

ON THE FRONT OF YOUR BLUEBOOK write: (1) your name, (2) your instructor's name, (3) your lecture section number and (4) a grading table for **six** problems. Text books, class notes, cell phones and calculators are NOT permitted. A one page (letter sized **two sided**) crib sheet is allowed.

**Problem 1** (40 points). Calculate the solutions to the following initial value problems.

(a)  $y' = y^2$ ,  $y(0) = 1$ . At what time does the solution become infinite?

(b)  $y' = -\frac{2}{t}y - 2$ ,  $y(1) = 1$ .

(c)  $y' = \frac{1}{t}y + y^3$ ,  $y(1) = 1$ . Hint: Let  $u = y^{-2}$ , then find and solve ODE satisfied by  $u$ .

**Solution:**

(a) Solve by Separation of Variables:

$$y' = y^2 \Rightarrow \int y^{-2} dy = \int dt \Rightarrow -y^{-1} = t + C$$

$y(0) = 1$  implies  $C = -1$  such that

$$y^{-1} = 1 - t \Rightarrow y(t) = \frac{1}{1 - t}.$$

Solution becomes infinite at  $t = 1$ .

(b) By **Integrating Factors**  $p(t) = 2/t$

$$\mu = e^{\int p(t)dt} = e^{\int \frac{2}{t} dt} = e^{2 \ln t} = t^2.$$

Multiplication by I.F.

$$t^2 \left( y' + \frac{2}{t}y \right) = -2t^2 \Rightarrow (t^2 y)' = -2t^2 \Rightarrow t^2 y(t) = -\frac{2}{3}t^3 + C \Rightarrow y(t) = -\frac{2}{3}t + \frac{C}{t^2}$$

Initial value  $y(1) = 1$  implies  $C = 5/3$ , such that

$$y(t) = -\frac{2}{3}t + \frac{5}{3} \frac{1}{t^2}.$$

By two-stage **Euler-Lagrange** (i.e. Variation of Parameters).

(i) Homogeneous solution:

$$y' = -\frac{2}{t}y \Rightarrow \int \frac{1}{y} dy = -\int \frac{2}{t} dt \Rightarrow \ln |y| = -2 \ln |t| + C \Rightarrow y_h(t) = \frac{C}{t^2}$$

(ii) Variation of Parameters:

$$y_p(t) = \frac{v(t)}{t^2} \Rightarrow \frac{1}{t^2} \frac{dv}{dt} = -2 \Rightarrow \frac{dv}{dt} = -2t^2 \Rightarrow v(t) = -\frac{2}{3}t^3 \Rightarrow y_p(t) = -\frac{2}{3}t$$

Again, initial value  $y(1) = 1$  implies  $C = 5/3$ , such that

$$y(t) = -\frac{2}{3}t + \frac{5}{3} \frac{1}{t^2}.$$

(c) Let  $u = y^{-2}$ . The initial value  $y(1) = 1$  converts to  $u(1) = 1$ . Then

$$\frac{du}{dt} = \frac{dy^{-2}}{dt} = -\frac{2}{y^3} \frac{dy}{dt} = -\frac{2}{y^3} \left( \frac{1}{t}y + y^3 \right) = -\frac{2}{t} \frac{1}{y^2} - 2 = -\frac{2}{t}u - 2$$

Thus the IVP satisfied by  $u$  is

$$\frac{du}{dt} = -\frac{2}{t}u - 2, \quad u(1) = 1.$$

This is the same ODE as in part (b), so we find  $u(t) = -\frac{2}{3}t + \frac{5}{3} \frac{1}{t^2}$ . Since  $u = y^{-2}$  we then find

$$y(t) = u^{-1/2} = \left[ -\frac{2}{3}t + \frac{5}{3} \frac{1}{t^2} \right]^{-1/2}$$

**Problem 2** (40 points) A tank initially contains 100 gallons of water in which 300 grams of an impurity are dissolved. Water containing the same impurity at a concentration of 2 grams per gallon enters the tank at a rate of 2 gallons per minute. Simultaneously, the well-mixed solution in the tank is pumped out at a rate of 4 gallons per minute. Let  $A(t)$  denote the amount of the impurity in the tank at time  $t$ .

