

APPM 2360: Final Exam

July 27, 2018

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ON THE FRONT OF YOUR BLUEBOOK write: (1) your name, (2) your instructor's name, (3) your recitation section number and (4) a grading table. Textbooks, class notes, cell phones and calculators are NOT permitted. A one page (letter sized **1 side only**) note sheet is allowed.

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**Problem 1:** (40 points) Answer each part of this question with TRUE or FALSE. **DO NOT** write T or F. Also, **provide a brief ONE SENTENCE justification.**

- (a) Suppose  $A$  is  $2 \times 2$  and has one repeated real eigenvalue  $\lambda$ . Then  $\lambda$  has two linearly independent eigenvectors.
- (b) Picard's Theorem says that there exists a unique solution to  $\frac{dy}{dt} = \frac{y}{t}$ ,  $y(1) = 0$  within some open interval containing  $t_0 = 1$ .
- (c) Suppose  $\lambda_1$  and  $\lambda_2$  are distinct eigenvalues of a matrix  $A$  and  $\lambda_1 \neq \lambda_2$ . Further assume that  $\vec{v}$  and  $\vec{u}$  are eigenvectors corresponding to  $\lambda_1$  and  $\vec{w}$  is an eigenvector corresponding to  $\lambda_2$ . Then the set  $\{\vec{v}, \vec{u}, \vec{w}\}$  is linearly independent by the Distinct Eigenvalue Theorem.
- (d) Suppose  $2 \times 2$  matrix  $A$  has eigenvalues  $\lambda_1 = 3$  and  $\lambda_2 = -1$  with corresponding eigenvectors  $\vec{v}_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$  and  $\vec{v}_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$  (i.e.,  $\vec{v}_i$  is an eigenvector corresponding to  $\lambda_i$  for  $i = 1, 2$ ). Then  $A \begin{pmatrix} -1 \\ 2 \end{pmatrix} = \begin{pmatrix} -3 \\ -2 \end{pmatrix}$
- (e) Let  $V = C([0, 1])$  be the space of continuous functions on  $[0, 1]$ . Then

$$W = \{f \in C([0, 1]) \mid \int_0^1 f(x) dx = 1\}$$

is a subspace of  $V$ .

**Solution:**

- (a) FALSE, may have 1
- (b) TRUE, both  $\frac{dy}{dt} = f(t, y) = \frac{y}{t}$  and  $f_y(t, y) = \frac{1}{t}$  are continuous in a region containing  $(t_0 = 1, y_0 = 0)$
- (c) FALSE,  $\vec{v}, \vec{u}$  may not be linearly independent
- (d) TRUE, because

$$A \begin{pmatrix} -1 \\ 2 \end{pmatrix} = A((-1)\vec{v}_1 + 2\vec{v}_2) = (-1)(3)\vec{v}_1 + (-1)(2)\vec{v}_2 = \begin{pmatrix} -3 \\ -2 \end{pmatrix}$$

- (e) FALSE, isn't closed under addition or scalar multiplication

**Problem 2:** (40 points) Solve the following IVP using Laplace Transforms.

$$y' - y = f(t), \quad y(0) = 0$$

where

$$f(t) = \begin{cases} 1 & 0 \leq t < 2 \\ 0 & \text{otherwise} \end{cases}$$

**Solution:**

$$f(t) = \text{step}(t) - \text{step}(t - 2)$$

Take Laplace Transform

$$\begin{aligned} sY - y(0) - Y &= \frac{1}{s} - \frac{e^{-2s}}{s} \\ \implies Y &= \frac{1}{s(s-1)} - \frac{e^{-2s}}{s(s-1)} \end{aligned}$$

Partial fractions

$$\frac{A}{s} + \frac{B}{s-1} = \frac{As - A + Bs}{s(s-1)} \implies A = -1, B + A = 0 \implies A = -1, B = 1$$

Thus,

$$\begin{aligned} \frac{1}{s(s-1)} - \frac{e^{-2s}}{s(s-1)} &= -\frac{1}{s} + \frac{1}{s-1} + e^{-2s} \left( -\frac{1}{s} + \frac{1}{s-1} \right) \\ &= -L(1) + L(e^t) - e^{-2s}L(1) + e^{-2s}L(e^t) \\ &= -L(1) + L(e^t) - e^{-2s}L(1) - L(1 \cdot \text{step}(t-2)) + L(e^{t-2}\text{step}(t-2)) \\ \implies y(t) &= -1 + e^t - \text{step}(t-2) + e^{t-2}\text{step}(t-2) \end{aligned}$$

**Problem 3:** (40 points)

Consider the differential equation

$$\ddot{x} + 3\dot{x} - 10x = f(t) \tag{1}$$

- (a) Determine the long term behavior of the differential equation when  $f(t) = 0$ .
- (b) Solve the initial value problem for the differential equation when  $f(t) = 21e^{2t}$ ,  $x(0) = 3$ , and  $\dot{x}(0) = 2$ .

**Solution:**

- (a) When  $f(t) = 0$ , we have

$$\ddot{x} + 3\dot{x} - 10x = 0$$

This differential equation has the characteristic polynomial

$$\lambda^2 + 3\lambda - 10 = 0$$

with solutions  $\lambda = -5, 2$

Given these eigenvalues, the solution to the differential equation will experience exponential growth as  $t \rightarrow \infty$ .

- (b) When  $f(t) = 3e^{2t}$ , we have

$$\ddot{x} + 3\dot{x} - 10x = 3e^{2t}$$

From above, we know that

$$x_h = c_1e^{-5t} + c_2e^{2t}$$

We can solve for the particular solution either via variation of parameters or undetermined coefficients.

