PEAPOD

$\underline{P} neumatically \ \underline{E} nergized \ \underline{A} uto-throttled \ \underline{P} ump \ \underline{O} perated \ for \ a \\ \underline{D} evelopmental \ Upperstage$

Test Readiness Review



Customer: Special Aerospace Services Chris Webber and Tim Bulk







- Project Overview
- Schedule
- Test Readiness
- Budget







Project Overview



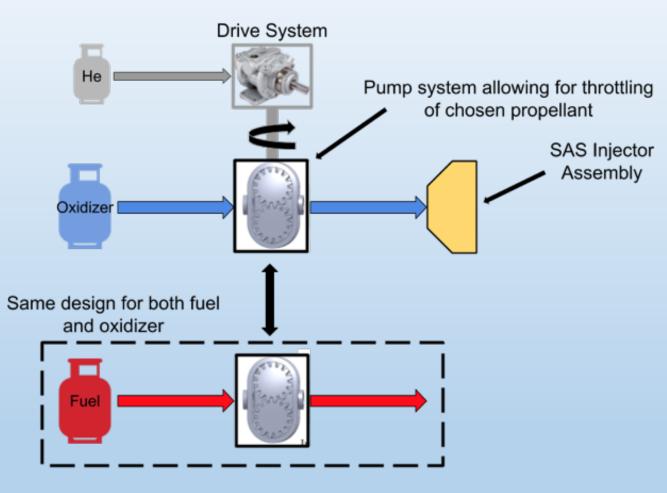


- Design, manufacture, and test a pneumatically powered pump system for use on an upper stage rocket engine or lander.
 - Proof of concept pump system for hypergolic propellants
 - 10%-100% throttleability
 - Pneumatically powered





