{\phi: \mathbb{R}^d \rightarrow \mathbb{R}, \|\phi\|_{Lips} \leq 1} \left(\int_{\mathbb{R}^d} \phi(x) d\mu(x) - \int_{\mathbb{R}^d} \phi(y) d\nu(y) \right). \end{aligned}$$

- Maximizer ϕ_μ^ν exists!
(also called *Kantorovich potential*).

EXTENSION TO W_1

- ▶ *Tempting* to solve (22) through

$$dY_t = -\nabla \phi_{\mu^{Y_t}}^{\mu_d}(Y_t)dt, \quad \mu^{Y_0} = \mu_0 \in \mathcal{P}_1^r(\mathbb{R}^d).$$

- ▶ **Challenges:**

- 1) “Gradient of $G : \mathcal{P}_1(\mathbb{R}^d) \rightarrow \mathbb{R}$ ” is not well-defined.

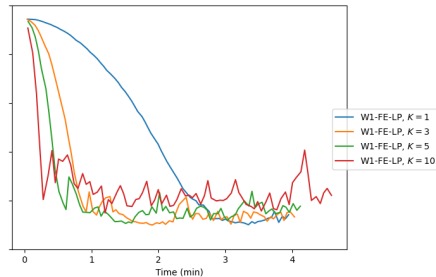
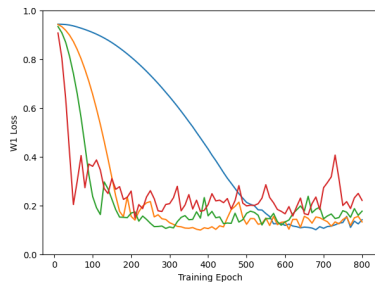
- ▶ Subdifferential calculus in AMBROSIO ET AL. (2008) excludes $\mathcal{P}_1(\mathbb{R}^d)$!
- ▶ MALIK & HUANG (2024) points to a possible way around....

- 2) In $\mathcal{P}_1(\mathbb{R}^d)$, $\mu_0 \ll \mathcal{L}^d \not\Rightarrow \mu^{Y_t} \ll \mathcal{L}^d$.

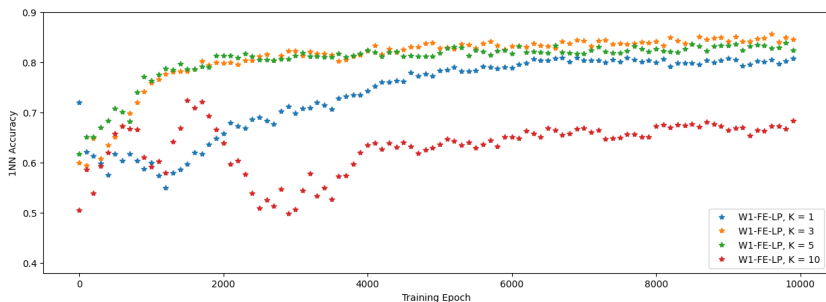
- ▶ Arguments below (12) no longer holds, by loss of convexity.

- ▶ Despite all this, can do numerical experiments first!

EXPERIMENT 1



EXPERIMENT 2



THANK YOU!!

Q & A

Preprint available

@ arXiv: 2406.13619

“Generative Modeling by Minimizing the Wasserstein-2 Loss”

@ arXiv: 2405.16351

“A Differential Equation Approach for Wasserstein GANs and Beyond”