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# A Time-Inconsistent Dynkin Game: Intra-personal v.s. Inter-personal Equilibria

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# OPTIMAL CONTROL/STOPPING

► Consider a Markovian state process *X*.

Stochastic Optimal Control/Stopping Given  $(t, x) \in [0, \infty) \times \mathbb{R}^d$ , can we solve

 $\sup_{\alpha \in \mathcal{A}} F(t, x, \alpha)?$ 

(1)

### Classical Theory:

- Want: find an optimal strategy  $\alpha_{t,x}^* \in \mathcal{A}$ .
- ► Methods: dynamic programming, martingale approach,...
- Consider  $\alpha_{t,x}^*$  as a mapping:

$$(t,x) \longrightarrow \alpha_{t,x}^* \in \mathcal{A}.$$



- Time Inconsistency:
  - $\alpha_{t,x}^*, \alpha_{s,X_s}^*, \alpha_{r,X_r}^*$  may all be different.
  - The original objective (1) cannot be attained...

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#### **Time-inconsistent objectives:**

► Non-exponential discounting:

$$F(t, x, \alpha) := \mathbb{E}_{t,x}[\delta(T - t)g(X_T^{\alpha})].$$

► Payoff depending on initials (*t*, *x*):

$$F(t, x, \alpha) := \mathbb{E}_{t,x}[g(t, x, X_T^{\alpha})].$$

• Nonlinear functionals of  $\mathbb{E}[\cdot]$ :

$$F(t, x, \alpha) := \mathbb{E}_{t,x}[g(X_T^{\alpha})] - H(\mathbb{E}_{t,x}[g(X_T^{\alpha})]).$$

### Probability distortion:

$$F(t, x, \alpha) := \int_0^\infty w \left( \mathbb{P}_{t, x} \left[ g(X_T^\alpha) > u \right] \right) du$$

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#### How to resolve time inconsistency?

Consistent Planning [Strotz (1955-56)]

Take into account future selves' behavior.
 Find an (*intra-personal*) equilibrium strategy that
 <u>once being enforced over time,</u>
 <u>no future self would want to deviate from.</u>

How to precisely define and characterize equilibria?
 For control problems,

- Ekeland & Lazrak (2006): Definition via spike variations.
- Ekeland & Pirvu (2008): Extended HJB system characterizes equilibrium controls  $\alpha^*$ .

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## LITERATURE

### Control problems:

Ekeland, Mbodji, & Pirvu (2012), Björk, Murgoci, & Zhou (2014), Dong & Sircar (2014), Björk & Murgoci (2014), Yong (2012), Björk, Khapko & Murgoci (2017), ...

### Stopping problems:

- (a) Extensions from "control" to "stopping"
  - ► Same *definition* and *extended HJB system* as in control case.
  - Christensen & Lindensjö (2018, 2020), Ebert et al. (2020).
- (b) The fixed-point approach
  - Equilibria as fixed-points, found via fixed-point iterations.
  - Huang & Nguyen-Huu (2018): non-exponential discounting; Huang, Nguyen-Huu, & Zhou (2020): probability distortion; Huang & Yu (2021): model uncertainty.



1. At first, one follows  $R \in \mathcal{B}(\mathbb{R}^d)$ .



3. Continue this procedure *until* we reach

 $R_0 := \lim_{n \to \infty} \Theta^n(R)$ 

**Expect:**  $\Theta(R_0) = R_0$ , i.e. cannot improve anymore.

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#### How about a game with "multiple agents"?

- Each agent has time-inconsistent preferences.
- ► <u>Two levels</u> of game-theoretic reasoning:

Each agent...

- 1. looks for an *intra-personal equilibrium* among her current and future selves;
- 2. finds the best response to other agents' strategies.
- An *inter-personal equilibrium* in the game is then

A **Nash equilibrium** among all agents, each of whom uses her *best* intra-personal equilibrium.

 Such *inter-personal equilibrium* have not been studied. (Precise definition? Existence? Construction?)

