

1. [2360/030922 (10 pts)] Given the matrices

$$\mathbf{A} = \begin{bmatrix} 1 & 0 \\ 3 & 4 \\ -1 & -2 \end{bmatrix} \quad \mathbf{B} = \begin{bmatrix} 2 & -1 & -3 \\ 0 & 1 & 2 \end{bmatrix} \quad \mathbf{C} = [-1 \quad 4]$$

write the word **TRUE** or **FALSE** as appropriate. No work need be shown, no work will be graded and no partial credit will be given.

(a)  $\mathbf{CB} = \begin{bmatrix} -2 \\ 5 \\ 11 \end{bmatrix}$  (b)  $\text{Tr}(\mathbf{B}^T \mathbf{A}^T) = 2$  (c)  $\mathbf{A}^T \mathbf{A} = \mathbf{A} \mathbf{A}^T$  (d)  $|\mathbf{C}^T \mathbf{C} - 3\mathbf{I}| = -10$  (e)  $\mathbf{AB} - \mathbf{A}^T \mathbf{B}^T$  is not defined

**SOLUTION:**

(a) **FALSE**  $\mathbf{CB} = [-1 \quad 4] \begin{bmatrix} 2 & -1 & -3 \\ 0 & 1 & 2 \end{bmatrix} = [-2 \quad 5 \quad 11]$

(b) **TRUE**  $\text{Tr}(\mathbf{B}^T \mathbf{A}^T) = \text{Tr} \left( \begin{bmatrix} 2 & 0 \\ -1 & 1 \\ -3 & 2 \end{bmatrix} \begin{bmatrix} 1 & 3 & -1 \\ 0 & 4 & -2 \end{bmatrix} \right) = \text{Tr} \begin{bmatrix} 2 & 6 & -2 \\ -1 & 1 & -1 \\ -3 & -1 & -1 \end{bmatrix} = 2 + 1 - 1 = 2$

(c) **FALSE**  $\mathbf{A}^T \mathbf{A}$  is  $(2 \times 3)(3 \times 2) = 2 \times 2$  whereas  $\mathbf{A} \mathbf{A}^T$  is  $(3 \times 2)(2 \times 3) = 3 \times 3$  so they cannot be equal

(d) **FALSE**  $|\mathbf{C}^T \mathbf{C} - 3\mathbf{I}| = \left| \begin{bmatrix} -1 \\ 4 \end{bmatrix} [-1 \quad 4] - 3 \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right| = \left| \begin{bmatrix} 1 & -4 \\ -4 & 16 \end{bmatrix} - \begin{bmatrix} 3 & 0 \\ 0 & 3 \end{bmatrix} \right| = \left| \begin{bmatrix} -2 & -4 \\ -4 & 13 \end{bmatrix} \right| = -42$

(e) **TRUE**  $\mathbf{AB}$  is  $(3 \times 2)(2 \times 3) = 3 \times 3$  whilst  $\mathbf{A}^T \mathbf{B}^T$  is  $(2 \times 3)(3 \times 2) = 2 \times 2$  so the subtraction is not defined

2. [2360/030922 (12 pts)] Let  $\mathbf{A} = \begin{bmatrix} 0 & 0 & 3 \\ 0 & 3 & 0 \\ 3 & 0 & 0 \end{bmatrix}$ .

(a) (4 pts) Find the eigenvalues of  $\mathbf{A}$  and state the multiplicity (also known as the algebraic multiplicity) of each.

(b) (8 pts) Find the dimension of and a basis for the eigenspace associated with the eigenvalue whose (algebraic) multiplicity is greater than 1.

**SOLUTION:**

(a)

$$|\mathbf{A} - \lambda \mathbf{I}| = \begin{vmatrix} -\lambda & 0 & 3 \\ 0 & 3 - \lambda & 0 \\ 3 & 0 & -\lambda \end{vmatrix} = (3 - \lambda)(-1)^{2+2} \begin{vmatrix} -\lambda & 3 \\ 3 & -\lambda \end{vmatrix} = (3 - \lambda)(\lambda^2 - 9) = -(\lambda - 3)^2(\lambda + 3) = 0$$

Eigenvalues are  $\lambda = -3$  with algebraic multiplicity 1 and  $\lambda = 3$  with algebraic multiplicity 2.

