

1. (60 pts) The following problems are unrelated.

(a) Find the general solution to the linear system of differential equations  $\vec{x}' = \begin{bmatrix} 0 & 1 \\ -2 & -3 \end{bmatrix} \vec{x}$ .

(b) Compute the Laplace transform of the function  $f(t) = \begin{cases} 0 & t < 0 \\ \sin(t) & 0 \leq t < \pi \\ 0 & t \geq \pi \end{cases}$ .

(c) Determine the inverse Laplace transform of the following:

i.  $F(s) = \frac{1}{s^2 + 2s + 4}$

ii.  $G(s) = \frac{3s + 11}{s^2 - s - 6}$

(d) For which initial conditions can we guarantee a unique solution exists to the initial value problem

$$y' = \frac{1}{y-t}, \quad y(t_0) = y_0$$

(e) i. Show that the set of diagonal  $3 \times 3$  matrices is a vector space.

ii. Let  $\mathbb{W}$  be a subspace of  $\mathbb{P}_4$ ,  $\mathbb{W} = \{p(x) \in \mathbb{P}_4 \mid p(x) = ax^4 + bx^2 + c\}$ . Determine the dimension and a basis of the subspace  $\mathbb{W}$ .

(f) For which values of  $b$  does the system  $\vec{x}' = \begin{bmatrix} 0 & 1 \\ -1 & -b \end{bmatrix} \vec{x}$  have a solution that is a spiral toward the origin?

**Solution:**

(a) The coefficient matrix has the eigenvalues

$$\begin{vmatrix} -\lambda & 1 \\ -2 & -3-\lambda \end{vmatrix} = \lambda^2 + 3\lambda + 2 = 0 \implies \lambda_1 = -1, \lambda_2 = -2$$

with corresponding eigenvectors

$$\lambda_1 = -1 : \begin{bmatrix} 1 & 1 \\ -2 & -2 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \implies v_1 + v_2 = 0 \implies v_1 = -v_2 \implies \vec{v}_1 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$\lambda_2 = -2 : \begin{bmatrix} 2 & 1 \\ -2 & -1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \implies 2v_1 + v_2 = 0 \implies v_1 = -\frac{1}{2}v_2 \implies \vec{v}_2 = \begin{bmatrix} 1 \\ -2 \end{bmatrix}$$

The general solution is then given by

$$\boxed{\vec{x} = c_1 e^{-t} \begin{bmatrix} 1 \\ -1 \end{bmatrix} + c_2 e^{-2t} \begin{bmatrix} 1 \\ -2 \end{bmatrix}}$$

(b) The piecewise function can be rewritten as

$$f(t) = \sin(t) (\text{step}(t) - \text{step}(t - \pi))$$

So the Laplace transform is given by

$$\begin{aligned} \mathcal{L}\{f(t)\} &= \mathcal{L}\{\sin(t)\text{step}(t)\} - \mathcal{L}\{\sin(t)\text{step}(t - \pi)\} \\ &= \mathcal{L}\{\sin(t)\} - e^{-\pi s} \mathcal{L}\{\sin(t + \pi)\} \\ &= \frac{1}{s^2 + 1} - e^{-\pi s} \mathcal{L}\{\sin(t) \cos(\pi) + \sin(\pi) \cos(t)\} \\ &= \frac{1}{s^2 + 1} + e^{-\pi s} \mathcal{L}\{\sin(t)\} = \frac{1 + e^{-\pi s}}{s^2 + 1} \end{aligned}$$

(c) i. Complete square in the denominator and then manipulate

$$F(s) = \frac{1}{s^2 + 2s + 1 - 1 + 4} = \frac{1}{(s + 1)^2 + (\sqrt{3})^2} = \frac{1}{\sqrt{3}} \frac{\sqrt{3}}{(s + 1)^2 + (\sqrt{3})^2}$$

which is of an appropriate form to compute the inverse Laplace transform using the table provided. The function in the time domain is then

$$f(t) = \mathcal{L}^{-1} \left\{ \frac{1}{\sqrt{3}} \frac{\sqrt{3}}{(s + 1)^2 + (\sqrt{3})^2} \right\} = \boxed{\frac{1}{\sqrt{3}} e^{-t} \sin(\sqrt{3}t)}$$

ii. Factoring the denominator, the function can be rewritten as

$$G(s) = \frac{3s + 11}{(s - 3)(s + 2)},$$

Seeking a partial fraction decomposition of the form  $\frac{A}{s - 3} + \frac{B}{s + 2}$ , we find that  $A$  and  $B$  are given by solutions to the linear system

$$\begin{aligned} A + B &= 3 \\ 2A - 3B &= 11 \end{aligned}$$

so that  $A = 4$  and  $B = -1$ . Therefore

$$G(s) = \frac{4}{s - 3} - \frac{1}{s + 2},$$

and the inverse Laplace transform is

$$g(t) = \mathcal{L}^{-1} \left\{ \frac{4}{s - 3} - \frac{1}{s + 2} \right\} = \boxed{4e^{3t} - e^{-2t}}$$

(d) Here we apply both parts of Picard's theorem with the function  $f(t, y) = \frac{1}{y - t}$ . Since  $f(t, y)$  is continuous for all values such that  $y \neq t$ , then we can guarantee a solution to the IVP exists for  $y_0 \neq t_0$ . Similarly,  $f_y(t, y) = \frac{1}{(y - t)^2}$  is continuous for all values such that  $y \neq t$ , guaranteeing there is a unique solution to the IVP so long as  $y_0 \neq t_0$ .