- What is the equation for the volume,  $V(t)$ , of fluid in the tank. At what time,  $t$ , does the tank become empty?
- Write an initial value problem that describes the amount of the impurity in the tank,  $A(t)$ .
- Solve the initial value problem from part (b).
- What is the amount of the impurity in the tank at  $t = 25$  minutes.

**Solution:**

- The volume of solution in the tank as a function of time is

$$V(t) = 100 + (2 - 4)t = 100 - 2t$$

- The tank becomes empty when  $t = 50$  minutes, so we are interested in values of  $t$  satisfying  $0 \leq t \leq 50$ .
- We let  $A(t)$  be the amount of dissolved impurity at time  $t$ . Then

$$\frac{dA}{dt} = \text{Rate in} - \text{Rate out} = \left( 2 \frac{\text{g}}{\text{gal}} \right) \left( 2 \frac{\text{gal}}{\text{min}} \right) - \left( \frac{A}{100 - 2t} \frac{\text{g}}{\text{gal}} \right) \left( 4 \frac{\text{gal}}{\text{min}} \right)$$

leading to the initial value problem (with first order linear differential equation)

$$\frac{dA}{dt} + \frac{4A}{100 - 2t} = 4 \quad A(0) = 300$$

- We will solve with integrating factors. The integrating factor for this is obtained as

$$\int \frac{4}{100 - 2t} dt = -2 \ln |100 - 2t| \implies \mu(t) = (100 - 2t)^{-2}$$

yielding

$$\int \left[ (100 - 2t)^{-2} A \right]' dt = (100 - 2t)^{-2} A = \int 4(100 - 2t)^{-2} dt = 2(100 - 2t)^{-1} + C$$

$$A(t) = 2(100 - 2t) + C(100 - 2t)^2$$

Applying the initial condition gives

$$A(0) = 200 + C(100^2) = 300 \implies C = \frac{1}{100}$$

and finally

$$\begin{aligned} A(t) &= 2(100 - 2t) + \frac{1}{100}(100 - 2t)^2 \\ &= (100 - 2t) \left[ 2 + \frac{1}{100}(100 - 2t) \right] \\ &= (100 - 2t) \left( 3 - \frac{1}{50}t \right) \\ &= 300 - 8t + \frac{1}{25}t^2, \quad 0 \leq t \leq 50 \end{aligned}$$

(d) The amount of impurity in the water at  $t = 25$  is given by

$$\begin{aligned} A(25) &= 2(100 - 2(25)) + \frac{1}{100}(100 - 2(25))^2 \\ &= 2(50) + \frac{1}{100}(50)^2 \\ &= 100 + 25 \\ &= 125 \text{ grams} \end{aligned}$$

**Problem 3** (45 points) The following are unrelated.

- (a) Calculate the inverse to  $\mathbf{A} = \begin{bmatrix} 1 & 1 & 1 \\ 0 & -1 & 1 \\ -1 & 0 & 1 \end{bmatrix}$ .
- (b) In the following problems,  $\mathbb{W}$  is a subset of a vector space  $\mathbb{V}$ . Determine whether  $\mathbb{W}$  is a vector subspace of  $\mathbb{V}$ . If  $\mathbb{W}$  is a vector subspace, prove it. Otherwise provide an explanation or counterexample to show why  $\mathbb{W}$  does not form a vector subspace of  $\mathbb{V}$ . No credit will be given for responses without justification.
- (i)  $\mathbb{V} = \mathbb{M}_{33}$  (set of all  $3 \times 3$  matrices).  $\mathbb{W}$ : All  $3 \times 3$  matrices with  $\text{Tr}(A) = 0$ . (Recall  $\text{Tr}(A)$  is the sum of the diagonal elements of a matrix  $A$ ).
- (ii)  $\mathbb{V} = \mathbb{M}_{22}$  (set of all  $2 \times 2$  matrices).  $\mathbb{W}$ : all  $2 \times 2$  matrices with zero determinant.
- (iii)  $\mathbb{V} = \mathbb{P}_2$  (set of all polynomials of degree  $\leq 2$ ).  $\mathbb{W}$ : all quadratic polynomials,  $p(x)$ , with  $x = 2$  as a root.
- (c) (i) Give the definition for a set of functions  $\{f_1, f_2, \dots, f_n\}$  to be linearly independent.  
(ii) Determine what the Wronskian tells about the linear dependence (or independence) of the functions  $\{1, \cos^2 t, \sin^2 t\}$ .