(b) We need to solve the system  $(\mathbf{A} - 3\mathbf{I})\vec{v} = \mathbf{0}$ .

$$\left[ \begin{array}{ccc|c} -3 & 0 & 3 & 0 \\ 0 & 0 & 0 & 0 \\ 3 & 0 & -3 & 0 \end{array} \right] \xrightarrow{\text{RREF}} \left[ \begin{array}{ccc|c} 1 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] \implies \vec{v} = \begin{bmatrix} s \\ t \\ s \end{bmatrix} = s \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} + t \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \quad s, t \in \mathbb{R}$$

A basis for the eigenspace is  $\left\{ \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \right\}$  with a dimension of 2.

3. [2360/030922 (14 pts)] Let  $\vec{p}_1 = 1 + x^2$ ,  $\vec{p}_2 = x - x^2$ ,  $\vec{p}_3 = 2 + 2x + 4x^2$ . Show that  $\vec{p} = 3 + 4x - 2x^2$  is in  $\text{span}\{\vec{p}_1, \vec{p}_2, \vec{p}_3\}$  by writing  $\vec{p}$  as a linear combination of  $\vec{p}_1, \vec{p}_2, \vec{p}_3$ . Use Cramer's Rule and cofactor expansion to solve an appropriate linear system.

**SOLUTION:**

We need to find constants  $c_1, c_2, c_3$  such that  $c_1\vec{p}_1 + c_2\vec{p}_2 + c_3\vec{p}_3 = \vec{p}$  or

$$c_1(1 + x^2) + c_2(x - x^2) + c_3(2 + 2x + 4x^2) = 3 + 4x - 2x^2$$

Equating coefficients on each side yields the linear system

$$\begin{aligned} 1c_1 + 0c_2 + 2c_3 &= 3 \\ 0c_1 + 1c_2 + 2c_3 &= 4 \\ 1c_1 - 1c_2 + 4c_3 &= -2 \end{aligned}$$

or written using matrices as  $\mathbf{A}\vec{c} = \vec{b}$

$$\begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 2 \\ 1 & -1 & 4 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} 3 \\ 4 \\ -2 \end{bmatrix}$$

Cramer's Rule gives:

$$c_1 = \frac{\begin{vmatrix} 3 & 0 & 2 \\ 4 & 1 & 2 \\ -2 & -1 & 4 \end{vmatrix}}{\begin{vmatrix} 1 & 0 & 2 \\ 0 & 1 & 2 \\ 1 & -1 & 4 \end{vmatrix}} = \frac{3(-1)^{1+1} \begin{vmatrix} 1 & 2 \\ -1 & 4 \end{vmatrix} + 2(-1)^{1+3} \begin{vmatrix} 4 & 1 \\ -2 & -1 \end{vmatrix}}{1(-1)^{1+1} \begin{vmatrix} 1 & 2 \\ -1 & 4 \end{vmatrix} + 1(-1)^{3+1} \begin{vmatrix} 0 & 2 \\ 1 & 2 \end{vmatrix}} = \frac{14}{4} = \frac{7}{2}$$

$$c_2 = \frac{\begin{vmatrix} 1 & 3 & 2 \\ 0 & 4 & 2 \\ 1 & -2 & 4 \end{vmatrix}}{4} = \frac{1(-1)^{1+1} \begin{vmatrix} 4 & 2 \\ -2 & 4 \end{vmatrix} + 1(-1)^{3+1} \begin{vmatrix} 3 & 2 \\ 4 & 2 \end{vmatrix}}{4} = \frac{18}{4} = \frac{9}{2}$$

$$c_3 = \frac{\begin{vmatrix} 1 & 0 & 3 \\ 0 & 1 & 4 \\ 1 & -1 & -2 \end{vmatrix}}{4} = \frac{1(-1)^{1+1} \begin{vmatrix} 1 & 4 \\ -1 & -2 \end{vmatrix} + 1(-1)^{3+1} \begin{vmatrix} 0 & 3 \\ 1 & 4 \end{vmatrix}}{4} = -\frac{1}{4}$$

Thus,  $\vec{p} = \frac{7}{2}\vec{p}_1 + \frac{9}{2}\vec{p}_2 - \frac{1}{4}\vec{p}_3$ . ■

4. [2360/030922 (14 pts)] Let  $\mathbf{A} = \begin{bmatrix} 2 & 0 & 1 \\ 0 & 1 & 0 \\ 3 & 0 & 1 \end{bmatrix}$ . NO credit will be given if Gauss-Jordan elimination is used.