- (e) i. The space of  $3 \times 3$  matrices contains the zero matrix, so the space is clearly nonempty. Now we need to show the closure properties. Let

$$A = \begin{bmatrix} a_{11} & 0 & 0 \\ 0 & a_{22} & 0 \\ 0 & 0 & a_{33} \end{bmatrix} \quad \text{and} \quad B = \begin{bmatrix} b_{11} & 0 & 0 \\ 0 & b_{22} & 0 \\ 0 & 0 & b_{33} \end{bmatrix}$$

Then

$$A + B = \begin{bmatrix} a_{11} + b_{11} & 0 & 0 \\ 0 & a_{22} + b_{22} & 0 \\ 0 & 0 & a_{33} + b_{33} \end{bmatrix},$$

which is a diagonal  $3 \times 3$  matrix, so the set is closed under addition. Similarly, for  $c \in \mathbb{R}$

$$cA = \begin{bmatrix} ca_{11} & 0 & 0 \\ 0 & ca_{22} & 0 \\ 0 & 0 & ca_{33} \end{bmatrix},$$

is a  $3 \times 3$  diagonal matrix so that the set is closed under scalar multiplication. Therefore, the set of  $3 \times 3$  diagonal matrices forms a vector space.

- ii. A basis for the subspace is  $\{x^4, x^2, 1\}$  so that the dimension is 3.
- (f) The solution will spiral towards the origin if the eigenvalues of  $A = \begin{bmatrix} 0 & 1 \\ -1 & -b \end{bmatrix}$  have negative real part and nonzero imaginary part. The eigenvalues are given when

$$|A - \lambda I| = \begin{vmatrix} -\lambda & 1 \\ -1 & -b - \lambda \end{vmatrix} = -\lambda(-b - \lambda) + 1 = \lambda^2 + b\lambda + 1 = 0$$

So the eigenvalues of  $A$  are

$$\lambda_{\pm} = \frac{-b \pm \sqrt{b^2 - 4}}{2}$$

We will therefore have a spiral solution towards the origin so long as  $b > 0$  and  $b^2 - 4 < 0$ . The latter inequality is equivalent to  $-2 < b < 2$ . Since  $b$  must be positive, this requires  $0 < b < 2$ .

Alternatively, using the  $\text{Tr}A/|A|$  parameter plane graph, for an attracting spiral we need  $\text{Tr}A$  negative,  $|A|$  positive and  $|A| > \frac{1}{4}(\text{Tr}A)^2$  (above the parabola).  $\text{Tr}A = -b < 0$  requires  $b > 0$ . To stay above the parabola we need  $1 > \frac{1}{4}(-b)^2 \implies 4 > b^2 \implies 2 > b > -2$ . Combining these two requirements gives  $0 < b < 2$  for an attracting spiral.

2. (25 pts) Solve the initial value problem with Laplace transforms.

$$y' + 2y = \delta(t - 1) - 3, \quad y(0) = 1.$$

**Solution:** Taking the Laplace transform of both sides, we obtain

$$\begin{aligned} \mathcal{L}\{y'\} + 2\mathcal{L}\{y\} &= \mathcal{L}\{\delta(t - 1)\} - \mathcal{L}\{3\} \\ \implies s\mathcal{L}\{y\} - y(0) + 2\mathcal{L}\{y\} &= e^{-s} - \frac{3}{s} \\ \implies (s + 2)Y(s) &= 1 + e^{-s} - \frac{3}{s} \end{aligned}$$

where  $Y(s) = \mathcal{L}\{y\}$ . Solving for  $Y(s)$ , we find

$$\begin{aligned} Y(s) &= \frac{1}{s+2} + \frac{e^{-s}}{s+2} - \frac{3}{s(s+2)} \quad (\text{partial fractions}) \\ &= \frac{1}{s+2} + \frac{e^{-s}}{s+2} - \frac{3/2}{s} + \frac{3/2}{s+2} \\ &= \frac{5/2}{s+2} + \frac{e^{-s}}{s+2} - \frac{3/2}{s} \end{aligned}$$

Taking the inverse Laplace transform, we find the solution to the initial value problem is

$$y(t) = \mathcal{L}^{-1} \left\{ \frac{5/2}{s+2} + \frac{e^{-s}}{s+2} - \frac{3/2}{s} \right\} = \boxed{\frac{5}{2}e^{-2t} + e^{-2(t-1)}\text{step}(t-1) - \frac{3}{2}}$$

3. (25 pts) Consider the first order equation

$$t \frac{dy}{dt} - y = t^2, \quad y(1) = 3.$$

- Determine an integrating factor to solve the differential equation.
- Use the integrating factor you found in part (a) to find the general solution to the differential equation.
- Apply the initial condition to determine the solution to the initial value problem.
- Use Euler's method with a step size of  $h = 1$  to approximate  $y(2)$ .