### IN THIS TALK...

#### Focus on a Dynkin game:

▶ 
$$\mathbb{Z}_+ := \{0, 1, 2, ...\}.$$

- ►  $X = (X_t)_{t \in \mathbb{Z}_+}$  time-homogeneous strong Markov, taking values in X.
- ► For  $i \in \{1, 2\}$ , given the other player uses  $\sigma \in \mathcal{T}$ , Player *i* maximizes

$$J_i(x,\tau,\sigma) := \mathbb{E}_x[F_i(\tau,\sigma)], \qquad (2)$$

over  $\tau \in \mathcal{T}$ , where

$$\begin{split} F_i(\tau,\sigma) &:= \delta_i(\tau) f_i(X_\tau) \mathbb{1}_{\{\tau < \sigma\}} + \delta_i(\sigma) g_i(X_\sigma) \mathbb{1}_{\{\tau > \sigma\}} \\ &+ \delta_i(\tau) h_i(X_\tau) \mathbb{1}_{\{\tau = \sigma\}}, \ \forall \tau, \sigma \in \mathcal{T}. \end{split}$$

*f<sub>i</sub>, g<sub>i</sub>, h<sub>i</sub>* : X → R<sub>+</sub> Borel measurable.
 *δ<sub>i</sub>* : R<sub>+</sub> → [0, 1] decreasing, *δ<sub>i</sub>*(0) = 1 (e.g. *δ<sub>i</sub>*(*t*) = *e<sup>-rt</sup>*).

# NON-EXPONENTIAL DISCOUNTING

**Assume** the discount function  $\delta_i : \mathbb{R}_+ \to [0, 1]$  satisfies

$$\delta_i(t)\delta_i(s) \le \delta_i(t+s) \quad \forall t, s \in \mathbb{Z}_+.$$
(3)

- ► Captures *decreasing impatience* in behavioral economics.
- ► Examples:
  - hyperbolic  $\delta_i(t) = \frac{1}{1+\beta t}$ ,
  - generalized hyperbolic  $\delta_i(t) = \frac{1}{(1+\beta t)^k}$ ,
  - pseudo-exponential  $\delta_i(t) = \lambda e^{-r_1 t} + (1 \lambda)e^{-r_2 t}$ .
- ► Time inconsistency arises under (3).



### STOPPING POLICIES

Assume each player stops at the first entrance time

 $\rho_S := \inf\{t \ge 0 : X_t \in S\}.$ 

- $S \in \mathcal{B}$ , a Borel subset of X, is called a *stopping policy*.
- Given the other player using  $T \in \mathcal{B}$ , Player *i*'s intra-personal reasoning

$$\Theta_i^T(S) := \{ x \in S : J_i(x, 0, \rho_T) \ge J_i(x, \rho_S^+, \rho_T) \}$$
$$\cup \{ x \notin S : J_i(x, 0, \rho_T) > J_i(x, \rho_S^+, \rho_T) \} \in \mathcal{B}.$$
(4)

• Stop at time 
$$0 \implies J_i(x, 0, \rho_T)$$
.

• Don't stop at time  $0 \implies J_i(x, \rho_S^+, \rho_T)$ , where

$$\rho_S^+ := \inf\{t > 0 : X_t \in S\}.$$

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### INTRA- AND INTER-PERSONAL EQUILIBRIA

Definition (Intra-personal)

 $S \in \mathcal{B}$  is Player *i*'s *intra-personal equilibrium* w.r.t.  $T \in \mathcal{B}$  if  $\Theta_i^T(S) = S$ .

We denote this by  $S \in \mathcal{E}_i^T$ .

Definition (*Soft* inter-personal)  $(S,T) \in \mathcal{B} \times \mathcal{B}$  is a <u>soft</u> inter-personal equilibrium if  $\Theta_1^T(S) = S$  and  $\Theta_2^S(T) = T$ . We denote this by  $(S,T) \in \mathcal{E}$ .



Given  $T \in \mathcal{B}$ , define the value function of  $S \in \mathcal{E}_i^T$  by

 $U_i^T(x,S) := J_i(x,0,\rho_T) \lor J_i(x,\rho_S^+,\rho_T), \quad x \in \mathbb{X}.$ 

Definition (*Optimal* Intra-personal)  $S \in \mathcal{E}_i^T$  is Player *i*'s <u>optimal</u> intra-personal equilibrium w.r.t.  $T \in \mathcal{B}$ if, for any  $R \in \mathcal{E}_i^T$ ,  $U_i^T(x, S) \ge U_i^T(x, R) \quad \forall x \in \mathbb{X}$ . We denote this by  $S \in \widehat{\mathcal{E}}_i^T$ .