**Solution:**

- (a) To find the inverse, we augment  $\mathbf{A}$  with the identity matrix and then carry out row operations until we obtain the identity matrix in the left half, for example as follows

$$\begin{aligned} & \left[ \begin{array}{ccc|ccc} 1 & 1 & 1 & 1 & 0 & 0 \\ 0 & -1 & 1 & 0 & 1 & 0 \\ -1 & 0 & 1 & 0 & 0 & 1 \end{array} \right] \\ & \xrightarrow{R_3^* = R_3 + R_1} \left[ \begin{array}{ccc|ccc} 1 & 1 & 1 & 1 & 0 & 0 \\ 0 & -1 & 1 & 0 & 1 & 0 \\ 0 & 1 & 2 & 1 & 0 & 1 \end{array} \right] \\ & \xrightarrow{R_2^* = R_2 + R_3} \left[ \begin{array}{ccc|ccc} 1 & 1 & 1 & 1 & 0 & 0 \\ 0 & 0 & 3 & 1 & 1 & 1 \\ 0 & 1 & 2 & 1 & 0 & 1 \end{array} \right] \\ & \xrightarrow{R_2/3} \left[ \begin{array}{ccc|ccc} 1 & 1 & 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1/3 & 1/3 & 1/3 \\ 0 & 1 & 2 & 1 & 0 & 1 \end{array} \right] \\ & \xrightarrow{R_3 - 2R_2} \left[ \begin{array}{ccc|ccc} 1 & 1 & 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1/3 & 1/3 & 1/3 \\ 0 & 1 & 0 & 1/3 & -2/3 & 1/3 \end{array} \right] \\ & \xrightarrow{R_1^* = R_1 - R_3} \left[ \begin{array}{ccc|ccc} 1 & 0 & 1 & 2/3 & 2/3 & -1/3 \\ 0 & 0 & 1 & 1/3 & 1/3 & 1/3 \\ 0 & 1 & 0 & 1/3 & -2/3 & 1/3 \end{array} \right] \\ & \xrightarrow{R_1^* = R_1 - R_2} \left[ \begin{array}{ccc|ccc} 1 & 0 & 0 & 1/3 & 1/3 & -2/3 \\ 0 & 0 & 1 & 1/3 & 1/3 & 1/3 \\ 0 & 1 & 0 & 1/3 & -2/3 & 1/3 \end{array} \right] \\ & \text{swap } R_2 \leftrightarrow R_3 \left[ \begin{array}{ccc|ccc} 1 & 0 & 0 & 1/3 & 1/3 & -2/3 \\ 0 & 1 & 0 & 1/3 & -2/3 & 1/3 \\ 0 & 0 & 1 & 1/3 & 1/3 & 1/3 \end{array} \right] \end{aligned}$$

Therefore

$$\mathbf{A}^{-1} = \begin{bmatrix} 1/3 & 1/3 & -2/3 \\ 1/3 & -2/3 & 1/3 \\ 1/3 & 1/3 & 1/3 \end{bmatrix} = \frac{1}{3} \begin{bmatrix} 1 & 1 & -2 \\ 1 & -2 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$