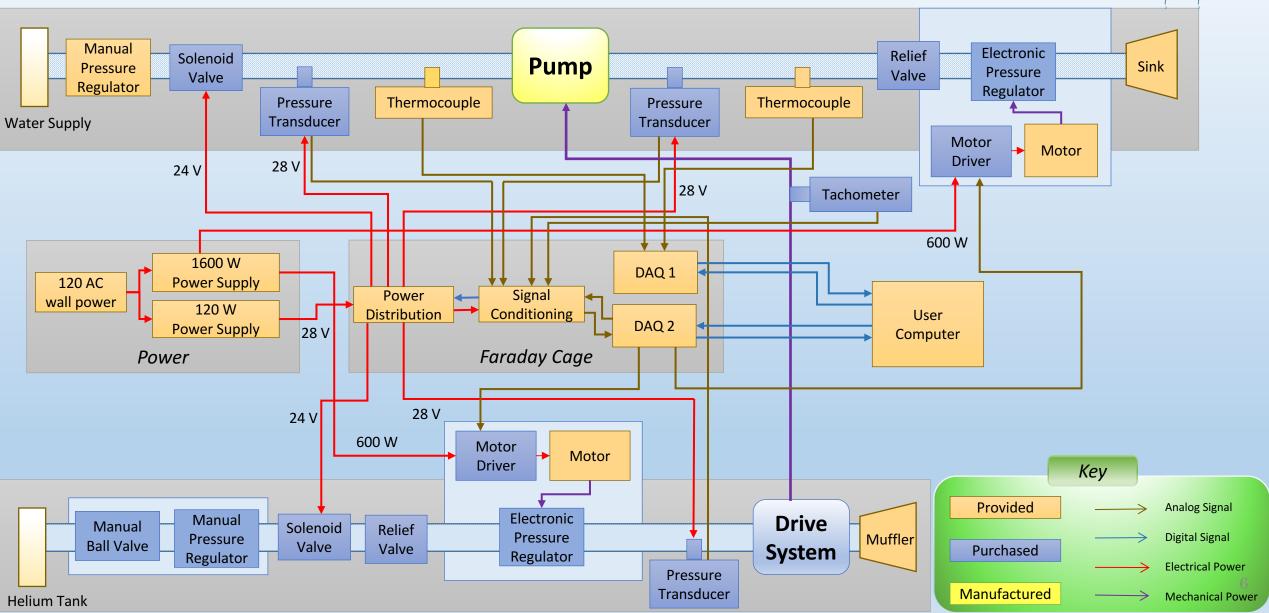


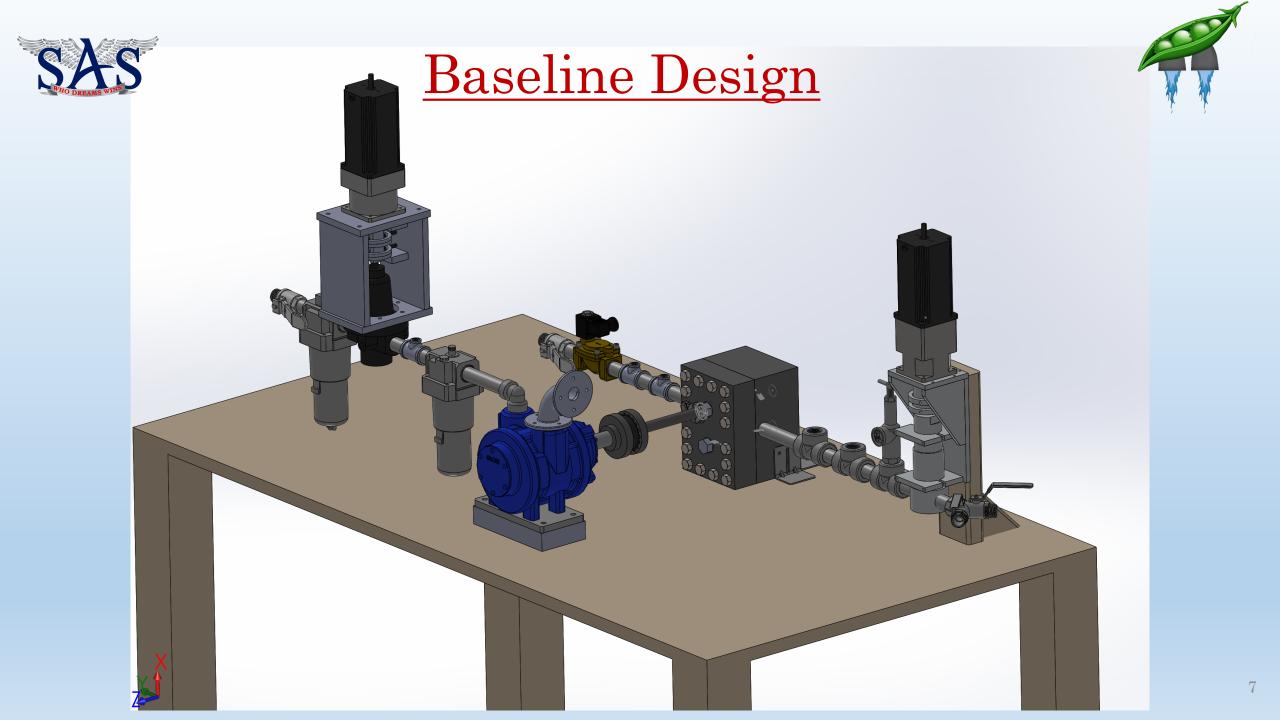






Functional Block Diagram

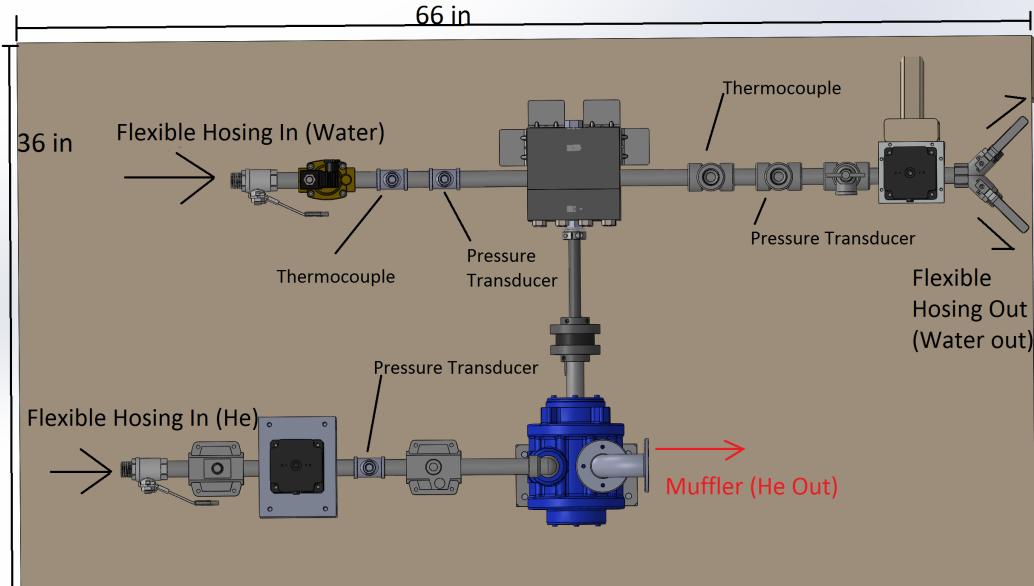








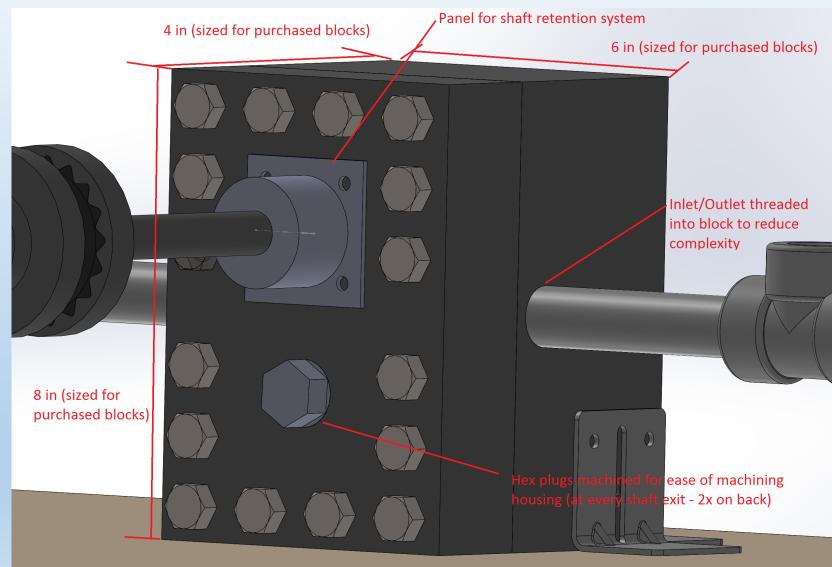














<u>S</u> <u>Design Changes – Air Motor Pressure</u> <u>Regulator</u>

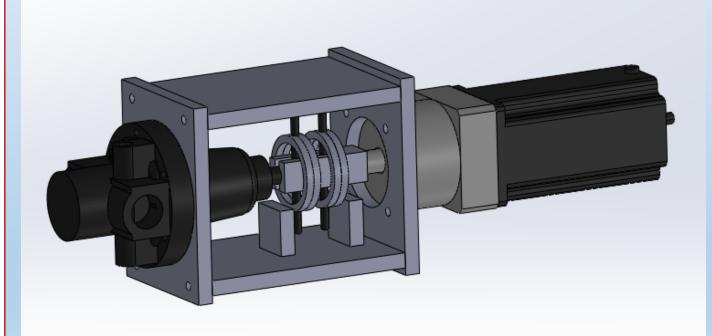
Constructed from a manual regulator and stepper motor:

Manual Regulator:

- <u>400 scfm flowrate (360 required)</u>
- <u>0 psi to 120 psi (105 psi required)</u>
- <u>12 turns for 0 psi to 105 psi</u>
- <u>8 N-m max. adjustment torque</u>