- "Optimal equilibrium" of Huang & Zhou (2019):
  - Wants an equilibrium to be uniformly dominating —a rare occurrence in game theory.
  - For stopping under (3), optimal equilibrium exists. (Huang & Zhou (2019, 2020), Huang & Wang (2021))

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# Definition (*Sharp* inter-personal) $(S,T) \in \mathcal{B} \times \mathcal{B}$ is a <u>sharp</u> inter-personal equilibrium if $S \in \widehat{\mathcal{E}}_1^T$ and $T \in \widehat{\mathcal{E}}_2^S$ . We denote this by $(S,T) \in \widehat{\mathcal{E}}$ .

#### **Ultimate goals:**

- Existence of *sharp* inter-personal equilibria.
- Construction via concrete *iterative procedures*.

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#### First Question: What type of iterations to use?

► Fixed-point iteration, i.e.

$$\lim_{n \to \infty} (\Theta_i^T)^n (S) \in \mathcal{E}_i^T$$

does not seem so promising ...

- Any iteration that <u>directly leads to</u>  $S^* \in \widehat{\mathcal{E}}_i^T$ ?
  - Recently approached by <u>Bayraktar, Zhang, & Zhou (2020)</u> in a one-player stopping poblem.

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For any  $T \in \mathcal{B}$ , define  $\Phi_i^T : \mathcal{B} \to \mathcal{B}$  by

$$\Phi_i^T(S) := S \cup \left\{ x \notin S : J_i(x, 0, \rho_T) > V_i^T(x, S) \right\},\tag{5}$$

where

$$V_i^T(x,S) := \sup_{1 \le \tau \le \rho_S^+} \mathbb{E}_x[F_i(\tau,\rho_T)] \quad x \in \mathbb{X}, S \in \mathcal{B}.$$
 (6)

Theorem (Direct iteration to  $\widehat{\mathcal{E}}_{i}^{T}$ ) Assume  $h_{i} \leq g_{i}$ . Given  $T \in \mathcal{B}$ , define  $(S_{i}^{n}(T))_{n \in \mathbb{N}} \subset \mathcal{B}$  by  $S_{i}^{1}(T) := \Phi_{i}^{T}(\emptyset), \quad S_{i}^{n}(T) := \Phi_{i}^{T}(S^{n-1}(T)) \text{ for } n \geq 2,$  (7) Then,  $D_{i}(T) = \Phi_{i}^{T}(\emptyset) = \Phi_{i}^{T}(G^{n-1}(T)) \quad (0)$ 

$$\Gamma_i(T) := \bigcup_{n \in \mathbb{N}} S_i^n(T) \in \widehat{\mathcal{E}}_i^T.$$
 (8)



### ALTERNATING ITERATION

Let Players 1 and 2 *take turns* to perform iteration (7).

$S_0$	$T_0 = \Gamma_2(S_0)$
$S_1 = \Gamma_1(T_0)$	$T_1 = \Gamma_2(S_1)$
$S_2 = \Gamma_1(T_1)$	$T_2 = \Gamma_2(S_2)$
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#### Hope:

- 1)  $(S_n, T_n)$  converges appropriately.
- 2) The limit  $(S_{\infty}, T_{\infty})$  is a (*sharp*) inter-personal equilibrium.

$$J_i(x,\tau,\rho_T) \le J_i(x,\tau,\rho_R) \quad \forall x \in \mathbb{X}, \ \tau \in \mathcal{T}.$$
 (11)

In view of (6), for any  $x \in \mathbb{X}$  and  $S, S' \in \mathcal{B}$  with  $S \supseteq S'$ ,

$$V_i^T(x,S) \leq V_i^R(x,S) \leq V_i^R(x,S'). \implies \Phi_i^T(S) \supseteq \Phi_i^R(S) \supseteq \Phi_i^R(S').$$

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Corollary ( $T \mapsto \Gamma_i(T)$  monotone) Assume  $f_i \leq h_i \leq g_i$  and (9). For any  $T, R \in \mathcal{B}$  with  $T \subseteq R$ ,  $\Gamma_i(T) \supseteq \Gamma_i(R).$ 

