- 1. [2360/041625 (10 pts)] Write the word **TRUE** or **FALSE** as appropriate. No work need be shown. No partial credit given. Please write your answers in a single column separate from any work you do to arrive at the answer.
  - (a) The set  $\{t^2, e^t\}$  forms a basis for the solution space of the differential equation (t-1)y'' ty' + y = 0.
  - (b) The potential energy of the conservative system governed by  $2y'' + e^{-y} + 2y = 0$  is  $y^2 e^{-y}$ .
  - (c) The general solution of  $2y'' + 24y = \sin(2\sqrt{3}t) + \cos t$  is bounded.
  - (d) The equation  $x'' + 2x' + x^2 = \sin t$  can be written as  $\vec{\mathbf{u}}' = \begin{bmatrix} 0 & 1 \\ -1 & -2 \end{bmatrix} \vec{\mathbf{u}} + \begin{bmatrix} 0 \\ \sin t \end{bmatrix}$ , where  $\vec{\mathbf{u}} = \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$ .
  - (e) The correct form of the particular solution when using the method of undetermined coefficients to solve the equation  $y^{(4)} - 4y''' + 13y'' = t^2 + e^{2t}\cos 3t + \sin 2t \text{ is } y_p = At^4 + Bt^3 + Ct^2 + te^{2t} (D\cos 3t + E\sin 3t) + F\cos 2t + G\sin 2t.$

## SOLUTION:

- (a) FALSE Although the Wronskian of the two functions,  $W = t(t-2)e^t$ , is not identically zero, showing that the functions are linearly independent, they do not form a basis of the solution space since  $t^2$  is not a solution of the differential equation.
- (b) **TRUE** The potential energy is  $\int (e^{-y} + 2y) dy = y^2 e^{-y}$ .
- (c) FALSE A basis for the solution space of the associated homogeneous equation is  $\{\cos 2\sqrt{3}t, \sin 2\sqrt{3}t\}$  meaning that the particular solution will contain either or both of  $t \sin 2\sqrt{3}t$  and  $t \cos 2\sqrt{3}t$ . These grow without bound as  $t \to \infty$  implying that the solutions are unbounded.
- (d) **FALSE** The equation is nonlinear. With  $u_1 = x$  and  $u_2 = x'$  and  $\vec{\mathbf{u}} = \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$ , we have

$$u'_{1} = x' = u_{2}$$
$$u'_{2} = x'' = \sin t - 2x' - x^{2} = -u_{1}^{2} - 2u_{2} + \sin t$$
$$\vec{\mathbf{u}}' = \begin{bmatrix} u_{1} \\ u_{2} \end{bmatrix}' = \begin{bmatrix} u_{2} \\ -u_{1}^{2} - 2u_{2} + \sin t \end{bmatrix}$$

- (e) **TRUE** A basis for the solution space of the associated homogeneous problem is  $\{1, t, e^{2t} \cos 3t, e^{2t} \sin 3t\}$ .
- 2. [2360/041625 (20 pts)] Consider the linear operator  $L(\vec{y}) = ty'' y' + \frac{y}{t}$ . Assume t > 0.
  - (a) (8 pts) Justify why the solution space, S, of  $L(\vec{\mathbf{y}}) = 0$  is  $S = \text{span}\{t, t \ln t\}$ .
  - (b) (12 pts) Solve  $L(\vec{\mathbf{y}}) = \ln t$ .

## SOLUTION:

(a)

$$t(t'') - t' + \frac{t}{t} = 0 - 1 + 1 = 0 \quad \checkmark$$
$$t(t\ln t)' - (t\ln t)' + \frac{t\ln t}{t} = t\left(\frac{1}{t}\right) - (1 + \ln t) + \ln t = 1 - 1 - \ln t + \ln t = 0 \quad \checkmark$$
$$W[t, t\ln t](t) = \begin{vmatrix} t & t\ln t \\ 1 & 1 + \ln t \end{vmatrix} = t \neq 0$$

Both functions are solutions and they are linearly independent. Since the solution space has dimension 2 (second order linear equation), the two functions form a basis of the solution space so that their span is the solution space.