Stepper Motor (HT34-487) w/Gearbox

- <u>2.2rev/s max. rotation rate (0.6 rev/s</u> <u>required)</u>
- <u>25 N-m min. torque (8 N-m</u> <u>required)</u>





<u>Design Changes – Back-Pressure</u>

Regulator

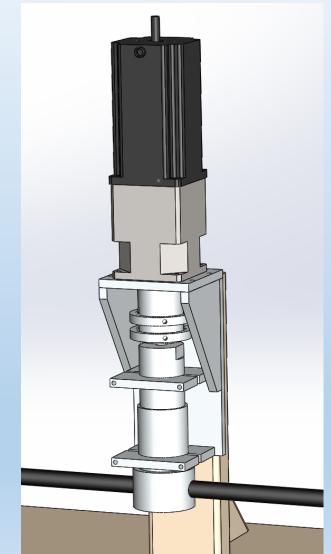
Constructed from a manual back-pressure regulator and stepper motor:

Manual Back-Pressure Regulator:

- <u>200 lpm flowrate (84 required)</u>
- <u>75 psi to 750 psi (full range req.)</u>
- <u>11 turns for 75 psi to 750 psi</u>
- <u>15N-m max. adjustment torque</u>

Stepper Motor (HT34-487) w/Gearbox

- <u>4 rev/s max. rotation rate (2.2 rev/s</u> <u>required)</u>
- <u>25 N-m min. torque @ 2.2 rev/s (15</u> <u>N-m required)</u>





Critical Project Elements



CPEs from CDR	Rationale
Develop a functioning pump	Manufacturing of the pump is in progress, but assembly and operation of the pump could pose a time risk.
Meet efficiency requirement of 75%	Control and design of the pump could cause the pump to achieve a lower efficiency.
Correct acquisition of pressure, RPM, and mass flow rate	Have yet to acquire a measurement on flow rate, which is needed for Level 1 Success.
Developing throttling capabilities (10-100%)	Throttling the air motor using a stepper motor attached to a regulator creates unforeseen mechanical and control loop challenges.
Safe operation of pump and drive system	Operating a pump with high pressures using digital control can present a multitude of problems towards safety.
Budgetary restrictions	A multitude of parts to purchase

Schedule









Level	Performance Success	
1	 750 ± 15 psi outlet pressure Structural FOS 2.5 120 seconds of operation 75% efficiency of pump at full throttle 	
2	 10-100% throttleability 0-100% throttle in 2 seconds All level 1 requirements 	
3	 0-100% throttle in 1 second All level 1 and 2 requirements Hypergolic Compatible 	C



