APPM 2360

- This exam is worth 150 points and has 9 questions.
- Show all work and simplify your answers! Answers with no justification will receive no points unless otherwise noted.
- Please begin each problem on a new page.
- DO NOT leave the exam until you have satisfactorily scanned and uploaded your exam to Gradescope.
- You are taking this exam in a proctored and honor code enforced environment. **NO** calculators, cell phones, or other electronic devices or the internet are permitted. You are allowed one 8.5"× 11" crib sheet with writing on both sides.

At the top of the page containing your answer to problem 1, write the following italicized statement and sign your name to it: *"I will abide by the CU Boulder Honor Code on this exam."* FAILURE TO INCLUDE THIS MAY RESULT IN A PENALTY.

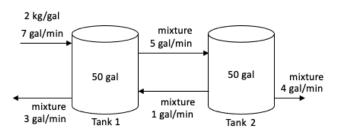
- 1. [2360/043022 (20 pts)] Solve the following initial value problem: $y'' + 3t^2 = 5\delta(t-2) + 6(t-4)$ step (t-4), y(0) = 2, y'(0) = 0.
- 2. [2360/043022 (15 pts)] Solve the system $\begin{cases} x + 2z = 1 \\ y 4z = 1 \\ x + z = 2 \end{cases}$ by using Gauss-Jordan elimination to find the inverse of an appropriate matrix.

No credit awarded if any other technique is used (e.g., RREF, Cramer's Rule).

- 3. [2360/043022 (18 pts)] Write the word TRUE or FALSE as appropriate. No work need be shown. No partial credit given.
 - (a) For invertible matrices A, B, and C, if AB = CA, then |B| = |C|.
 - (b) The space of all solutions to the differential equation $y'' (\cos t^2) y' + y 5t = 0$ forms a vector space (usual addition and scalar multiplication are assumed).
 - (c) A is a 3×4 matrix. When the system of linear equations $A\vec{x} = \vec{b}$ is consistent, then we must have infinitely many solutions. Here \vec{x} is a 4×1 column vector and \vec{b} is a 3×1 column vector.
 - (d) The equilibrium solution x = 1 of the differential equation x'(t) = x(1 x) is unstable.
 - (e) If f(t, y) is continuous everywhere, Picard's theorem guarantees that the differential equation y' = f(t, y) has a unique solution for any initial condition $y(t_0) = y_0$.
 - (f) If 1 is an eigenvalue of a 3×3 matrix ${\bf A},$ then ${\bf A}$ must be invertible.

(g) The function
$$f(t) = \begin{cases} 1 & t < 2 \\ e^t & 2 \le t < 3 \\ 2 & t \ge 3 \end{cases}$$
 can be written as $f(t) = 1 + (e^t - 1)\operatorname{step}(t - 2) + (2 - e^t)\operatorname{step}(t - 3)$.

- (h) The set of all 2×2 diagonal matrices is a dimension 4 subspace of $\mathbb{M}_{22}.$
- (i) If the functions $\{y_1(t), y_2(t), y_3(t)\}$ are all solutions to a third order linear homogeneous differential equation and $W[y_1, y_2, y_3](t) \equiv 0$, then the functions cannot form a basis for the solution solution space.
- 4. [2360/043022 (12 pts)] Two fifty gallon tanks are full of Kool-Aid[®] solution. Initially, Tank 1 contains 5 kg of dissolved Kool-Aid[®] powder and Tank 2 has 3 kg of dissolved Kool-Aid[®] powder in it. The well-stirred solution is pumped between the tanks as shown in the figure below. Construct, but **DO NOT SOLVE**, a mathematical model for the number of kilograms of Kool-Aid[®] powder $x_1(t)$ and $x_2(t)$ at time t in Tanks 1 and 2, respectively. Write your final answer using matrices and vectors.



- 5. [2360/043022 (15 pts)] Use the integrating factor method to solve the initial value problem $xy' + 3y = -4x^{-4}$, y(1) = -4 on the interval x > 0.
- 6. [2360/043022 (20 pts)] Solve the initial value problem $\vec{\mathbf{x}}' = \begin{bmatrix} 0 & 0 & 2 \\ 0 & 2 & 0 \\ 2 & 0 & 0 \end{bmatrix} \vec{\mathbf{x}}, \ \vec{\mathbf{x}}(0) = \begin{bmatrix} 2 \\ 2 \\ 6 \end{bmatrix}$. Write your final answer as a single vector.
- 7. [2360/043022 (12 pts)] Convert $t^2 y''' (\cos t)y' = 2$, y(0) = 3, y'(0) = -1, y''(0) = 4 with t > 0 into a system of first order differential equations. Write your final answer using matrices, if possible.