- (b) Vector spaces

(i) Consider general  $3 \times 3$  matrices

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}, \quad B = \begin{bmatrix} b_{11} & b_{12} & b_{13} \\ b_{21} & b_{22} & b_{23} \\ b_{31} & b_{32} & b_{33} \end{bmatrix}$$

with zero trace, so  $a_{11} + a_{22} + a_{33} = b_{11} + b_{22} + b_{33} = 0$ . To verify that  $\mathbb{W}$  is a subspace, then we verify the following

Closure under scalar multiplication:  $\text{Tr}(cA) = c(a_{11} + a_{22} + a_{33}) = 0$

Closure under addition:

$$\begin{aligned} \text{Tr}(A + B) &= a_{11} + b_{11} + a_{22} + b_{22} + a_{33} + b_{33} \\ &= (a_{11} + a_{22} + a_{33}) + (b_{11} + b_{22} + b_{33}) \\ &= 0 + 0. \end{aligned}$$

Since the subset is closed under scalar multiplication and addition, then  $\mathbb{W}$  is a vector subspace.

(ii)  $\mathbb{W}$  is not a vector subspace. Consider

$$M_1 = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \quad M_2 = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$

so  $M_1, M_2 \in \mathbb{W}$ . However, their sum

$$M_1 + M_2 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

has determinant 1 so  $\mathbb{W}$  is not closed under addition and hence not a vector

(iii) A quadratic polynomial with root  $x = 2$  can be factored into the form

$$p(x) = k(x - 2)(x - x_0),$$

where  $k$  and  $x_0$  are arbitrary real constants. Now we need to verify closure under scalar multiplication and addition. Let  $p_1(x) = k_1(x - 2)(x - x_1)$  and  $p_2(x) = k_2(x - 2)(x - x_2)$ .

Closure under scalar multiplication: if we multiply  $p_1(x)$  by any constant  $c$ , we have

$$cp_1(x) = ck(x - 2)(x - x_1) \in \mathbb{W},$$

so the set is closed under scalar multiplication.

Closure under addition:

$$\begin{aligned} p_1(x) + p_2(x) &= k_1(x - 2)(x - x_1) + k_2(x - 2)(x - x_2) \\ &= (x - 2)(k_1(x - x_1) + k_2(x - x_2)) \in \mathbb{W}, \end{aligned}$$

so the set is closed under addition.

Therefore  $\mathbb{W}$  is a vector subspace of  $\mathbb{V}$ .

(c) (i) The functions are linearly independent if and only if the relation

$$c_1 f_1(t) + c_2 f_2(t) + \dots + c_n f_n(t) = 0$$

implies that all the constants are zero.

(ii) The Wronskian is

$$\begin{aligned} W &= \begin{vmatrix} 1 & \sin^2 t & \cos^2 t \\ 0 & 2 \sin t \cos t & -2 \sin t \cos t \\ 0 & 2(\cos^2 t - \sin^2 t) & -2(\cos^2 t - \sin^2 t) \end{vmatrix} \\ &= 1 \begin{vmatrix} 2 \sin t \cos t & -2 \sin t \cos t \\ 2(\cos^2 t - \sin^2 t) & -2(\cos^2 t - \sin^2 t) \end{vmatrix} \\ &= 1 [(2 \sin t \cos t)(-2(\cos^2 t - \sin^2 t)) - (-2 \sin t \cos t)(2(\cos^2 t - \sin^2 t))] \\ &= 4 [-\sin t \cos t(\cos^2 t - \sin^2 t) + \sin t \cos t(\cos^2 t - \sin^2 t)] \\ &= 0 \end{aligned}$$

Since the Wronskian is 0, then the test is inconclusive.

**Problem 4** (40 points) Solve the initial value problem

$$\begin{aligned}y'' - 2y' + y &= te^t \\ y(0) &= 0 \quad y'(0) = 1,\end{aligned}$$

using the variation of parameters method. At most half credit will be awarded if an alternative method is used.