(b) Getting the equation into the correct form, we need to solve  $y'' - \frac{y'}{t} + \frac{y}{t^2} = \frac{\ln t}{t}$ . We use Variation of Parameters with  $y_1 = t, y_2 = t \ln t$  and  $y_p = v_1(t)y_1 + v_2(t)y_2$ .

$$v_{1}(t) = \int -\frac{t \ln t}{t} \left(\frac{\ln t}{t}\right) dt = -\int \frac{(\ln t)^{2}}{t} \stackrel{u=\ln t}{=} -\frac{1}{3} (\ln t)^{3}$$
$$v_{2}(t) = \int \frac{t}{t} \left(\frac{\ln t}{t}\right) dt = \int \frac{\ln t}{t} dt \stackrel{u=\ln t}{=} \frac{1}{2} (\ln t)^{2}$$
$$y_{p} = -\frac{1}{3} (\ln t)^{3} (t) + \frac{1}{2} (\ln t)^{2} (t \ln t) = \frac{1}{6} t (\ln t)^{3}$$
$$y = y_{h} + y_{p} = c_{1}t + c_{2}t \ln t + \frac{1}{6}t(\ln t)^{3} = t \left[c_{1} + c_{2}\ln t + \frac{1}{6}(\ln t)^{3}\right]$$

3. [2360/041625 (20 pts)] Use the method of undetermined coefficients to solve the initial value problem

$$3y'' - 6y' - 9y = 12e^t \left(2e^{2t} + 3\right), \ y(0) = y'(0) = 0$$

## SOLUTION:

The characteristic equation for the associated homogeneous problem is  $3r^2 - 6r - 9 = 3(r^2 - 2r - 3) = 3(r - 3)(r + 1) = 0$ which has roots r = -1, 3, implying that the solution to the homogeneous problem is  $y_h = c_1e^{3t} + c_2e^{-t}$ . The forcing function is  $24e^{3t} + 36e^t$  so that the guess for the particular solution is  $y_p = Ate^{3t} + Be^t$ . Substituting into the nonhomogeneous problem gives

$$3y_p'' - 6y_p' - 9y_p = 3\left(9Ate^{3t} + 6Ae^{3t} + Be^t\right) - 6\left(3Ate^{3t} + Ae^{3t} + Be^t\right) - 9\left(Ate^{3t} + Be^t\right)$$
$$= 12Ae^{3t} - 12Be^t = 24e^{3t} + 36e^t \implies A = 2, B = -3 \implies y_p = 2te^{3t} - 3e^t$$

We apply the initial conditions to  $y(t) = y_h + y_p = c_1e^{3t} + c_2e^{-t} + 2te^{3t} - 3e^t$  and  $y'(t) = 3c_1e^{3t} - c_2e^{-t} + 6te^{3t} + 2e^{3t} - 3e^t$  yielding.

$$y(0) = c_1 + c_2 - 3 = 0 \implies c_1 + c_2 = 3$$
$$y'(0) = 3c_1 - c_2 + 2 - 3 = 0 \implies 3c_1 - c_2 = 1$$

These give  $4c_1 = 4 \implies c_1 = 1$  and  $c_2 = 2$  so that the solution to the initial value problem is  $y(t) = e^{3t} + 2e^{-t} + 2te^{3t} - 3e^t$ .

4. [2360/041625 (40 pts)] The differential equation governing the motion of an harmonic oscillator can be written in the alternate form

$$\ddot{x} + 2a\dot{x} + \omega_0^2 x = g(t) \tag{1}$$

where  $\omega_0 > 0$  is the circular frequency and  $a \ge 0$ . Use Eq. (1) to answer the following.