(a) (5 pts) Using only matrix multiplication, verify that  $\mathbf{B} = \begin{bmatrix} -1 & 0 & 1 \\ 0 & 1 & 0 \\ 3 & 0 & -2 \end{bmatrix}$  is the inverse of  $\mathbf{A}$ .

(b) (9 pts) Using only matrix multiplication and properties of the matrix inverse and transpose, solve  $\mathbf{A}^T \mathbf{A} \vec{x} = \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix}$ .

**SOLUTION:**

(a)

$$\mathbf{AB} = \begin{bmatrix} 2 & 0 & 1 \\ 0 & 1 & 0 \\ 3 & 0 & 1 \end{bmatrix} \begin{bmatrix} -1 & 0 & 1 \\ 0 & 1 & 0 \\ 3 & 0 & -2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \mathbf{I} \quad \text{or} \quad \mathbf{BA} = \begin{bmatrix} -1 & 0 & 1 \\ 0 & 1 & 0 \\ 3 & 0 & -2 \end{bmatrix} \begin{bmatrix} 2 & 0 & 1 \\ 0 & 1 & 0 \\ 3 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \mathbf{I}$$

(b)

$$\begin{aligned}\mathbf{A}^T \mathbf{A} \vec{x} &= \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix} \\ (\mathbf{A}^T)^{-1} \mathbf{A}^T \mathbf{A} \vec{x} &= (\mathbf{A}^T)^{-1} \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix} && \text{Note: } (\mathbf{A}^T)^{-1} \mathbf{A}^T = \mathbf{I} \text{ and } \mathbf{I} \mathbf{A} = \mathbf{A} \\ \mathbf{A} \vec{x} &= (\mathbf{A}^T)^{-1} \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix} \\ \mathbf{A}^{-1} \mathbf{A} \vec{x} &= \mathbf{A}^{-1} (\mathbf{A}^T)^{-1} \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix} && \text{Note: } \mathbf{A}^{-1} \mathbf{A} = \mathbf{I} \text{ and } \mathbf{I} \vec{x} = \vec{x} \\ \vec{x} &= \mathbf{A}^{-1} (\mathbf{A}^{-1})^T \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix} && \text{Note: } (\mathbf{A}^T)^{-1} = (\mathbf{A}^{-1})^T \\ \vec{x} &= \begin{bmatrix} -1 & 0 & 1 \\ 0 & 1 & 0 \\ 3 & 0 & -2 \end{bmatrix} \begin{bmatrix} -1 & 0 & 3 \\ 0 & 1 & 0 \\ 1 & 0 & -2 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix} \\ \vec{x} &= \begin{bmatrix} 2 & 0 & -5 \\ 0 & 1 & 0 \\ -5 & 0 & 13 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix} = \begin{bmatrix} 7 \\ 2 \\ -18 \end{bmatrix}\end{aligned}$$

5. [2360/030922 (12 pts)] Determine if each of the following sets of vectors forms a basis for  $\mathbb{R}^3$ . Justify your answers.

$$(a) \left\{ \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix}, \begin{bmatrix} 3 \\ -1 \\ 1 \end{bmatrix} \right\} \quad (b) \left\{ \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix}, \begin{bmatrix} 3 \\ -1 \\ 1 \end{bmatrix}, \begin{bmatrix} -3 \\ 8 \\ -2 \end{bmatrix} \right\}$$

**SOLUTION:**

Note that the dimension of  $\mathbb{R}^3$  is 3 so a basis consists of 3 linearly independent vectors.