**Solution:** We first find the homogeneous solution.

$$y'' - 2y' + y = 0,$$

which has the characteristic polynomial

$$r^2 - 2r + 1$$

upon seeking a solution  $e^{rt}$ . The roots of the characteristic polynomial are

$$r = 1 \quad \text{with multiplicity 2.}$$

Therefore the homogeneous solution is

$$y(t) = c_1 e^t + c_2 t e^t.$$

The two linearly independent solutions are

$$\begin{aligned}y_1 &= e^t, \\ y_2 &= t e^t.\end{aligned}$$

The Wronskian of the linearly independent solutions is

$$\begin{aligned}W[y_1, y_2] &= \begin{vmatrix} e^t & t e^t \\ e^t & e^t + t e^t \end{vmatrix} \\ &= e^t (e^t + t e^t) - t e^{2t} \\ &= e^{2t}\end{aligned}$$

We seek the particular solution to be

$$y(t) = v_1(t)y_1 + v_2(t)y_2, \tag{1}$$

$$\begin{aligned}v_1' &= -\frac{y_2 f}{W[y_1, y_2]}, \\ v_2' &= \frac{y_1 f}{W[y_1, y_2]},\end{aligned}$$

where  $f = te^t$ . Integrating, we find

$$\begin{aligned}v_1 &= -\int \frac{(te^t)(te^t)}{e^{2t}} dt \\ &= -\int t^2 dt \\ &= -\frac{1}{3}t^3 \\ v_2 &= \int \frac{e^t(te^t)}{e^{2t}} dt \\ &= \int t dt \\ &= \frac{1}{2}t^2\end{aligned}$$

Together, these give the particular solution

$$\begin{aligned}y_p &= -\frac{1}{3}t^3(e^t) + \frac{1}{2}t^2(te^t) \\ &= \frac{1}{6}t^3 e^t\end{aligned}$$

The general solution is then given by

$$y(t) = c_1 e^t + c_2 t e^t + \frac{1}{6} t^3 e^t$$

Applying the initial conditions, we have

$$y(0) = c_1 = 0$$

$$y'(0) = c_2 = 1,$$

therefore, the solution to the IVP is

$$y(t) = t e^t + \frac{1}{6} t^3 e^t$$

**Problem 5** (40 points) In this problem we will solve the initial value problem

$$y' - y = f(t), \quad y(0) = -1.$$

Use **Laplace transforms** to solve the initial value problem with the following forcing functions:

- (a)  $f(t) = 5 \cos(2t)$
- (b)  $f(t) = e^{-t} \text{step}(t - 2)$

**Solution:**

- (a) Taking the Laplace transform of all terms in the equation we have

$$\begin{aligned} \mathcal{L}\{y'\} &= sY(s) + 1 \\ \mathcal{L}\{y\} &= Y(s) \\ \mathcal{L}\{5 \cos 2t\} &= \frac{5s}{s^2 + 4} \end{aligned}$$

So the equation for  $Y(s)$  is

$$\begin{aligned} sY(s) + 1 - Y(s) &= \frac{5s}{s^2 + 4} \\ \implies Y(s) &= \frac{5s}{(s-1)(s^2+4)} - \frac{1}{s-1}. \end{aligned}$$

Performing a partial fraction decomposition on the first term, we find

$$Y(s) = \frac{-s+4}{s^2+4} + \frac{1}{s-1} - \frac{1}{s-1}$$

Canceling out the last two terms and rewriting we find

$$\begin{aligned} Y(s) &= -\frac{s}{s^2+4} + \frac{4}{s^2+4} \\ &= -\mathcal{L}\{\cos(2t)\} + 2\mathcal{L}\{\sin(2t)\}. \end{aligned}$$

