

1. [2360/041724 (10 pts)] Write the word **TRUE** or **FALSE** as appropriate. No work need be shown. No partial credit given.

- (a) $7\ddot{x} + 6\dot{x} + e^x + \cos x = 0$ describes a conservative system.
- (b) If y_1, y_2, y_3 are solutions to a third order linear, homogeneous differential equation, then the solution space must be equal to $\text{span}\{y_1, y_2, y_3\}$.
- (c) $\mathcal{L}\{t \cosh t\} = \frac{s^2 + 1}{(s^2 - 1)^2}$
- (d) If the characteristic equation of the differential equation governing a forced oscillator is $2r^2 + 2r + 1 = 0$, and the oscillator is forced by $f(t) = 10 \cos\left(\frac{t}{2}\right)$, then the oscillator is in resonance.
- (e) If the charge in a circuit is given by $q(t) = e^{-4t}(\cos t + \sin t) + \frac{1}{2} \sin 2t - \frac{1}{2} \cos 2t$, then the value of the steady state charge when $t = \frac{\pi}{4}$ is $\frac{1}{2}$.

SOLUTION:

- (a) **FALSE** Due to the presence of the x term, the system is damped and therefore not conservative.
- (b) **FALSE** This will only be the case if $W[y_1, y_2, y_3](t)$ is not identically zero, that is, the functions must be linearly independent.
- (c) **TRUE**

$$\mathcal{L}\{t \cosh t\} = (-1)^1 \frac{d}{ds} \left(\frac{s}{s^2 - 1} \right) = -1 \left[\frac{(s^2 - 1)(1) - s(2s)}{(s^2 - 1)^2} \right] = \frac{s^2 + 1}{(s^2 - 1)^2}$$

- (d) **FALSE** Based on the characteristic equation, specifically the $2r$ term, the oscillator is damped and therefore cannot be in resonance.
- (e) **TRUE** The steady state part of the solution is $q_{ss}(t) = \frac{1}{2} \sin 2t - \frac{1}{2} \cos 2t$ which gives $q_{ss}\left(\frac{\pi}{4}\right) = \frac{1}{2} \sin 2\left(\frac{\pi}{4}\right) - \frac{1}{2} \cos 2\left(\frac{\pi}{4}\right) = \frac{1}{2}$. ■

2. [2360/041724 (24 pts)] Use variation of parameters to find the general solution of $t^2 u'' + tu' - 9u = 72(t + 1)$, assuming solutions of the associated homogeneous equation are of the form $u = t^r$. Be sure to simplify your final answer.

SOLUTION:

$$\begin{aligned} u = t^r &\implies u' = rt^{r-1} \implies u'' = r(r-1)t^{r-2} \\ t^2 u'' + tu' - 9u &= t^2 r(r-1)t^{r-2} + trt^{r-1} - 9t^r = (r^2 - 9)t^r = 0 \\ \implies (r+3)(r-3) = 0 &\implies r = 3, -3 \implies u_1 = t^3, u_2 = t^{-3} \implies u_h = c_1 t^3 + c_2 t^{-3} \\ W(t^3, t^{-3}) &= \begin{vmatrix} t^3 & t^{-3} \\ 3t^2 & -3t^{-4} \end{vmatrix} = -6t^{-1} \end{aligned}$$

The proper form of the nonhomogeneous term for use in variation of parameters is $\frac{72(t+1)}{t^2} = 72(t^{-1} + t^{-2})$.

$$\begin{aligned} v_1' &= \frac{-u_2 f}{W} = \frac{-t^{-3}(72)(t^{-1} + t^{-2})}{-6t^{-1}} = 12(t^{-3} + t^{-4}) \implies v_1 = \int 12(t^{-3} + t^{-4}) dt = -6t^{-2} - 4t^{-3} \\ v_2' &= \frac{u_1 f}{W} = \frac{t^3(72)(t^{-1} + t^{-2})}{-6t^{-1}} = -12(t^3 + t^2) \implies v_2 = \int -12(t^3 + t^2) dt = -3t^4 - 4t^3 \\ u_p &= v_1 u_1 + v_2 u_2 = (-6t^{-2} - 4t^{-3})t^3 + (-3t^4 - 4t^3)t^{-3} \\ &= -6t - 4 - 3t - 4 = -9t - 8 \\ u(t) &= u_h + u_p = c_1 t^3 + c_2 t^{-3} - 9t - 8 \end{aligned}$$
■

3. [2360/041724 (24 pts)] Consider the initial value problem $2\ddot{x} + 6\dot{x} + 4x = f(t)$, $x(0) = 1$, $\dot{x}(0) = -8$ describing a certain mass/spring harmonic oscillator.