**Idea:** Taking  $S_0 = \emptyset$ ,

$S_0 = \emptyset$	$T_0 = \Gamma_2(S_0)$
$S_1 = \Gamma_1(T_0)$	$T_1 = \Gamma_2(S_1)$
$S_2 = \Gamma_1(T_1)$	$T_2 = \Gamma_2(S_2)$
:	:

Hence, the limit is well-defined as

$$(S_{\infty},T_{\infty})=(\cup_n S_n,\cap_n T_n)\in\mathcal{B}\times\mathcal{B}.$$

INTRODUCTION Model RESULTS Theorem (Existence of the *soft*) Assume  $|f_i \le h_i \le g_i$  and (9). Set  $S_0 := \emptyset$  and define  $T_n := \Gamma_2(S_n) \qquad S_{n+1} := \Gamma_1(T_n), \quad \forall n \in \mathbb{N} \cup \{0\}.$ (12)Then,  $(S_{\infty}, T_{\infty}) := (\bigcup_n S_n, \bigcap_n T_n) \in \mathcal{E}$  and satisfies  $\Gamma_1(T_\infty) = S_\infty, \quad \Gamma_2(S_\infty) \subset T_\infty.$ (13)

**Proof.** Fix  $x \in S_{\infty}$ .  $\exists N \in \mathbb{N}$  s.t.  $x \in S_{n+1} = \Gamma_1(T_n) \in \mathcal{E}_1^{T_n} \ \forall n > N$ .

$$J_1(x,0,\rho_{T_n}) \ge J_1(x,\rho_{S_{n+1}}^+,\rho_{T_n}) \quad \forall n \ge N.$$
  
$$\Longrightarrow J_1(x,0,\rho_{T_\infty}) \ge J_1(x,\rho_{S_\infty}^+,\rho_{T_\infty}), \text{ i.e. } x \in \Theta_1^{T_\infty}(S_\infty).$$

Thus,  $S_{\infty} \subseteq \Theta_1^{T_{\infty}}(S_{\infty})$ . Can get  $(S_{\infty})^c \subseteq (\Theta_1^{T_{\infty}}(S_{\infty}))^c$  similarly. <u>Conclude:</u>  $S_{\infty} = \Theta_1^{T_{\infty}}(S_{\infty})$  and  $T_{\infty} = \Theta_2^{S_{\infty}}(T_{\infty})$ .

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**Proof (conti.).** By monotonicity of  $T \mapsto \Gamma_i(T)$ ,

$$S_n \subseteq S_{\infty} \implies \Gamma_2(S_{\infty}) \subseteq \Gamma_2(S_n) = T_n \implies \Gamma_2(S_{\infty}) \subseteq T_{\infty},$$
  
$$T_n \supseteq T_{\infty} \implies \Gamma_1(T_{\infty}) \supseteq \Gamma_1(T_n) = S_{n+1} \implies \Gamma_1(T_{\infty}) \supseteq S_{\infty},$$

Also, by  $S_0 = \emptyset \subseteq S_\infty \in \mathcal{E}_1^{T_\infty}$ , can construct  $\{S_i^n(T_\infty)\}_n$  in (7) and find  $S_i^n(T_\infty) \subseteq S_\infty$  for all *n*. Hence,  $\Gamma_1(T_\infty) \subseteq S_\infty$ .

#### Lemma

Assume 
$$h_i \leq g_i$$
. If  $(S,T) \in \mathcal{B} \times \mathcal{B}$  satisfies  
 $\Gamma_1(T) = S \quad and \quad \Gamma_2(S) = T,$  (14)  
then  $(S,T) \in \widehat{\mathcal{E}}.$ 

• By (13),  $(S_{\infty}, T_{\infty})$  is <u>almost</u> sharp!

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### EXAMPLE I

• 
$$\mathbb{X} = \{x_0, x_1, x_2, ...\}$$
 with  
 $\mathbb{P}_{x_{n+1}}(X_1 = x_n) = 1, \quad n = 0, 1, 2...,$   
 $\mathbb{P}_{x_0}(X_1 = x_0) = 1 - \varepsilon, \quad \mathbb{P}_{x_0}(X_1 = x_1) = \varepsilon, \text{ for } \varepsilon \in [0, 1).$ 

- Take M > 1 such that  $\delta_2(2) < 1/M < \delta_2(1)$ .
- Take L > 1 and define

$$f_1(x_n) = 1, \quad g_1(x_n) = L \quad n = 0, 1, 2, \dots,$$
  
$$f_2(x_0) = 0, \quad f_2(x_n) = 1 \quad n = 1, 2, \dots, \quad g_2(x_n) = M \quad n = 0, 1, 2 \dots,$$

while  $h_i$  is any function such that  $f_i \leq h_i \leq g_i$ .