- (a) (4 pts) Find a relationship between a and  $\omega_0$  that guarantees the oscillator passes through its equilibrium position at most once.
- (b) (4 pts) If  $g(t) = 10 \cos 5t$  and the restoring (spring) constant is 100, find values of a and the mass of the object that put the oscillator into resonance.
- (c) (32 pts) If  $a = 4, \omega_0 = \sqrt{18}$  and g(t) = 36, answer the following.
  - i. (3 pts) Is the oscillator undamped, critically damped, overdamped or underdamped? Justify your answer.
  - ii. (25 pts) Use Laplace transforms to find the equation of motion assuming that the oscillator is initially at rest at its equilibrium position.
  - iii. (4 pts) Identify the steady state and transient portions of the solution, if they exist. If they don't exist, explain why not.

## SOLUTION:

(a) The characteristic equation is  $r^2 + 2ar + \omega_0^2 = 0$  having solutions  $r = \frac{-2a \pm \sqrt{4a^2 - 4\omega_0^2}}{2} = -a \pm \sqrt{a^2 - \omega_0^2}$ . In order for the oscillator to pass through its equilibrium position at most once, the roots of the characteristic equation must be real. Thus  $a^2 - \omega_0^2 \ge 0 \implies a^2 \ge \omega_0^2 \implies |a| \ge |\omega_0| \implies a \ge \omega_0$  since both a and  $\omega_0$  are positive.

- (b) The system must be undamped so that a = 0. Furthermore, the circular frequency of the oscillator must match that of the forcing function. Thus, we need  $\omega_0 = 5 = \sqrt{\frac{100}{m}} \implies 25 = \frac{100}{m} \implies m = 4$ .
- (c) The initial value problem is  $\ddot{x} + 8\dot{x} + 18x = 36$ ,  $x(0) = \dot{x}(0) = 0$ .
  - i. From part (a),  $a^2 \omega_0^2 = 16 18 < 0$  so the oscillator is underdamped. Note also that  $8^2 4(1)(18) < 0$ .
  - ii. The initial conditions are  $x(0) = \dot{x}(0) = 0$ .

$$\begin{aligned} \mathscr{L}\left\{\ddot{x}+8\dot{x}+18x=36\right\}\\ s^{2}X(s)-sx(0)-\dot{x}(0)+8[sX(s)-x(0)]+18X(s)=\frac{36}{s}\\ (s^{2}+8s+18)X(s)=\frac{36}{s}\\ X(s)=\frac{36}{s(s^{2}+8s+18)}=\frac{A}{s}+\frac{Bs+C}{s^{2}+8s+18}\\ 36=A(s^{2}+8s+18)+(Bs+C)s\\ s=0:36=A(18)\implies A=2\\ s=1:36=2(1+8+18)+B+C\implies B+C=-18\\ s=-1:36=2(1-8+18)+(-B+C)(-1)\implies B-C=14\\ 2B=-4\implies B=-2 \text{ and } C=-16\\ X(s)=\frac{2}{s}-\frac{2s+16}{s^{2}+8s+18}=\frac{2}{s}-\frac{2s+16}{(s+4)^{2}+2}=\frac{2}{s}-2\left[\frac{s+4+4}{(s+4)^{2}+(\sqrt{2})^{2}}\right]\\ =\frac{2}{s}-2\left[\frac{s+4}{(s+4)^{2}+(\sqrt{2})^{2}}+\frac{4}{\sqrt{2}}\frac{\sqrt{2}}{(s+4)^{2}+(\sqrt{2})^{2}}\right]\\ =\frac{2}{s}-2\left[\frac{s+4}{(s+4)^{2}+(\sqrt{2})^{2}}\right]-4\sqrt{2}\left[\frac{\sqrt{2}}{(s+4)^{2}+(\sqrt{2})^{2}}\right]\\ x(t)=\mathscr{L}^{-1}\left\{X(s)\right\}=\mathscr{L}^{-1}\left\{\frac{2}{s}-2\left[\frac{s+4}{(s+4)^{2}+(\sqrt{2})^{2}}\right]-4\sqrt{2}\left[\frac{\sqrt{2}}{(s+4)^{2}+(\sqrt{2})^{2}}\right]\\ =2\mathscr{L}^{-1}\left\{\frac{1}{s}\right\}-2e^{-4t}\mathscr{L}^{-1}\left\{\frac{s}{s^{2}+(\sqrt{2})^{2}}\right\}-4\sqrt{2}e^{-4t}\mathscr{L}^{-1}\left\{\frac{\sqrt{2}}{s^{2}+(\sqrt{2})^{2}}\right\}\\ =2-2e^{-4t}\cos\sqrt{2}t-4\sqrt{2}e^{-4t}\sin\sqrt{2}t=2\left[1-e^{-4t}\left(\cos\sqrt{2}t+2\sqrt{2}\sin\sqrt{2}t\right)\right]\end{aligned}$$