Schedule



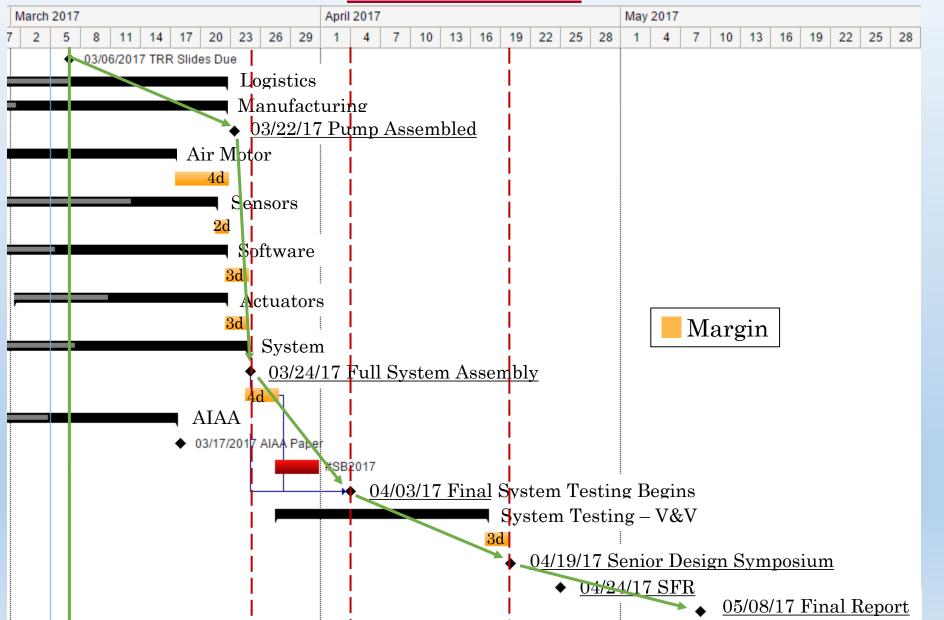


<u>Schedule</u>





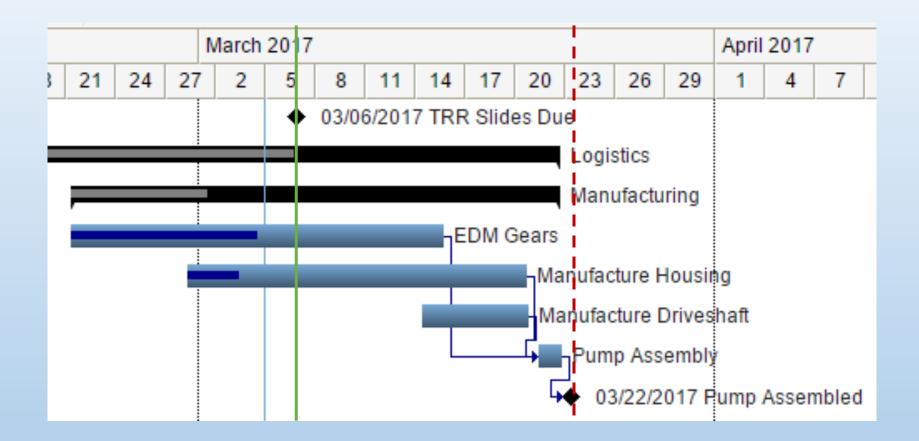










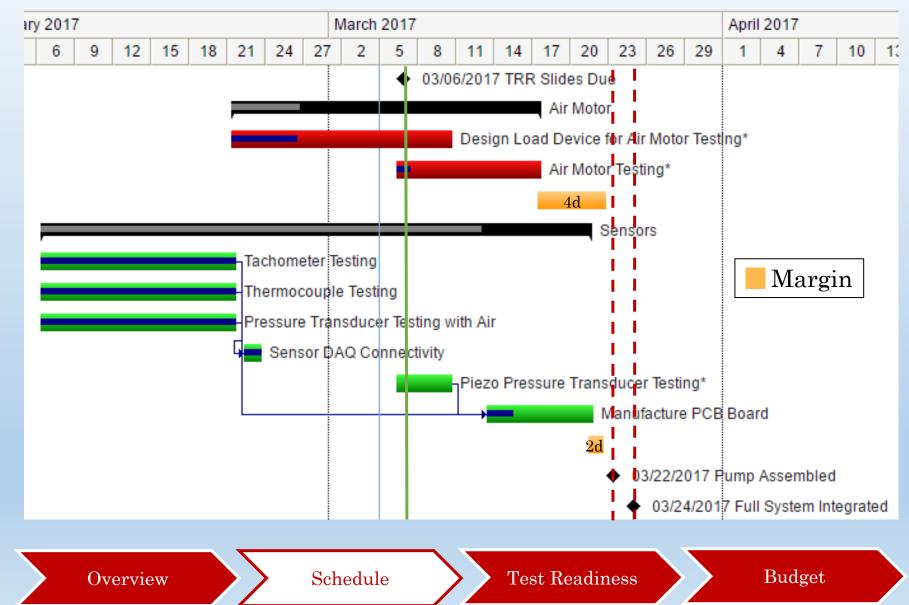








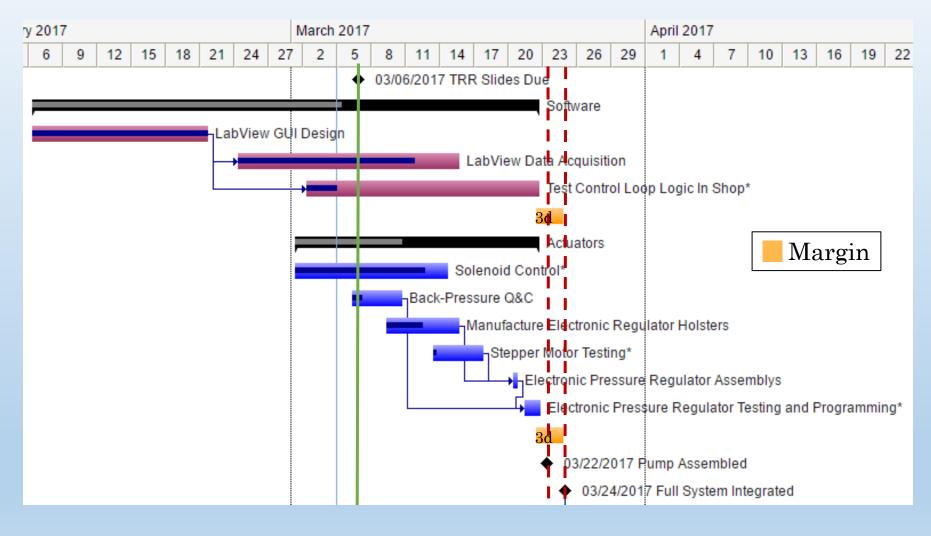












Overview

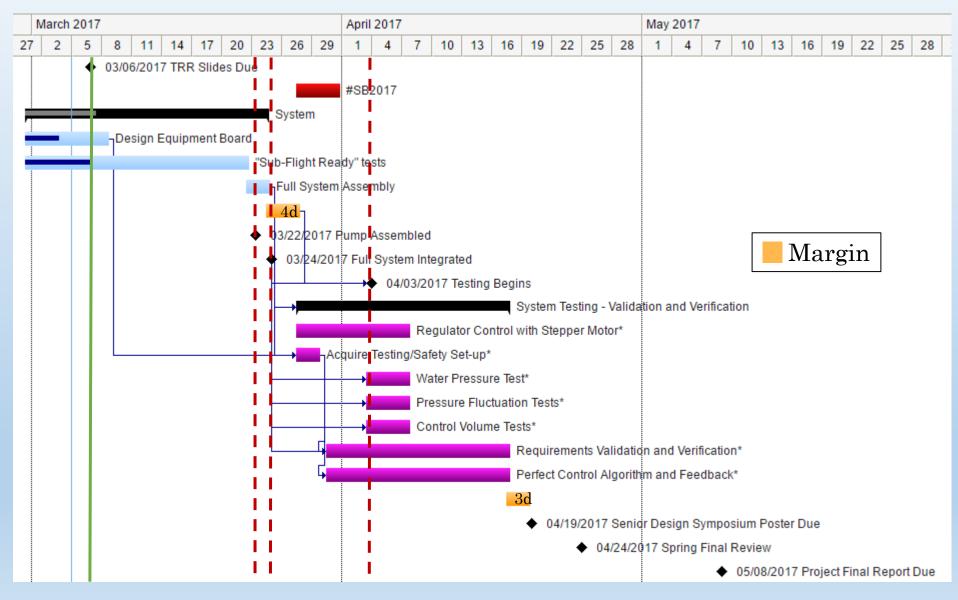
Schedule

Budget













Largest Concerns March 2017 April 2017 May 2017 11 14 17 20 23 26 29 10 13 16 19 22 25 28 7 10 13 16 19 22 25 28 7 2 5 8 1 4 4 03/06/2017 TRR Slides Due Housing manufacturing Logistics Manufacturing is a slow process 03/22/2017 Pump Assemble Air Motor Control loop design may take longer than expected Sensors and already have Software encountered some DAQ issues Waiting for the arrival of Actuators the drivers. Possibility of System ^{03/24/2017} Full System Integrated problems with the regulators Having enough time to AIAA Paper 03/17/2017 AIAA Paper troubleshoot and verify #SB2017 our requirements 04/03/2017 Testing Begins System Testing - Validation and Verification 04/19/2017 Senidr Design Symposium Poster Due 04/24/2017 Spring Final Review 05/08/2017 Project Final Report Due