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#### For $\varepsilon \in [0, 1)$ small enough,

- $S_{0} = \emptyset, \qquad T_{0} = \{x_{1}, x_{2}, \dots\}, \\S_{1} = \{x_{0}\}, \qquad T_{1} = \{x_{2}, x_{3}, \dots\}, \\S_{2} = \{x_{0}, x_{1}\}, \qquad T_{2} = \{x_{3}, x_{4}, \dots\}, \\\vdots \qquad \vdots \\S_{n} = \{x_{0}, x_{1}, \dots, x_{n-1}\}, \qquad T_{n} = \{x_{n+1}, x_{n+2}, \dots\}.$
- $\blacktriangleright (S_{\infty}, T_{\infty}) = (\mathbb{X}, \emptyset).$
- Is it *sharp*? Let's check  $\Gamma_2(\mathbb{X}) = \emptyset$ .

 $V_2^{\mathbb{X}}(x_n, \emptyset) = \sup_{1 \le \tau \le \rho_{\emptyset}^+} \mathbb{E}_{x_n}[F_2(\tau, \rho_{\mathbb{X}})] = g_2(x_n) \ge h_2(x_n) = J_2(x_n, 0, \rho_{\mathbb{X}}).$ 

This implies  $\Phi_2^{\mathbb{X}}(\emptyset) = \emptyset$ , so  $\Gamma_2(\mathbb{X}) = \emptyset$ .  $\Longrightarrow (S_{\infty}, T_{\infty}) \in \widehat{\mathcal{E}}$ .

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### EXAMPLE II

- $\blacktriangleright \mathbb{X} = \{x_0, x_1, x_2, \dots\} \cup \{y, z\}.$
- ► All previous settings remain.
- Transition probabilities for  $\{y, z\}$

$$\mathbb{P}_{y}(X_{1} = x_{n}) = p_{n} > 0 \text{ with } \sum_{n=0}^{\infty} p_{n} = 1, \ \mathbb{P}_{z}(X_{1} = y) = 1.$$

► 
$$\delta_2(1)^2 < \delta_2(2).$$

• Payoffs on  $\{y, z\}$ :

$$\begin{split} f_2(y) &= M\delta_2(1), \quad f_2(z) \in \left(M\delta_2(1)^2 \lor \delta_2(2), M\delta_2(2)\right), \\ g_2(y) &= g_2(z) = M. \end{split}$$

• Only require  $f_1 \leq g_1$ .

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For  $\varepsilon \in [0, 1)$  small enough,

 $\begin{array}{ll} S_0 = \emptyset, & T_0 = \{x_1, x_2, \dots\} \cup \{y, z\}, \\ S_1 = \{x_0\}, & T_1 = \{x_2, x_3, \dots\} \cup \{y, z\}, \\ S_2 = \{x_0, x_1\}, & T_2 = \{x_3, x_4, \dots\} \cup \{y, z\}, \end{array}$ 

$$S_n = \{x_0, x_1, \dots, x_{n-1}\}, \quad T_n = \{x_{n+1}, x_{n+2}, \dots\} \cup \{y, z\}.$$

:

 $\blacktriangleright (S_{\infty}, T_{\infty}) = (\mathbb{X}, \{y, z\}).$ 

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- Similarly to Example I,  $\Gamma_2(\mathbb{X}) = \emptyset$ .  $\implies \Gamma_2(S_\infty) = \emptyset \subsetneq T_\infty$ .
- <u>Note</u>:  $\emptyset = \Gamma_2(S_\infty) \in \widehat{\mathcal{E}}_2^{S_\infty}$  dominates  $T_\infty \in \mathcal{E}_2^{S_\infty}$  at *z*:

$$\begin{aligned} U_2^{S_{\infty}}(z,T_{\infty}) &= J_2(z,0,\rho_{S_{\infty}}) \lor J_2(z,\rho_{T_{\infty}}^+,\rho_{S_{\infty}}) = f_2(z) \lor M\delta_2(1)^2 \\ &= f_2(z) < M\delta_2(2) = J_2(z,\rho_{\emptyset}^+,\rho_{S_{\infty}}) \le U_2^{S_{\infty}}(z,\emptyset). \end{aligned}$$

• So, 
$$T_{\infty} \notin \widehat{\mathcal{E}}_2^{S_{\infty}}$$
.  $\implies (S_{\infty}, T_{\infty}) \notin \widehat{\mathcal{E}}$ .