- (a) The set contains only 2 vectors and thus cannot form a basis for  $\mathbb{R}^3$  regardless of the linear dependence or independence of the vectors in the set.
- (b) Three vectors in  $\mathbb{R}^3$  can potentially be a basis if they are linearly independent. To check for this, we need to see if the only solution to

$$c_1 \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix} + c_2 \begin{bmatrix} 3 \\ -1 \\ 1 \end{bmatrix} + c_3 \begin{bmatrix} -3 \\ 8 \\ -2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \iff \begin{bmatrix} 1 & 3 & -3 \\ 2 & -1 & 8 \\ 0 & 1 & -2 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

is the trivial solution. The determinant of the coefficient matrix is

$$\begin{vmatrix} 1 & 3 & -3 \\ 2 & -1 & 8 \\ 0 & 1 & -2 \end{vmatrix} = 1(-1)^{1+1} \begin{vmatrix} -1 & 8 \\ 1 & -2 \end{vmatrix} + 2(-1)^{2+1} \begin{vmatrix} 3 & -3 \\ 1 & -2 \end{vmatrix} = 1(1)(-6) + 2(-1)(-3) = 0$$

implying that the system has nontrivial solutions, further implying that the vectors are linearly dependent and thus cannot form a basis for  $\mathbb{R}^3$ .

6. [2360/030922 (24 pts)] The following parts are unrelated.

(a) (12 pts) Find the RREF of  $\mathbf{A} = \begin{bmatrix} 1 & 3 & 1 & 9 \\ 1 & 1 & -1 & 1 \\ 3 & 11 & 5 & 35 \end{bmatrix}$ .

- (b) (12 pts) We need to solve the system  $\mathbf{A}\vec{x} = \vec{b}$ . After a number of elementary row operations, the augmented matrix for the system is

$$\left[ \begin{array}{ccccc|c} 1 & 0 & 0 & 0 & 3 & 5 \\ 0 & 1 & 3 & 0 & -2 & 4 \\ 0 & 0 & 0 & 1 & -2 & -1 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

- i. (10 pts) Use this and the Nonhomogeneous Principle to find the solution to the original system.  
 ii. (2 pts) Find the dimension of the solution space of the original associated homogeneous system,  $\mathbf{A}\vec{x} = \vec{0}$ . Hint: You have the information you need from part (i); very little additional work is required.

**SOLUTION:**

(a)

$$\left[ \begin{array}{cccc|c} 1 & 3 & 1 & 9 & 5 \\ 1 & 1 & -1 & 1 & 4 \\ 3 & 11 & 5 & 35 & -1 \end{array} \right] \begin{array}{l} R_2^* = -1R_1 + R_2 \\ R_3^* = -3R_1 + R_3 \end{array} \left[ \begin{array}{cccc|c} 1 & 3 & 1 & 9 & 5 \\ 0 & -2 & -2 & -8 & -4 \\ 0 & 2 & 2 & 8 & -8 \end{array} \right] \begin{array}{l} R_3^* = R_2 + R_3 \\ R_2^* = -\frac{1}{2}R_2 \end{array} \left[ \begin{array}{cccc|c} 1 & 3 & 1 & 9 & 5 \\ 0 & 1 & 1 & 4 & -2 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right] R_1^* = -3R_2 + R_1 \left[ \begin{array}{cccc|c} 1 & 0 & -2 & -3 & 11 \\ 0 & 1 & 1 & 4 & -2 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

- (b) i. Pivot columns correspond to  $x_1, x_2, x_4$  so these are basic variables with  $x_3$  and  $x_5$ , corresponding to the nonpivot columns, being free variables. Setting  $x_3 = s$  and  $x_5 = t$ , solutions have the form

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} 5 - 3t \\ 4 - 3s + 2t \\ s \\ -1 + 2t \\ t \end{bmatrix} = \begin{bmatrix} 5 \\ 4 \\ 0 \\ -1 \\ 0 \end{bmatrix} + s \begin{bmatrix} 0 \\ -3 \\ 1 \\ 0 \\ 0 \end{bmatrix} + t \begin{bmatrix} -3 \\ 2 \\ 0 \\ 2 \\ 1 \end{bmatrix} \quad \text{where } s, t \in \mathbb{R}$$

$$= \vec{x}_p + \vec{x}_h$$

- ii. A basis for the solution space of the associated homogeneous system is  $\left\{ \begin{bmatrix} 0 \\ -3 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -3 \\ 2 \\ 0 \\ 2 \\ 1 \end{bmatrix} \right\}$ , containing two linearly independent vectors so its dimension is 2.