Therefore the solution to the IVP is

$$\boxed{y(t) = -\cos(2t) + 2\sin(2t)}$$

- (b) Again we begin by taking the Laplace transform of both sides of the equation. The relevant transforms are

$$\begin{aligned} \mathcal{L}\{y'\} &= sY(s) + 1 \\ \mathcal{L}\{y\} &= Y(s) \\ \mathcal{L}\{e^{-t}\text{step}(t-2)\} &= e^{-2s}\mathcal{L}\{e^{-(t+2)}\} = e^{-2-2s}\frac{1}{s+1} \end{aligned}$$

Upon taking a Laplace transform of the equation, we have

$$\begin{aligned} sY(s) + 1 - Y(s) &= e^{-2-2s}\frac{1}{s+1} \\ \implies Y(s) &= e^{-2-2s}\frac{1}{(s+1)(s-1)} - \frac{1}{s-1}. \end{aligned}$$

Via a partial fraction decomposition, we have

$$Y(s) = e^{-2} \left( \frac{e^{-2s}}{2(s-1)} - \frac{e^{-2s}}{2(s+1)} \right) - \frac{1}{s-1}$$

Taking the inverse Laplace transform (using the tables and applying the shifting theorem) we have

$$\boxed{y(t) = e^{-2} \left( \frac{1}{2}e^{t-2} - \frac{1}{2}e^{-t+2} \right) \text{step}(t-2) - e^t}$$



**Problem 6** (45 points)

(a) Consider the following system of coupled linear ODE's

$$\mathbf{x}' = \mathbf{A}\mathbf{x}, \quad \mathbf{A} = \begin{bmatrix} -1 & 0 & 0 \\ 0 & -2 & 0 \\ 1 & 0 & -2 \end{bmatrix}$$

- (i) Find the eigenvalues of the matrix  $\mathbf{A}$ .
  - (ii) Find the eigenvectors of  $\mathbf{A}$ .
  - (iii) Show that all the eigenvectors computed in (ii) are linearly independent.
  - (iv) Find the general solution using the three linearly independent solutions associated with your computed eigenvalues and eigenvectors.
  - (v) What is the long time behavior of the general solution as  $t \rightarrow \infty$ .
- (b) Now consider the linear system of ODE

$$\mathbf{x}' = \mathbf{A}\mathbf{x}, \quad \mathbf{A} = \begin{bmatrix} -1 & 0 & 0 \\ 0 & -2 & 0 \\ 1 & 1 & -2 \end{bmatrix}$$

which has the solution

$$\mathbf{x}(t) = c_1\mathbf{x}_1(t) + c_2\mathbf{x}_2(t) + c_3\mathbf{x}_3(t),$$

where the first two linearly independent solutions are

$$\mathbf{x}_1(t) = e^{-t} \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \quad \mathbf{x}_2(t) = e^{-2t} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

find the third linearly independent solution by solving a generalized eigenvalue problem with  $\lambda = -2$ .

**Solution:**

- (a) (i) Matrix is lower triangular, therefore eigenvalues are  $\lambda_1 = -1$ ,  $\lambda_2 = \lambda_3 = -2$ .
- (ii) Solve  $(\mathbf{A} - \lambda_i\mathbf{I})\mathbf{v}_i = \mathbf{0}$  where  $\mathbf{v}_i = (\alpha, \beta, \gamma)^T$  such that

$$\left[ \begin{array}{ccc|c} -1 - \lambda_i & 0 & 0 & 0 \\ 0 & -2 - \lambda_i & 0 & 0 \\ 1 & 0 & -2 - \lambda_i & 0 \end{array} \right].$$

Solution

$$\mathbf{v}_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}_{\lambda_1=-1}, \quad \mathbf{v}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}_{\lambda_2=-2}, \quad \mathbf{v}_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}_{\lambda_3=-2}.$$

Computation of eigenvectors

$$\lambda_1 = -1: \left[ \begin{array}{ccc|c} 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 1 & 0 & -1 & 0 \end{array} \right] \Rightarrow \left[ \begin{array}{ccc|c} 1 & 0 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Free variable  $\gamma = s$ . Replace redundant row with this equation.