- (a) (2 pts) Is the oscillator underdamped, overdamped or critically damped? Justify your answer.
- (b) (10 pts) Assuming that oscillator is unforced/undriven, $f(t) = 0$, determine if and when the mass will pass through the equilibrium position.
- (c) (10 pts) Suppose now that the oscillator is forced by $f(t) = 4e^{-t}$. Using the same initial conditions, use the Method of Undetermined Coefficients to find the position of the mass when $t = 2$.
- (d) (2 pts) Now suppose you have the ability to change the value of the mass, m , in the mass/spring system. Find all the values of m , if any, that will allow the mass to pass through its equilibrium position more than once, assuming the damping and restoring constants are their original values.

SOLUTION:

(a) Overdamped: $b^2 - 4mk = 6^2 - 4(2)(4) = 36 - 32 = 4 > 0$

(b) Solve the initial value problem.

$$2r^2 + 6r + 4 = 2(r^2 + 3r + 2) = 2(r + 2)(r + 1) = 0 \implies r = -2, -1$$

$$x(t) = c_1e^{-2t} + c_2e^{-t} \implies x(0) = c_1 + c_2 = 1$$

$$\dot{x}(t) = -2c_1e^{-2t} - c_2e^{-t} \implies \dot{x}(0) = -2c_1 - c_2 = -8$$

$$c_1 = \frac{\begin{vmatrix} 1 & 1 \\ -8 & -1 \end{vmatrix}}{\begin{vmatrix} 1 & 1 \\ -2 & -1 \end{vmatrix}} = 7 \quad c_2 = \frac{\begin{vmatrix} 1 & 1 \\ -2 & -8 \end{vmatrix}}{\begin{vmatrix} 1 & 1 \\ -2 & -1 \end{vmatrix}} = -6$$

$$x(t) = 7e^{-2t} - 6e^{-t}$$

Now see if there exists a t where the solution vanishes.

$$7e^{-2t} - 6e^{-t} = 0$$

$$e^{-2t}(7 - 6e^t) = 0$$

$$e^t = \frac{7}{6}$$

$$t = \ln \frac{7}{6}$$

The mass passes through the equilibrium position when $t = \ln \frac{7}{6}$.

(c) We need to find a particular solution.

$$x_p = Ate^{-t} \implies \dot{x}_p = Ae^{-t}(1 - t) \implies \ddot{x}_p = Ae^{-t}(t - 2)$$

$$2\ddot{x}_p + 6\dot{x}_p + 4x_p = 2Ae^{-t}(t - 2) + 6Ae^{-t}(1 - t) + 4Ate^{-t}$$

$$2Ate^{-t} - 4Ae^{-t} + 6Ae^{-t} - 6Ate^{-t} + 4Ate^{-t} = 2Ae^{-t} = 4e^{-t} \implies A = 2 \text{ and } x_p = 2te^{-t}$$

$$x(t) = x_h(t) + x_p(t) = c_1e^{-2t} + c_2e^{-t} + 2te^{-t}$$

$$x(0) = c_1 + c_2 = 1$$

$$\dot{x}(t) = -2c_1e^{-2t} - c_2e^{-t} - 2te^{-t} + 2e^{-t} \implies \dot{x}(0) = -2c_1 - c_2 + 2 = -8 \implies -2c_1 - c_2 = -10$$

$$c_1 = \frac{\begin{vmatrix} 1 & 1 \\ -10 & -1 \end{vmatrix}}{\begin{vmatrix} 1 & 1 \\ -2 & -1 \end{vmatrix}} = 9 \quad c_2 = \frac{\begin{vmatrix} 1 & 1 \\ -2 & -10 \end{vmatrix}}{\begin{vmatrix} 1 & 1 \\ -2 & -1 \end{vmatrix}} = -8$$

$$x(t) = 9e^{-2t} - 8e^{-t} + 2te^{-t}$$

When $t = 2$, the position of the mass is $x(2) = 9e^{-4} - 4e^{-2}$

(d) We need $b^2 - 4mk = 6^2 - 4m(4) = 36 - 16m < 0 \implies \frac{9}{4} < m$

4. [2360/041724 (22 pts)] This problem will consider the following initial value problem $y'' + 25y = 100e^{5t}$, $y(0) = -2$, $y'(0) = 3$.
- (a) (6 pts) Convert the initial value problem into a system of a first order equations with appropriate initial conditions, writing the system in the form $\vec{x}' = \mathbf{A}\vec{x} + \vec{f}$, if possible.
- (b) (6 pts) Find the partial fraction decomposition of $\frac{100}{(s-5)(s^2+25)}$. Make sure you do this correctly; it will be useful in the next part.
- (c) (10 pts) Use Laplace transforms to solve the initial value problem.

