

1. (28 points: 7 each) If the statement is **always true** mark “TRUE” and provide a *brief* justification; if it is possible for the statement to be false then mark “FALSE” and provide a counterexample.

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(a) If  $U$  is an upper triangular matrix and has an inverse, then its inverse is lower triangular.

**False.** As a counterexample, consider the upper triangular matrix  $U = \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix}$ . Its inverse is  $U^{-1} = \begin{bmatrix} 1 & -2 \\ 0 & 1 \end{bmatrix}$  which is not lower triangular.

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(b) If the rank of  $A$  is 2 and  $A$  is a  $2 \times 4$  matrix, then the kernel of  $A$  has dimension 2.

**True.** From the Fundamental Theorem of Linear Algebra (FTLA), we know that the number of columns of  $A$  is the sum of the rank of  $A$  and the dimension of the kernel of  $A$ . That is,  $4 = 2 + \dim(\ker(A))$ , which implies  $\dim(\ker(A)) = 2$ .

(c) If  $\det(A) = 0$ , then  $A\mathbf{x} = \mathbf{b}$  has no solutions.

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**False.** Consider  $A = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$  and  $\mathbf{b} = \mathbf{0}$ . We have  $\det(A) = 0$  but  $A\mathbf{x} = \mathbf{b}$  has solution  $\mathbf{x} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ .

(d) If  $\mathcal{W}$  is the set of  $n \times n$  matrices,  $A$ , such that  $\det(A) = 0$ , then  $\mathcal{W}$  a subspace of the  $\mathbb{R}^{n \times n}$ , the vector space of all  $n \times n$  matrices.

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**False.** Note that  $A = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$  and  $B = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$  both lie in  $\mathcal{W}$ , but  $A + B = I$  does not. That is,  $\mathcal{W}$  is not closed under addition, so  $\mathcal{W}$  cannot be a subspace of  $\mathbb{R}^{n \times n}$ .

2. (16 points) Consider  $A = \begin{bmatrix} 1 & -1 & 2 & 1 \\ 2 & 1 & -2 & -1 \\ 1 & 2 & -4 & -3 \\ 0 & 3 & -6 & -2 \end{bmatrix}$ .  $A$  is row equivalent to  $\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & -2 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$  and

$A^T$  is row equivalent to  $\begin{bmatrix} 1 & 0 & 0 & -3 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$ . Use this information to determine bases for the four

fundamental subspaces associated with the matrix  $A$ . (Clearly indicate which basis belongs to which subspace.)

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The columns of  $A$  that correspond to the pivots of its reduced form are a basis for  $\text{Ran}(A)$ :

$$\left\{ \begin{bmatrix} 1 \\ 2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ -3 \\ -2 \end{bmatrix} \right\}.$$

The rows of a row echelon form of  $A$  form a basis for  $\text{Coran}(A)$ :

$$\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ -2 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right\}.$$

To find a basis for  $\ker(A)$ , we consider the solutions of  $A\mathbf{x} = \mathbf{0}$ . Note that  $x_1 = 0$ ,  $x_2 = 2x_3$ , and  $x_4 = 0$  where  $x_3$  is free. So, a basis for  $\ker(A)$  is

$$\left\{ \begin{bmatrix} 0 \\ 2 \\ 1 \\ 0 \end{bmatrix} \right\}.$$

To find a basis for  $\text{Coker}(A)$ , we consider the solutions of  $A^T\mathbf{x} = \mathbf{0}$ . Note that  $x_1 = 3x_4$ ,  $x_2 = -2x_4$ , and  $x_3 = x_4$  where  $x_4$  is free. So, a basis for  $\text{Coker}(A)$  is

$$\left\{ \begin{bmatrix} 3 \\ -2 \\ 1 \\ 1 \end{bmatrix} \right\}.$$

3. Consider the matrix  $A = \begin{bmatrix} 1 & 2 & 3 \\ 3 & 5 & 5 \\ 2 & 1 & 2 \end{bmatrix}$ .

(a) (14 points) Use Gauss-Jordan Elimination to find the inverse of  $\mathbf{A}$ .

We set up the augmented matrix  $[A|I]$  and row reduce until we have  $I$  on the left-side of the partition.