<u>Test Readiness</u>





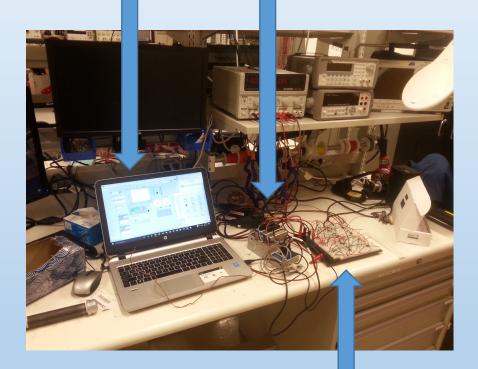
PC/ User Interface DAQ



- <u>Completed Tasks</u>
 - DAQ Data Collection
 - Sensor Calibration
 - Sensor Signal Conditioning
 - Leak Testing

<u>Requirement(s) met</u>:

• FR.7

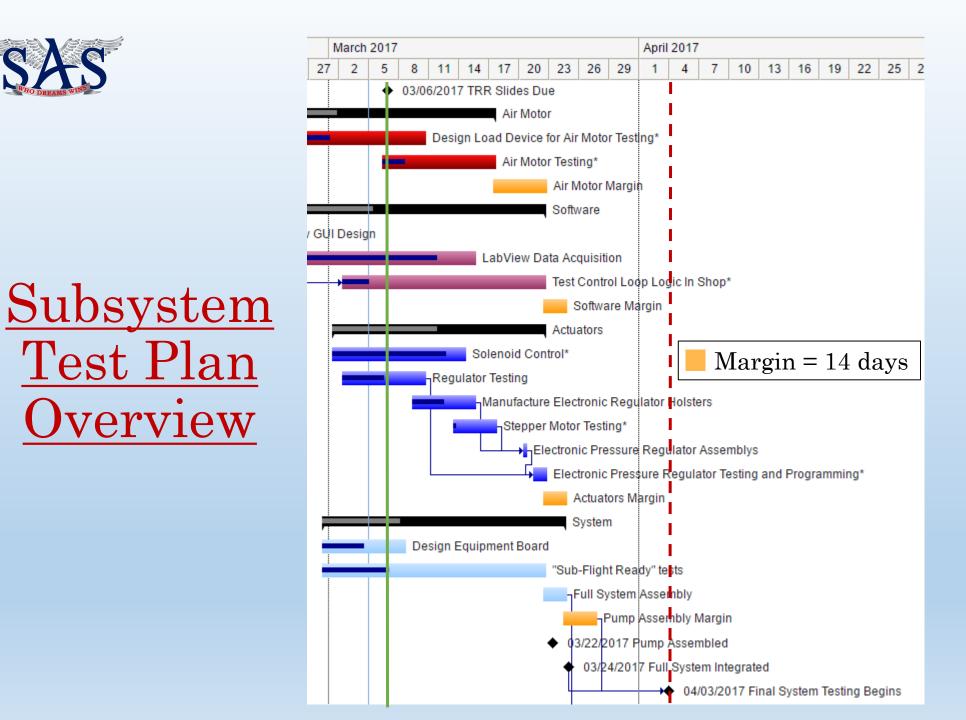


Signal Conditioning

Schedule





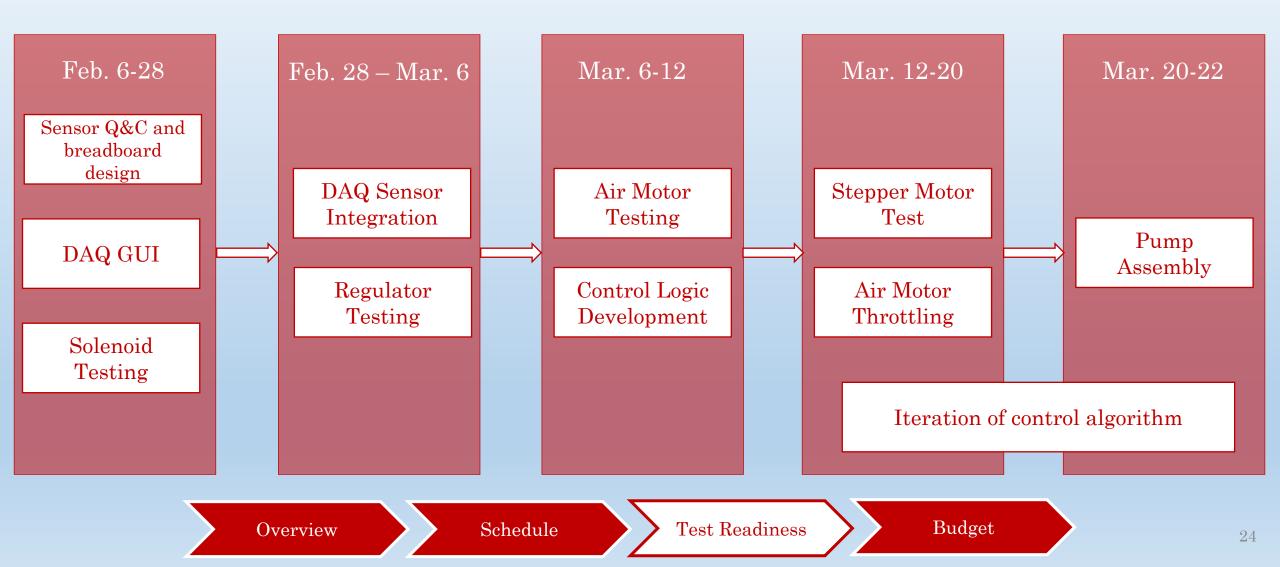




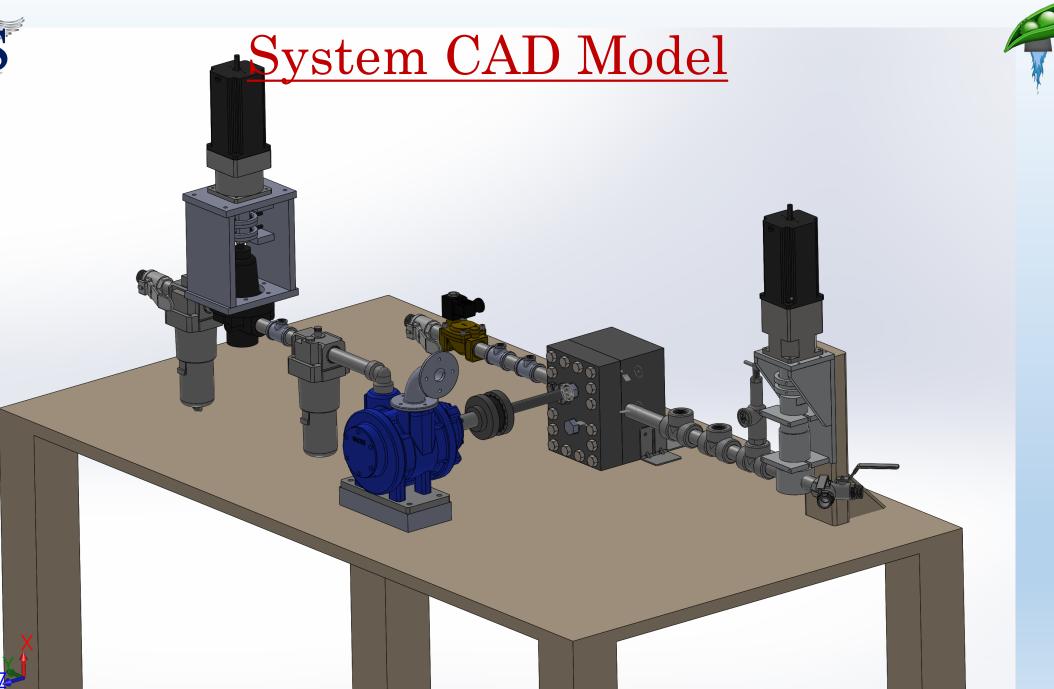








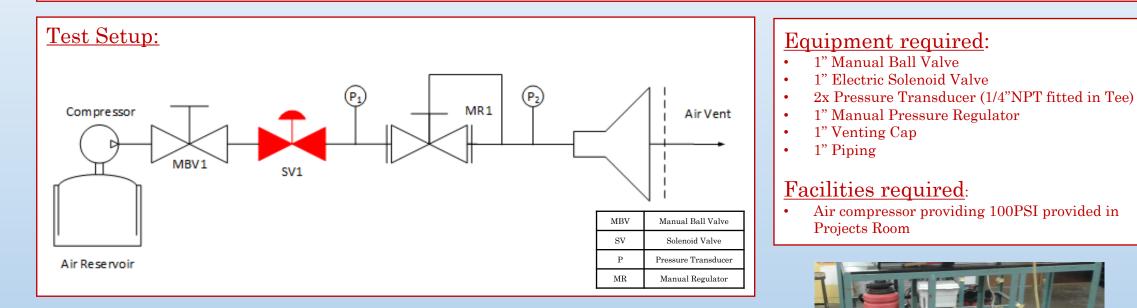








<u>Test Rationale</u>: Relate regulator opening to downstream pressure through data collection. Use results to calibrate downstream pressure to regulator thread engagement.



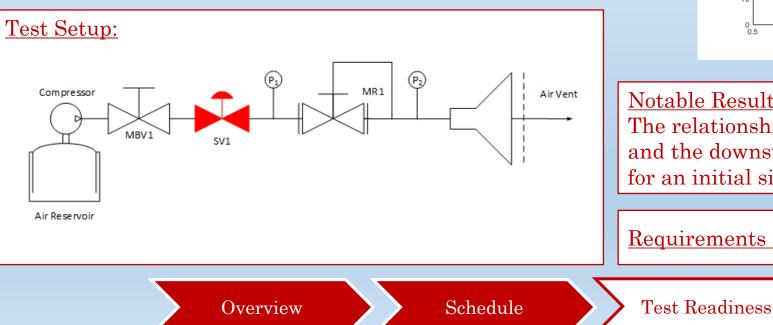


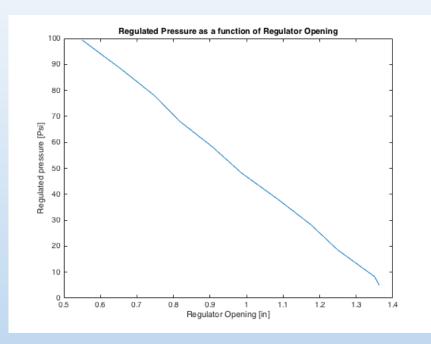
Pressure Regulator Testing

<u>Test Procedure</u>: Set regulator to certain thread engagement, record the subsequent downstream pressure. Repeat as needed for a sufficient amount of points over the full pressure range.

Risk Mitigation: The results of this test will help to operate the regulator electronically, getting the project closer to fulfilling its requirement of electronically regulating the pump.

Time Requirement: 7 man hours





Notable Results:

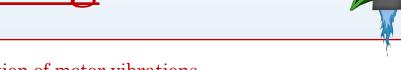
The relationship between the regulator thread engagement and the downstream pressure is **roughly linear**, allowing for an initial simple controller to be designed.