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### EXISTENCE OF THE Sharp

#### Assumption 1

X has transition densities  $(p_t)_{t\geq 1}$  w.r.t a measure  $\mu$  on  $(\mathbb{X}, \mathcal{B})$ . That is, for  $t = 1, 2, ..., p_t : \mathbb{X} \times \mathbb{X} \to \mathbb{R}_+$  is Borel and

$$\mathbb{P}_x(X_t \in A) = \int_A p_t(x,y) \mu(dy) \quad orall x \in \mathbb{X}, \ A \in \mathcal{B}.$$

#### Lemma

Let  $\mu$  be a measure on (X, B). Given  $A \subseteq X$ , there is a maximal Borel minorant of A under  $\mu$ , defined as

• a set  $A^{\mu} \in \mathcal{B}$  with  $A^{\mu} \subseteq A$  such that

for any 
$$A' \in \mathcal{B}$$
 with  $A' \subseteq A$ ,  $\mu(A' \setminus A^{\mu}) = 0$ .



Under Assumption 1, 
$$f_i \leq h_i \leq g_i$$
, and (9),

there exists a *sharp* inter-personal equilibrium.

To prove this, we focus on the collection

 $A := \{ (S,T) \in \mathcal{E} : \Gamma_1(T) \supseteq S \text{ and } \Gamma_2(S) \subseteq T \}.$ 

By previous Thm,  $A \neq \emptyset$ . Define a *partial order* on *A*:

 $(S,T) \succeq (S',T') \text{ if } S \supseteq S' \text{ and } T \subseteq T'.$  (15)

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Suppose there exists a *maximal element*  $(\overline{S}, \overline{T})$  in *A*.

Claim: 
$$(\overline{S}, \overline{T}) \in \widehat{\mathcal{E}}$$
.

• Set  $S_0 := \overline{S}$ ,  $T_0 := \overline{T}$ . Do alternating iteration:

 $S_{n+1} := \Gamma_1(T_n)$  and  $T_{n+1} := \Gamma_2(S_{n+1})$   $\forall n \ge 0.$ 

► As shown in previous Thm,

$$(S_{\infty},T_{\infty}):=(\cup_n S_n,\cap_n T_n)\in A.$$

▶ By construction,  $S_{\infty} \supseteq S_0 = \overline{S}$  and  $T_{\infty} \subseteq T_0 = \overline{T}$ . As  $(\overline{S}, \overline{T})$  is maximal in  $A, S_{\infty} = S_0 = \overline{S}$  and  $T_{\infty} = T_0 = \overline{T}$ .

$$\begin{cases} \Gamma_1(\bar{T}) = \Gamma_1(T_0) = S_1 = S_0 = \bar{S} \\ \Gamma_2(\bar{S}) = \Gamma_2(S_0) = \Gamma_2(S_1) = T_1 = T_0 = \bar{T} \implies (\bar{S}, \bar{T}) \in \widehat{\mathcal{E}}. \end{cases}$$

Let  $(S_{\alpha}, T_{\alpha})_{\alpha \in I}$  be a *totally ordered* subset of *A*. **Claim:**  $(S_{\alpha}, T_{\alpha})_{\alpha \in I}$  has an upper bound in *A*.

#### Idea:

• Set  $S_0 := \bigcup_{\alpha \in I} S_\alpha$ ,  $T_0 := \bigcap_{\alpha \in I} T_\alpha$ . Do alternating iteration:

 $S_{n+1} := \Gamma_1(T_n)$  and  $T_{n+1} := \Gamma_2(S_{n+1})$   $\forall n \ge 0.$ 

► <u>Expect:</u>  $(S_{\infty}, T_{\infty}) := (\cup_n S_n, \cap_n T_n) \in A.$ ⇒ This is an upper bound for  $(S_{\alpha}, T_{\alpha})_{\alpha \in I}$ .