iii. The steady state solution is 2 and the transient solution is  $-2e^{-4t} (\cos \sqrt{2}t + 2\sqrt{2} \sin \sqrt{2}t)$ .

5. [2360/041625 (10 pts)] Consider the initial value problem  $ty'' + t^2y' + 3y = tg(t)$ , y(0) = -5, y'(0) = 0 and suppose  $\mathscr{L} \{g(t)\} = \frac{2s}{s^4 + 4}$ . Using Laplace transforms find, **but do not solve**, the ODE that  $Y(s) = \mathscr{L} \{y(t)\}$  must satisfy. Write your answer in the form  $L(\vec{\mathbf{Y}}) = f(s)$ . SOLUTION:

$$\begin{aligned} \text{Begin by noting that } \mathscr{L}\left\{tg(t)\right\} &= (-1)^1 \frac{\mathrm{d}}{\mathrm{d}s} \left(\frac{2s}{s^4+4}\right) = -\left[\frac{(s^4+4)(2)-2s(4s^3)}{(s^4+4)^2}\right] = \frac{2(3s^4-4)}{(s^4+4)^2}.\\ \mathscr{L}\left\{ty''+t^2y'+3y\right\} &= \mathscr{L}\left\{ty''\right\} + \mathscr{L}\left\{t^2y'\right\} + \mathscr{L}\left\{3y\right\} = \mathscr{L}\left\{tg(t)\right\} \\ &(-1)^1 \frac{\mathrm{d}}{\mathrm{d}s} \mathscr{L}\left\{y''\right\} + (-1)^2 \frac{\mathrm{d}^2}{\mathrm{d}s^2} \mathscr{L}\left\{y'\right\} + 3\mathscr{L}\left\{y\right\} = \mathscr{L}\left\{tg(t)\right\} \\ &- \frac{\mathrm{d}}{\mathrm{d}s}\left[s^2Y(s) - sy(0) - y'(0)\right] + \frac{\mathrm{d}^2}{\mathrm{d}s^2}\left[sY(s) - y(0)\right] + 3Y(s) = \frac{2(3s^4-4)}{(s^4+4)^2} \\ &- \left[s^2Y'(s) + 2sY(s) - y(0)\right] + \frac{\mathrm{d}}{\mathrm{d}s}\left[sY'(s) + Y(s)\right] + 3Y(s) = \frac{2(3s^4-4)}{(s^4+4)^2} \\ &- s^2Y'(s) - 2sY(s) - 5 + sY''(s) + Y'(s) + Y'(s) + 3Y(s) = \frac{2(3s^4-4)}{(s^4+4)^2} \\ &= sY''(s) + (2-s^2)Y'(s) + (3-2s)Y(s) = 5 + \frac{2(3s^4-4)}{(s^4+4)^2} \end{aligned}$$