Budget

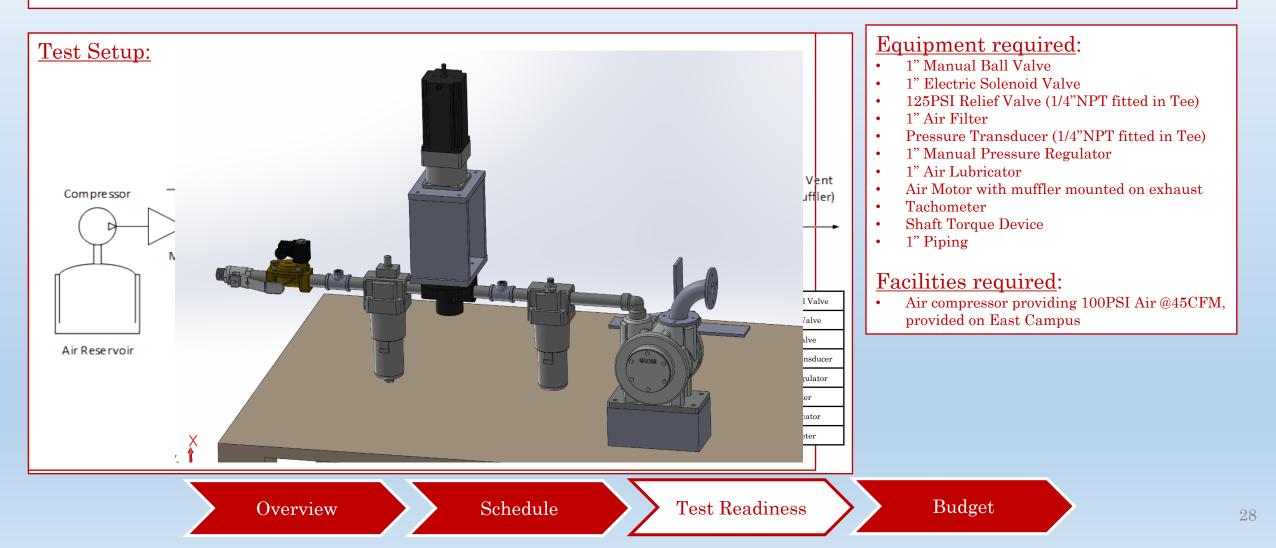
<u>Requirements met at test completion:</u> None







<u>Test Rationale</u>: Determine the operational throttle range of the motor. Quantification of motor vibrations.





<u>Air Motor Testing</u>

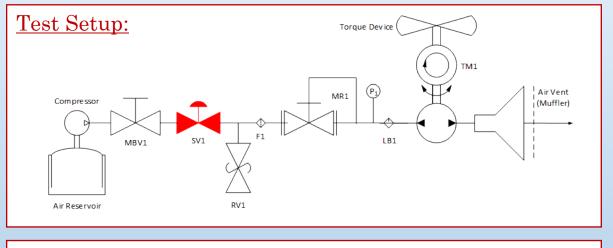


<u>Test Procedure</u>:

Regulator is set to a known pressure (starting at 10PSI), the system is activated. The resulting RPM of the drive shaft is recorded. The test is run for a the full range of pressures 0-100PSI.

<u>Risk Mitigation:</u> The results of this test will verify that the motor can attain the full throttle range of 10-100% throttleability. This test will also quantify expected vibrations the motor will induce on the test assembly

<u>Time Requirement:</u> 20 man hours



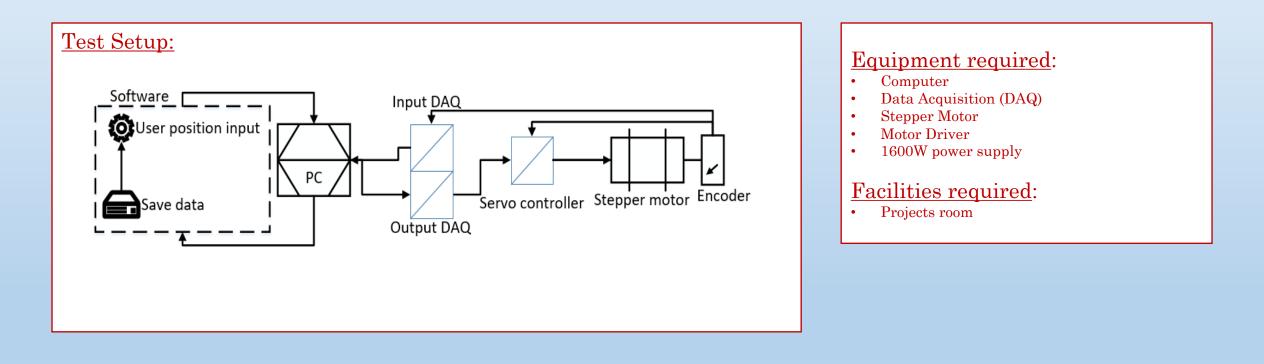
<u>Requirements met at test completion:</u>

• FR2 – Pump is throttleable

Test Rationale:

Overview

Determined motor can be controlled through LabVIEW. Quantify accuracy of control system and slew rates



S <u>Stepper Motor Testing – Phase 1</u>



Budget

Schedule

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Test Procedure:

Motor will be connected to the DAQ, while LabVIEW commands the motor to step to specific angles.

<u>Risk Mitigation:</u> The results of this test will verify that the stepper motor can be controlled through LabVIEW allowing pressure to be regulated to the angles specified.

<u>Time Requirement:</u> 10 man hours

Test Setup: Software Input DAQ User position input PC User position input PC Servo controller Stepper motor Encoder Output DAQ

<u>Requirements met at test completion:</u> None





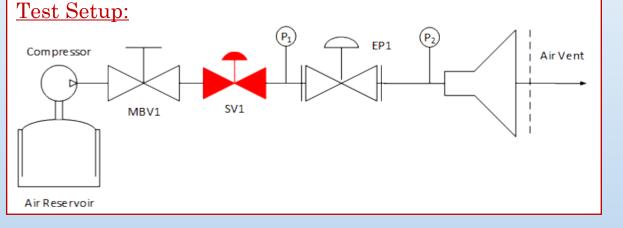
<u>Test Procedure</u>:

Motor will be connected to the DAQ, while in LabVIEW the command the motor to step at specific angles. The corresponding downstream pressure is recorded. The test is then iterated through a series of pressure settings

<u>Risk Mitigation:</u> The results of this test will verify that the stepper motor can be controlled through LabVIEW allowing pressure to be regulated electronically. This allows for the development of the feedback control with the downstream pressure transducer.