**Measurability issue:**  $\cup_{\alpha \in I} S_{\alpha}$ ,  $\cap_{\alpha \in I} T_{\alpha} \notin \mathcal{B}$  in general!



• Let  $T_0^{\mu} \in \mathcal{B}$  a maximal Borel minorant of  $T_0$  under  $\mu$ .

• 
$$T_0^{\mu} \in \mathcal{B}$$
 and  $T_0^{\mu} \subseteq T_0$ .

• For any  $T \in \mathcal{B}$  with  $T \subseteq T_0$ ,  $\mu(T \setminus T_0^{\mu}) = 0$ .

• For any  $T \in \mathcal{B}$  with  $T \subseteq T_0$ ,

$$\mathbb{P}_x(X_t \in T \setminus T_0^\mu) = \int_{T \setminus T_0^\mu} p_t(x, y) \mu(dy) = 0 \quad \forall x \in \mathbb{X}, \ t > 0.$$

Hence,

 $\mathbb{P}_{x}(X_{t} \in T \setminus T_{0}^{\mu} \text{ for some } t \in \mathbb{N}) = 0 \quad \forall x \in \mathbb{X}.$ (16)



Modified alternating iteration:

$$S_{0} = \bigcup_{\alpha \in I} S_{\alpha} \qquad T_{0} = \bigcap_{\alpha \in I} T_{\alpha}$$

$$S_{1} = \Gamma_{1}(T_{0}^{\mu}) \supseteq S_{0} \qquad T_{1} = \Gamma_{2}(S_{1})$$

$$S_{2} = \Gamma_{1}(T_{1}) \qquad T_{2} = \Gamma_{2}(S_{2})$$

$$\vdots \qquad \vdots$$

• For any  $T \in \mathcal{B}$  with  $T \subseteq T_0$ ,

 $\Gamma_1(T) \supseteq \Gamma_1(T_\alpha) \supseteq S_\alpha \ \forall \alpha \in I \implies \Gamma_1(T) \supseteq S_0.$ 

For any  $S \in \mathcal{B}$  with  $S \supseteq S_0$ ,

 $\Gamma_2(S) \subseteq \Gamma_2(S_\alpha) \subseteq T_\alpha \ \forall \alpha \in I \implies \Gamma_2(S) \subseteq T_0.$ 



Modified alternating iteration:

 $S_{0} = \bigcup_{\alpha \in I} S_{\alpha} \qquad T_{0} = \bigcap_{\alpha \in I} T_{\alpha}$   $S_{1} = \Gamma_{1}(T_{0}^{\mu}) \supseteq S_{0} \qquad T_{1} = \Gamma_{2}(S_{1}) \subseteq T_{0}$   $S_{2} = \Gamma_{1}(T_{1}) \supseteq \Gamma_{1}(T_{0}) \neq S_{1} \qquad T_{2} = \Gamma_{2}(S_{2})$   $\vdots \qquad \vdots$   $\mathsf{By} (16), \ \rho_{T_{1} \cup T_{0}^{\mu}} = \rho_{T_{0}^{\mu}} \mathbb{P}_{x}\text{-a.s., for } x \notin T_{1} \cup T_{0}^{\mu}.$   $S_{2} := \Gamma_{1}(T_{1}) \supseteq \Gamma_{1}(T_{1} \cup T_{0}^{\mu}) = \Gamma_{1}(T_{0}^{\mu}) = S_{1}.$ 



Modified alternating iteration:

 $S_{0} = \bigcup_{\alpha \in I} S_{\alpha} \qquad T_{0} = \bigcap_{\alpha \in I} T_{\alpha}$   $S_{1} = \Gamma_{1}(T_{0}^{\mu}) \supseteq S_{0} \qquad T_{1} = \Gamma_{2}(S_{1}) \subseteq T_{0}$   $S_{2} = \Gamma_{1}(T_{1}) \supseteq S_{1} \qquad T_{2} = \Gamma_{2}(S_{2}) \subseteq T_{1}$   $\vdots \qquad \vdots$ 

**Conclude:**  $(S_{\infty}, T_{\infty}) := (\cup_n S_n, \cap_n T_n) \in A$  is well-defined, and is an upper bound for  $(S_{\alpha}, T_{\alpha})_{\alpha \in I}$ .