7. [2360/030922 (14 pts)] Determine if the subsets,  $\mathbb{W}$ , are subspaces of the given vector spaces,  $\mathbb{V}$ .

- (a) (7 pts)  $\mathbb{V} = \mathbb{M}_{22}$ ;  $\mathbb{W} = \left\{ \mathbf{A} \in \mathbb{M}_{22}, \mathbf{A}^T = -\mathbf{A} \right\}$ , the set of all matrices of the form  $\begin{bmatrix} 0 & k \\ -k & 0 \end{bmatrix}$  where  $k$  is a real number.

- (b) (7 pts)  $\mathbb{V} = \mathbb{R}^3$ ;  $\mathbb{W} = \left\{ \vec{v} \in \mathbb{R}^3 \mid \vec{v} = \begin{bmatrix} p+q \\ r \\ s \end{bmatrix} \text{ where } p, q, r, s \in \mathbb{R} \text{ and } s \geq 0 \right\}$

**SOLUTION:**

- (a) Clearly  $\vec{0} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \in \mathbb{W}$ . Let  $\vec{u} = \begin{bmatrix} 0 & u \\ -u & 0 \end{bmatrix} \in \mathbb{W}$  and  $\vec{v} = \begin{bmatrix} 0 & v \\ -v & 0 \end{bmatrix} \in \mathbb{W}$  and  $p, q \in \mathbb{R}$ . Then

$$p\vec{u} + q\vec{v} = p \begin{bmatrix} 0 & u \\ -u & 0 \end{bmatrix} + q \begin{bmatrix} 0 & v \\ -v & 0 \end{bmatrix} = \begin{bmatrix} 0 & pu \\ -pu & 0 \end{bmatrix} + \begin{bmatrix} 0 & qv \\ -qv & 0 \end{bmatrix} = \begin{bmatrix} 0 & pu + qv \\ -pu - qv & 0 \end{bmatrix} = \begin{bmatrix} 0 & pu + qv \\ -(pu + qv) & 0 \end{bmatrix} \in \mathbb{W}$$

since

$$\begin{bmatrix} 0 & pu + qv \\ -(pu + qv) & 0 \end{bmatrix}^T = \begin{bmatrix} 0 & -(pu + qv) \\ pu + qv & 0 \end{bmatrix} = - \begin{bmatrix} 0 & pu + qv \\ -(pu + qv) & 0 \end{bmatrix}$$

The set is closed under linear combinations and thus is a subspace.

Alternatively, let  $\mathbf{A}, \mathbf{B} \in \mathbb{W}$  and  $\alpha, \beta \in \mathbb{R}$ . Let  $\mathbf{C} = \alpha\mathbf{A} + \beta\mathbf{B}$ . Then

$$\mathbf{C}^T = (\alpha\mathbf{A} + \beta\mathbf{B})^T = \alpha\mathbf{A}^T + \beta\mathbf{B}^T = -\alpha\mathbf{A} - \beta\mathbf{B} = -(\alpha\mathbf{A} + \beta\mathbf{B}) = -\mathbf{C}.$$

Therefore  $\mathbf{C} \in \mathbb{W}$ , so by the Vector Subspace Theorem,  $\mathbb{W}$  is a subspace of  $\mathbb{V}$ .

(b) Let  $\vec{v} = \begin{bmatrix} p+q \\ r \\ s \end{bmatrix} \in \mathbb{W}$  with  $s > 0$ . Then  $-1\vec{v} = \begin{bmatrix} -p-q \\ -r \\ -s \end{bmatrix} \notin \mathbb{W}$  since  $-s < 0$ . This implies that  $\mathbb{W}$  is not closed under scalar multiplication and thus is not a subspace.