CONTINUED

8. [2360/043022 (20 pts)] Consider the linear system of differential equations given by $\vec{\mathbf{x}}' = \mathbf{A}\vec{\mathbf{x}}$ where $\mathbf{A} = \begin{bmatrix} a-1 & 1 \\ a-2 & 1 \end{bmatrix}$ (a is a real

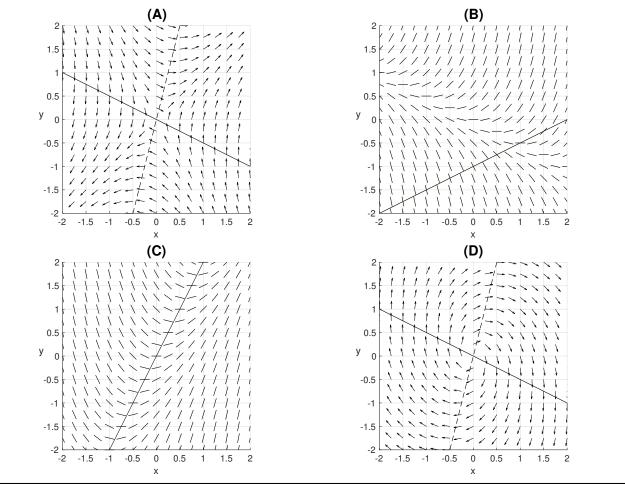
number) and with equilibrium solution $\vec{\mathbf{x}}_* = \begin{bmatrix} 0\\ 0 \end{bmatrix}$.

- (a) Is \vec{x}_* the only possible equilibrium solution? Justify your answer.
- (b) For what value(s) of a, if any, will the equilibrium solution $\vec{\mathbf{x}}_*$ be a saddle?
- (c) For what value(s) of a, if any, will the equilibrium solution $\vec{\mathbf{x}}_*$ be unstable?
- (d) For what value(s) of a, if any, will the equilibrium solution $\vec{\mathbf{x}}_*$ be an attracting node?
- 9. [2360/043022 (18 pts)] The following parts of this problem are related.
 - (a) In your bluebook, write the letters A-D. Next to each letter, write the Roman numeral corresponding to the equation or system depicted in each figure. Each letter corresponds to exactly one Roman numeral.

I.
$$x' = x - 2y$$

 $y' = 4x - y$ II. $x' = x + 2y$
 $y' = -4x + y$ III. $y' = x + 2y$ IV. $x' = x + 2y$
 $y' = 4x - y$ V. $y' = x - 2y$ VI. $y' = 2x - y$

- (b) What do the lines in graph A represent? Be sure to differentiate between solid and dashed in your answer.
- (c) What does the line in graph C represent?



Short table of Laplace Transforms: $\mathscr{L} \{f(t)\} = F(s) \equiv \int_0^\infty e^{-st} f(t) dt$ In this table, a, b, c are real numbers with $c \ge 0$, and n = 0, 1, 2, 3, ...

$$\begin{aligned} \mathscr{L}\left\{t^{n}e^{at}\right\} &= \frac{n!}{(s-a)^{n+1}} \qquad \mathscr{L}\left\{e^{at}\cos bt\right\} = \frac{s-a}{(s-a)^{2}+b^{2}} \qquad \mathscr{L}\left\{e^{at}\sin bt\right\} = \frac{b}{(s-a)^{2}+b^{2}} \\ &\qquad \mathscr{L}\left\{t^{n}f(t)\right\} = (-1)^{n}\frac{\mathrm{d}^{n}F(s)}{\mathrm{d}s^{n}} \qquad \mathscr{L}\left\{e^{at}f(t)\right\} = F(s-a) \qquad \mathscr{L}\left\{\delta(t-c)\right\} = e^{-cs} \\ &\qquad \mathscr{L}\left\{tf'(t)\right\} = -F(s) - s\frac{\mathrm{d}F(s)}{\mathrm{d}s} \qquad \mathscr{L}\left\{f(t-c)\operatorname{step}(t-c)\right\} = e^{-cs}F(s) \qquad \mathscr{L}\left\{f(t)\operatorname{step}(t-c)\right\} = e^{-cs}\mathscr{L}\left\{f(t+c)\right\} \\ &\qquad \mathscr{L}\left\{f^{(n)}(t)\right\} = s^{n}F(s) - s^{n-1}f(0) - s^{n-2}f'(0) - s^{n-3}f''(0) - \cdots - f^{(n-1)}(0) \end{aligned}$$