SOLUTION:

(a)

$$x_1 = y, \quad x_2 = y', \quad \vec{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$x_1' = y' = x_2, \quad x_2' = y'' = 100e^{5t} - 25x_1$$

$$\vec{x}' = \begin{bmatrix} 0 & 1 \\ -25 & 0 \end{bmatrix} \vec{x} + \begin{bmatrix} 0 \\ 100e^{5t} \end{bmatrix}, \quad \vec{x}(0) = \begin{bmatrix} -2 \\ 3 \end{bmatrix}$$

(b)

$$\frac{100}{(s-5)(s^2+25)} = \frac{A}{s-5} + \frac{Bs+C}{s^2+25}$$

$$100 = A(s^2+25) + (Bs+C)(s-5)$$

$$100 = (A+B)s^2 + (-5B+C)s + (25A-5C) \quad \text{equate coefficients}$$

$$A+B = 0 \implies A = -B$$

$$-5B+C = 0 \implies C = 5B$$

$$25A-5C = 100 \implies 5A-C = 20 \implies 5(-B)-5B = 20 \implies B = -2 \implies A = 2, C = -10$$

$$\frac{100}{(s-5)(s^2+25)} = \frac{2}{s-5} - \frac{2s+10}{s^2+25}$$

(c)

$$s^2Y(s) - sy(0) - y'(0) + 25Y(s) = \frac{100}{s-5}$$

$$(s^2+25)Y(s) = \frac{100}{s-5} - 2s + 3$$

$$Y(s) = \frac{100}{(s-5)(s^2+25)} - \frac{2s}{s^2+25} + \frac{3}{s^2+25}$$

$$= \frac{2}{s-5} - \frac{2s+10}{s^2+25} - \frac{2s}{s^2+25} + \frac{3}{s^2+25}$$

$$= \frac{2}{s-5} - \frac{4s}{s^2+25} - \frac{7}{s^2+25}$$

$$y(t) = \mathcal{L}^{-1} \left\{ \frac{2}{s-5} - \frac{4s}{s^2+25} - \frac{7}{5} \frac{5}{s^2+25} \right\}$$

$$= 2e^{5t} - 4 \cos 5t - \frac{7}{5} \sin 5t$$

5. [2360/041724 (20 pts) Consider the differential equation $y^{(6)} = 16y'' + f(t)$.

- (a) (10 pts) Find a basis for the solution space when $f(t) = 0$.
- (b) (10 pts) For each of the following functions $f(t)$, write down the form of the particular solution you would use to solve the nonhomogeneous equation using the Method of Undetermined Coefficients. Do not find the constants and write N/A if the method is not applicable.
- i. $f(t) = 3t(t - 4)$ ii. $f(t) = te^t + e^{-2t}$ iii. $f(t) = \cos t + \sin 3t$ iv. $f(t) = t \sin 2t$ v. $f(t) = \frac{\sin 2t}{e^{2t}}$

SOLUTION:

- (a) The homogeneous equation is $y^{(6)} - 16y'' = 0$ with characteristic equation

$$r^6 - 16r^2 = r^2(r^4 - 16) = r^2(r^2 - 4)(r^2 + 4) = r^2(r - 2)(r + 2)(r^2 + 4) = 0$$

$$\implies r = 0 \text{ (multiplicity 2), } r = -2, r = 2, r = 2i, r = -2i$$

$$\text{basis for solution space is } \{1, t, e^{2t}, e^{-2t}, \cos 2t, \sin 2t\}$$

- (b) i. $y_p = t^2(At^2 + Bt + C)$
 ii. $y_p = (At + B)e^t + Cte^{-2t}$
 iii. $y_p = A \cos t + B \sin t + C \cos 3t + D \sin 3t$
 iv. $y_p = t[(At + B) \sin 2t + (Ct + D) \cos 2t]$
 v. $y_p = Ae^{-2t} \sin 2t + Be^{-2t} \cos 2t$