$$\left[ \begin{array}{ccc|c} 1 & 0 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & s \end{array} \right] \Rightarrow \left[ \begin{array}{ccc|c} 1 & 0 & 0 & s \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & s \end{array} \right] \Rightarrow \mathbf{v}_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}.$$

$$\lambda_1 = -2: \left[ \begin{array}{ccc|c} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{array} \right] \Rightarrow \left[ \begin{array}{ccc|c} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Free variables  $\beta = r, \gamma = s$ . Replace redundant row with these equations.

$$\left[ \begin{array}{ccc|c} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & r \\ 0 & 0 & 1 & s \end{array} \right] \Rightarrow \mathbf{v} = \begin{bmatrix} 0 \\ r \\ s \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \quad \mathbf{v}_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}.$$

(iii) We determine linear independence by building a matrix whose columns are the eigenvectors computed in the previous part.

$$\det(\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3) = \begin{vmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 0 & 1 \end{vmatrix} = 1 \neq 0$$

(iv) General solution

$$\mathbf{x}_g(t) = c_1 \mathbf{x}_1(t) + c_2 \mathbf{x}_2(t) + c_3 \mathbf{x}_3(t).$$

$$\mathbf{x}_1(t) = e^{-t} \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \quad \mathbf{x}_2(t) = e^{-2t} \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \quad \mathbf{x}_3(t) = e^{-2t} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}.$$

(v) As  $t \rightarrow \infty$ , all nontrivial solutions tend to the origin.

(b) The third solution is found by solving the generalized eigenvector problem

$$(\mathbf{A} + 2I)\mathbf{u} = \mathbf{v},$$

where  $\mathbf{v}$  is the eigenvector that corresponds to the solution  $\mathbf{x}_2$ . The linear system for  $\mathbf{u}$  is then

$$\left[ \begin{array}{ccc|c} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 1 & 1 & 0 & 1 \end{array} \right] \xrightarrow{\text{rref}} \left[ \begin{array}{ccc|c} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{array} \right] \rightarrow \left[ \begin{array}{ccc|c} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & s \end{array} \right]$$

This then gives

$$\mathbf{u} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + s \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix},$$

where  $s$  is a constant that can be taken to be  $s = 0$ . The third solution is then given by

$$\mathbf{x}_3(t) = e^{-2t} \left( t \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \right)$$

Table of Laplace transforms

$f(t)$	$F(s)$	$s$ domain	$f(t)$	$F(s)$	$s$ domain
1	$\frac{1}{s}$	$s > 0$	$t^n$	$\frac{n!}{s^{n+1}}$	$s > 0,$ $n$ a positive integer
$e^{at}$	$\frac{1}{s-a}$	$s > a$	$t^n e^{at}$	$\frac{n!}{(s-a)^{n+1}}$	$s > a,$ $n$ a positive integer
$\sin(bt)$	$\frac{b}{s^2 + b^2}$	$s > 0$	$\cos(bt)$	$\frac{s}{s^2 + b^2}$	$s > 0$
$e^{at} \sin(bt)$	$\frac{b}{(s-a)^2 + b^2}$	$s > a$	$e^{at} \cos(bt)$	$\frac{s-a}{(s-a)^2 + b^2}$	$s > a$
$\delta(t-c)$	$e^{-cs}$	$c \geq 0, s > 0$	$\text{step}(t-c)$	$\frac{e^{-sc}}{s}$	$c \geq 0, s > 0$
$f'(t)$	$sF(s) - f(0)$	depends on $f(t)$	$f(t-c)\text{step}(t-c)$	$e^{-cs}F(s)$	$c \geq 0, s > 0$

$$n^{\text{th}} \text{ order derivative: } \mathcal{L}\{f^{(n)}\} = s^n \mathcal{L}\{f\} - s^{n-1}f(0) - s^{n-2}f'(0) - \dots - f^{(n-1)}(0)$$