The solution here will use undetermined coefficients. The particular solution is of the form

$$x_p = ate^{2t}$$

Substituting this form into the differential equation, we have

$$4ae^{2t} + 4ate^{2t} + 3ae^{2t} + 6ate^{2t} - 10ate^{2t} = 21e^{2t}$$

Thus,

$$7ae^{2t} = 21e^{2t} \text{ or } a = 3$$

Therefore,

$$x = x_h + x_p = c_1e^{-5t} + c_2e^{2t} + 3te^{2t}$$

Solving the initial value problem, we have

$$\begin{aligned}
x(0) &= c_1 + c_2 = 3 \\
\dot{x}(0) &= -5c_1 + 2c_2 + 3 = 2 \\
\text{so } c_1 &= 1 \text{ and } c_2 = 2. \\
\text{The solution is thus} \\
x &= e^{-5t} + 2e^{2t} + 3te^{2t}
\end{aligned}$$

**Problem 4:** (40 points) The following two parts are unrelated.

(a) Consider a series of tanks of brine (salt water) with the following properties:

- Tank A:
  - Size: 50 gallons
  - Outflow:
    - 10 gallons a minute to Tank B
    - 10 gallons a minute to Tank C
- Tank B:
  - Size: 30 gallons
  - Outflow:
    - 15 gallons a minute to Tank A
- Tank C:
  - Size: 35 gallons
  - Outflow:
    - 5 gallons a minute to Tank A
    - 5 gallons a minute to Tank B

Set up a system of differential equations to represent the change in salt levels in each tank. Do **NOT** solve this system.

(b) Provide the general solution for the following system of differential equations:

$$\vec{x}' = \begin{pmatrix} 2 & 8 \\ 2 & 2 \end{pmatrix} \vec{x}$$

**Solution:**

(a) The system can be represented by

$$\begin{bmatrix} A \\ B \\ C \end{bmatrix}' = \begin{bmatrix} -\frac{2}{5} & \frac{1}{2} & \frac{1}{7} \\ \frac{1}{5} & -\frac{1}{2} & \frac{1}{7} \\ \frac{1}{5} & 0 & -\frac{2}{7} \end{bmatrix} \begin{bmatrix} A \\ B \\ C \end{bmatrix}$$

(b) First we must find the eigenvalues of this system. The characteristic polynomial is

$$\det(A - \lambda I) = \lambda^2 - 4\lambda - 12 = 0$$

This has solutions  $\lambda_1 = -2, \lambda_2 = 6$

Now we need the eigenvectors of this system. Substituting and row reducing, we see that

$$\vec{v}_1 = \begin{bmatrix} 2 \\ -1 \end{bmatrix}, \vec{v}_2 = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

The solution to this system is therefore given by

$$\vec{x} = c_1 e^{-2t} \begin{bmatrix} 2 \\ -1 \end{bmatrix} + c_2 e^{6t} \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

**Problem 5:** (40 points)

Consider the set of vectors

$$\left\{ \vec{v}_1 = \begin{pmatrix} 1 \\ 2 \\ 4 \end{pmatrix}, \vec{v}_2 = \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}, \vec{v}_3 = \begin{pmatrix} 3 \\ 3 \\ 9 \end{pmatrix} \right\}$$

(a) Find a basis for  $\text{span}\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$ .

(b) Let  $A$  be the matrix with the vectors above as its columns, i.e., the  $i^{\text{th}}$  column of  $A$  is  $\vec{v}_i$ . What is the dimension of the column space of  $A$ ?

(c) Find a basis for and the dimension of the null space of the matrix  $A$  from part (b).

**Solution:**

(a)

$$\begin{pmatrix} 1 & 0 & 3 \\ 2 & 1 & 3 \\ 4 & 1 & 9 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & 3 \\ 0 & 1 & -3 \\ 0 & 0 & 0 \end{pmatrix}$$

Thus,  $\{\vec{v}_1, \vec{v}_2\}$  is a basis for  $\text{span}\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$ .

(b) By work in part (a), dimension is 2

(c) By work in part (a),  $x_1 = -3x_3$ ,  $x_2 = 3x_3$

$$\implies \vec{x} = x_3 \begin{pmatrix} -3 \\ 3 \\ 1 \end{pmatrix}$$

Table of Laplace Transforms.  $\mathcal{L}\{f(t)\} = F(s) = \int_0^\infty e^{-st} f(t) dt$  where  $f$  is of exponential order  $\alpha$

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$\mathcal{L}\{tf(t)\} = -\frac{d}{ds}F(s), s > 0$	$\mathcal{L}\{\sin bt\} = \frac{b}{s^2+b^2}, s > 0$	$\mathcal{L}\{\delta(t)\} = 1, s > 0$
$\mathcal{L}\{e^{at}f(t)\} = F(s-a), s > a$	$\mathcal{L}\{\cos bt\} = \frac{s}{s^2+b^2}, s > 0$	$\mathcal{L}\{f'(t)\} = sF(s) - f(0), s > \alpha$
$\mathcal{L}\{\text{step}(t)\} = \frac{1}{s}, s > 0$	$\mathcal{L}\{t^n\} = \frac{n!}{s^{n+1}}, s > 0$	$\mathcal{L}\{f''(t)\} = s^2F(s) - sf(0) - f'(0), s > \alpha$
$\mathcal{L}\{f(t-a)\text{step}(t-a)\} = e^{-as}F(s), s > a$	$\mathcal{L}\{e^{at}\} = \frac{1}{s-a}, s > a$	

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