► By Zorn's lemma, the proof is complete.

### SUMMARY

### **Soft** inter-personal equilibrium:

A **Nash equilibrium** between two players, each of whom uses an intra-personal equilibrium.

- Always exists.
- Can be found via concrete alternating iteration.
- ► Sharp inter-personal equilibrium:

A **Nash equilibrium** between two players, each of whom uses an *<u>optimal</u>* intra-personal equilibrium.

- Exists, if *X* has transition densities.
- Constructed via alternating iteration + Zorn's lemma.

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## APPLICATION TO NEGOTIATION

Firms 1, 2 want to cooperate to initiate a project

- Each firm has a proprietary skill/technology.
- Revenue R > 0 fixed.
- Cost X > 0 is random:  $\exists u > 1$  and  $p \in (0, 1)$  s.t.

$$\mathbb{P}_x[X_1/x=u]=p \text{ and } \mathbb{P}_x[X_1/x=1/u]=1-p, \quad \forall x\in\mathbb{X}.$$

That is, X evolves on the binomial tree

$$\mathbb{X} = \{ u^i : i = 0, \pm 1, \pm 2, \dots \}$$
(17)



- Each firm insists on...
  - ▶ Taking a larger (risk-free) share  $N \in (R/2, R)$ ;
  - Demanding the other to take smaller share  $K := R N \in (0, R/2)$  and incur (risky) cost *X*.

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► In our Dynkin game,

$$F_i(\tau,\sigma) := \delta_i(\tau) (K - X_\tau)^+ \mathbf{1}_{\{\tau < \sigma\}} + \delta_i(\sigma) N \mathbf{1}_{\{\tau > \sigma\}} + \delta_i(\tau) h_i(X_\tau) \mathbf{1}_{\{\tau = \sigma\}},$$

$$\delta_i(t) = \frac{1}{1 + \beta_i t},$$

•  $\beta_i > 0$ : impatience level of Firm *i*.



### THE STRATEGY OF COERCION

► Demonstrate (or pretend!?) a strong will <u>not</u> to give in...

- ...to *coerce* the other firm to give in.
- "Never give in"  $\iff \tau = \infty \iff S_0 = \emptyset$ .

### Proposition (Firm 1 more patient)

If  $\beta_1 \leq \beta_2$ , the alternating iterative procedure (12) terminates after one iteration:  $\exists y_2^* \in [0, \infty) \cap \mathbb{X}$  s.t.

$$\underbrace{S_0 = \emptyset}_{0 = \infty} \implies T_0 = (0, y_2^*] \cap \mathbb{X} \implies \underbrace{S_1 = \emptyset}_{0 = \infty}.$$

Moreover,  $(S_{\infty}, T_{\infty}) = (S_0, T_0) = (\emptyset, (0, y_2^*] \cap \mathbb{X}) \in \widehat{\mathcal{E}}$ .

► **Message:** *"More patient"* ⇒ coercion works

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• What if Firm 1 is *less patient*  $(\beta_1 > \beta_2)$ ?

- ► Complicated...
  - $\implies$  Coercion may or may not work.

Proposition (Firm 1 *significantly less patient*) If  $\beta_1 > 0$  sufficiently large and  $\beta_2 > 0$  sufficiently small, iterative procedure (12) yields

$$\begin{split} (\underline{S_0}, T_0) &= (\underline{\emptyset}, (0, y_2^*] \cap \mathbb{X}) \implies (S_1, T_1) \implies (S_2, T_2) \\ &\implies \cdots \\ &\implies (S_{\infty}, \underline{T_{\infty}}) = ((0, y_1^*] \cap \mathbb{X}, \underline{\emptyset}) \in \widehat{\mathcal{E}}, \end{split}$$

for some  $y_1^*, y_2^* \in [0, \infty) \cap \mathbb{X}$ .

► Message: "significantly less patient" ⇒ coercer is coerced!

# THANK YOU!!

 "A Time-Inconsistent Dynkin Game: from Intra-personal to Inter-personal Equilibria" (H. and Z. Zhou), to appear in Finance & Stochastics, available @ arXiv:2101.00343.