**Solution:**

- First we need to rewrite the ODE so that the leading coefficient is 1.

$$y' - \frac{1}{t}y = t$$

The integrating factor is then  $\mu = e^{-\int \frac{1}{t} dt} = \boxed{\frac{1}{t}}$ .

- Multiplying the equation by the integrating factor, we have

$$\frac{1}{t}y' - \frac{1}{t^2}y = 1 \implies \frac{d}{dt} \left[ \frac{1}{t}y \right] = 1.$$

Integrating with respect to  $t$  gives

$$\frac{1}{t}y = t + C$$

so that the general solution is

$$\boxed{y = t^2 + Ct}$$

- Applying the initial condition  $y(1) = 3$  gives

$$\begin{aligned} 3 &= 1 + C \\ \implies C &= 2 \end{aligned}$$

so that the solution to the IVP is  $\boxed{y(t) = t^2 + 2t}$ .

(d) Euler's method with  $h = 1$  gives the approximation at  $t = 2$  as

$$y_2 = y_1 + hf(t_1, y_1),$$

where  $t_1 = 1$  and  $y_1 = 3$ , so that  $f(t_1, y_1) = t_1 + \frac{y_1}{t_1} = 4$ . So the approximation of  $y(2)$  from Euler's method with a step size of  $h = 1$  is

$$y(2) \approx y_2 = 3 + 1(4) = \boxed{7}$$

4. (20 pts) In this problem we will solve the differential equation

$$y'' + \frac{t}{1-t}y' - \frac{1}{1-t}y = 2(1-t)e^{-t}$$

- (a) Knowing that  $y_1 = t$  and  $y_2 = e^t$  are solutions to the homogeneous differential equation, use variation of parameters to determine the particular solution of the differential equation.
- (b) Give the general solution to the differential equation.

**Solution:**

- (a) Using variation of parameters, the particular solution is  $y_p = v_1y_1 + v_2y_2$ . The variable coefficients are then

$$v_1 = - \int \frac{y_2 f}{W(y_1, y_2)}, \quad v_2 = \int \frac{y_1 f}{W(y_1, y_2)}$$

where  $f = 2(1-t)e^{-t}$  and  $W(y_1, y_2) = \begin{vmatrix} t & e^t \\ 1 & e^t \end{vmatrix} = (t-1)e^t$ . Now, computing  $v_1$  and  $v_2$

$$\begin{aligned} v_1 &= - \int \frac{e^t (2(1-t)e^{-t})}{(t-1)e^t} dt \\ &= 2 \int e^{-t} dt \\ &= -2e^{-t} \end{aligned}$$

$$\begin{aligned} v_2 &= \int \frac{t (2(1-t)e^{-t})}{(t-1)e^t} dt \\ &= -2 \int te^{-2t} dt \quad (\text{integration by parts}) \\ &= \frac{1}{2}e^{-2t} + te^{-2t} \end{aligned}$$

Now, since  $y_p = v_1y_1 + v_2y_2$ , we find

$$\begin{aligned} y_p &= -2e^{-t}t + \left( \frac{1}{2}e^{-2t} + te^{-2t} \right) e^t \\ &= \boxed{\frac{1}{2}e^{-t} - te^{-t}} \end{aligned}$$

- (b) The general solution of the ODE is then given by

$$\boxed{y(t) = c_1t + c_2e^t + \frac{1}{2}e^{-t} - te^{-t}}$$

5. (20 pts) Consider the nonlinear system of equations

$$\begin{aligned}\frac{dx}{dt} &= (2 - x - y), \\ \frac{dy}{dt} &= -y(1 - x)\end{aligned}$$

- (a) Compute the nullclines of the system.
- (b) Identify the equilibrium solution(s) to the system of ordinary differential equations.

**Solution:**

- (a) The *v* nullclines (isoclines of vertical slope) occur where  $dx/dt = 0$ , so that these nullclines are  $y = 2 - x$ . Similarly the *h* nullclines (isoclines of horizontal slope) occur where  $dy/dt = 0$

$$-y(1 - x) = 0 \implies y = 0, \quad x = 1$$

- (b) The equilibrium solutions are found when  $dx/dt$  and  $dy/dt$  are simultaneously zero. The equilibrium solutions are

$$(2, 0), \quad (1, 1)$$