$$[A|I] = \left[ \begin{array}{ccc|ccc} 1 & 2 & 3 & 1 & 0 & 0 \\ 3 & 5 & 5 & 0 & 1 & 0 \\ 2 & 1 & 2 & 0 & 0 & 1 \end{array} \right] \xrightarrow{\substack{R'_2=R_2-3R_1 \\ R'_3=R_3-2R_1}} \left[ \begin{array}{ccc|ccc} 1 & 2 & 3 & 1 & 0 & 0 \\ 0 & -1 & -4 & -3 & 1 & 0 \\ 0 & -3 & -4 & -2 & 0 & 1 \end{array} \right] \xrightarrow{R'_2=-R_2}$$

$$\left[ \begin{array}{ccc|ccc} 1 & 2 & 3 & 1 & 0 & 0 \\ 0 & 1 & 4 & 3 & -1 & 0 \\ 0 & -3 & -4 & -2 & 0 & 1 \end{array} \right] \xrightarrow{\substack{R'_1=R_1-2R_2 \\ R'_3=R_3+3R_2}} \left[ \begin{array}{ccc|ccc} 1 & 0 & -5 & -5 & 2 & 0 \\ 0 & 1 & 4 & 3 & -1 & 0 \\ 0 & 0 & 8 & 7 & -3 & 1 \end{array} \right] \xrightarrow{R'_3=\frac{1}{8}R_3}$$

$$\left[ \begin{array}{ccc|ccc} 1 & 0 & -5 & -5 & 2 & 0 \\ 0 & 1 & 4 & 3 & -1 & 0 \\ 0 & 0 & 1 & \frac{7}{8} & -\frac{3}{8} & \frac{1}{8} \end{array} \right] \xrightarrow{\substack{R'_1=R_1+5R_3 \\ R'_2=R_2-4R_3}} \left[ \begin{array}{ccc|ccc} 1 & 0 & 0 & -\frac{5}{8} & \frac{1}{8} & \frac{5}{8} \\ 0 & 1 & 0 & -\frac{1}{8} & \frac{1}{8} & -\frac{1}{8} \\ 0 & 0 & 1 & \frac{7}{8} & -\frac{3}{8} & \frac{1}{8} \end{array} \right]$$

So, we have  $A^{-1} = \frac{1}{8} \begin{bmatrix} -5 & 1 & 5 \\ -4 & 4 & -4 \\ 7 & -3 & 1 \end{bmatrix}$ .

(b) (6 points) Use your answer from (a) to find the solution of

$$\begin{cases} x_1 + 2x_2 + 3x_3 = -3 \\ 3x_1 + 5x_2 + 5x_3 = 0 \\ 2x_1 + x_2 + 2x_3 = 2 \end{cases} .$$

You must use your answer from (a) to receive points. (Other methods will receive no points.)

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$$\mathbf{x} = A^{-1}\mathbf{b} = \frac{1}{8} \begin{bmatrix} -5 & 1 & 5 \\ -4 & 4 & -4 \\ 7 & -3 & 1 \end{bmatrix} \begin{bmatrix} -3 \\ 0 \\ 2 \end{bmatrix} = \frac{1}{8} \begin{bmatrix} 25 \\ 4 \\ -19 \end{bmatrix} .$$

4. (15 points) Prove that if  $A$  is nonsingular, then  $A^T A$  is also nonsingular.

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**One Possibility:**

Recall that a matrix is nonsingular if and only if its determinant is nonzero. Also,  $\det(A) = \det(A^T)$ . So,  $\det(A)$  is nonzero and

$$\det(A^T A) = \det(A^T) \det(A) = \det(A) \det(A) = \det(A)^2 \neq 0.$$

Thus,  $A^T A$  is nonsingular.

**Another Possibility:**

Recall that a matrix is nonsingular if and only if it is invertible. Since  $A$  is invertible, then we know that  $A^T$  is also invertible with inverse  $(A^T)^{-1} = (A^{-1})^T$ . We observe that

$$\begin{aligned} (A^T A)(A^{-1}(A^{-1})^T) &= A^T(AA^{-1})(A^{-1})^T \\ &= A^T I (A^{-1})^T \\ &= A^T (A^{-1})^T \\ &= I. \end{aligned}$$

We have shown that  $A^T A$  is invertible. Therefore it is nonsingular.

5. Let  $A = \begin{bmatrix} 0 & 0 & -4 \\ 1 & 2 & 3 \\ 0 & 1 & 7 \end{bmatrix}$ .

(a) (15 points) Determine the permuted LU-factorization of  $A$ .

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$$A \xrightarrow{R_1 \leftrightarrow R_2} \begin{bmatrix} 1 & 2 & 3 \\ 0 & 0 & -4 \\ 0 & 1 & 7 \end{bmatrix} \xrightarrow{R_2 \leftrightarrow R_3} \begin{bmatrix} 1 & 2 & 3 \\ 0 & 1 & 7 \\ 0 & 0 & -4 \end{bmatrix} = U$$

where  $L = I$  because no elimination operations were applied, and

$$P = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}$$

because of the row interchanges that were applied. With these matrices, we have  $PA = LU$ .

(b) (6 points) Use the answer from (a) to find the determinant of  $A$ . (Other methods will receive no credit here.)

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From (a), we know  $U$  and that  $N = 2$  because two elementary permutations were applied. So,

$$\det(A) = (-1)^N \det(U) = (-1)^2(1)(1)(-4) = -4.$$