<u>Time Requirement:</u> 10 man hours

<u>Stepper Motor Testing – Phase 2</u>



Budget

MBV	Manual Ball Valve
SV	Solenoid Valve
Р	Pressure Transducer
EP	Electronic Pressure Regulator

<u>Requirements met at test completion:</u> None









•

Facilities required:

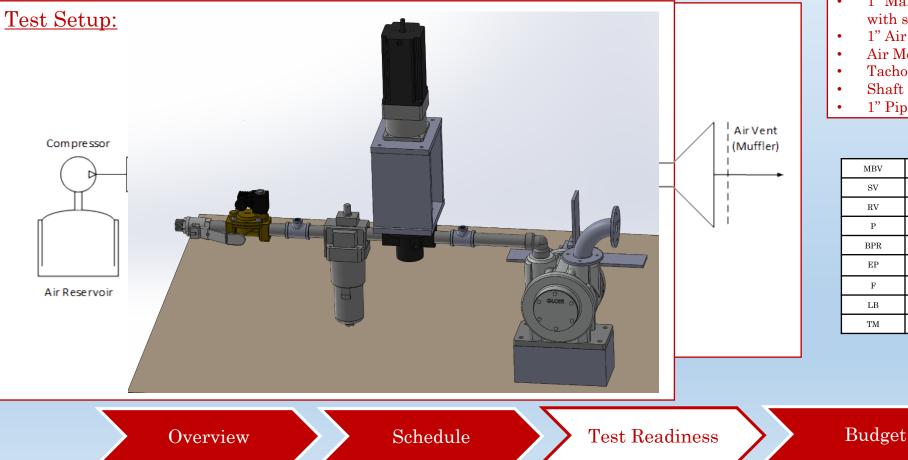
100PSI Air @45CFM.

Air compressor providing

provided on East Campus



<u>Test Rationale</u>: Verify that acquired stepper motor operates as expected. Verify that control algorithms and driver correctly actuate motor to desired positions. Quantify accuracy of control system and slew rates



Equipment required:

- 1" Manual Ball Valve
- 1" Electric Solenoid Valve
- 125PSI Relief Valve (1/4"NPT fitted in Tee)
- 1" Air Filter ٠
- Pressure Transducer (1/4"NPT fitted in Tee) ٠
- 1" Manual Pressure Regulator mounted ٠ with stepper motor
- 1" Air Lubricator
- Air Motor with muffler mounted on exhaust
- Tachometer
- Shaft Torque Device
 - 1" Piping

MBV	Manual Ball Valve
SV	Solenoid Valve
RV	Relief Valve
Р	Pressure Transducer
BPR	Back Pressure Regulator
EP	Electronic Pressure Regulator
F	Air Filter
LB	Air Lubricator
TM	Tachometer



Air Motor Throttling

Test Procedure:

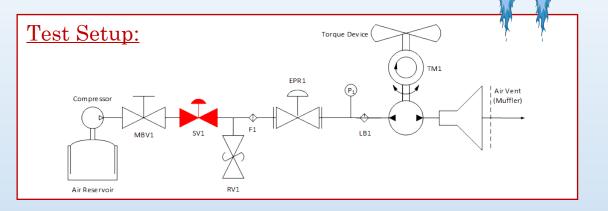
The DAQ system is loaded with a desired throttle profile. The DAQ now starts up the test by setting the motor to 10% throttle. The motor is then ran through a throttle profile.

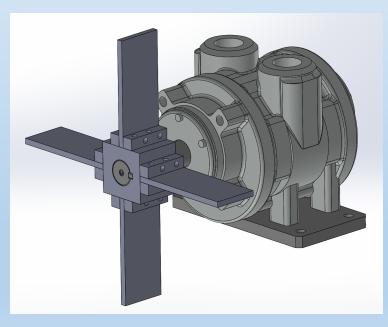
<u>Risk Mitigation:</u> The results of this test will verify that the stepper motor can actuate the regulator through the full range of 10-100% to guarantee electronic throttle-ability. This test will also quantify the slew rate of this control system.

<u>Time Requirement:</u> 15 man hours

<u>Requirements met at test completion:</u>

- FR2 Pump is electronically throttleable
- FR4 Pump system can run throttle profile



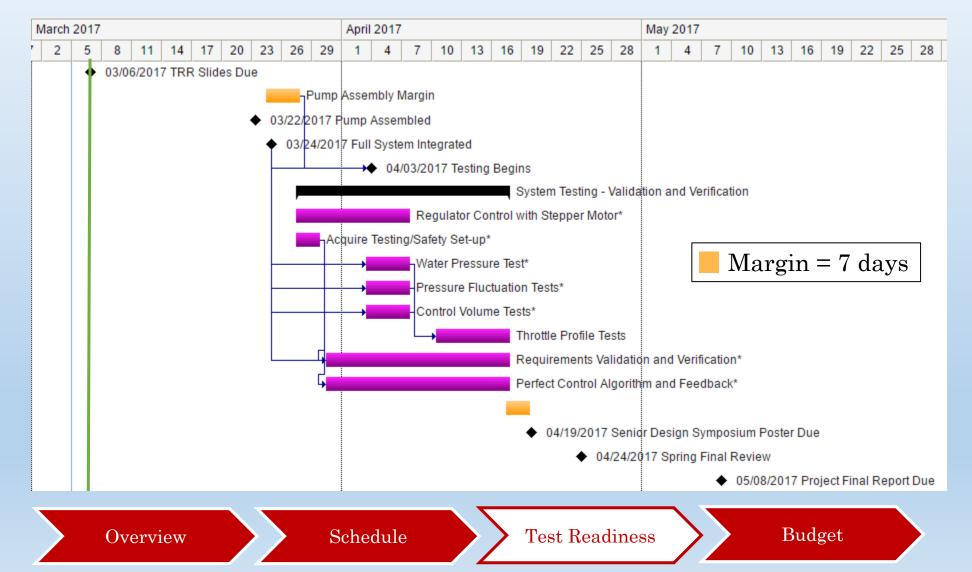








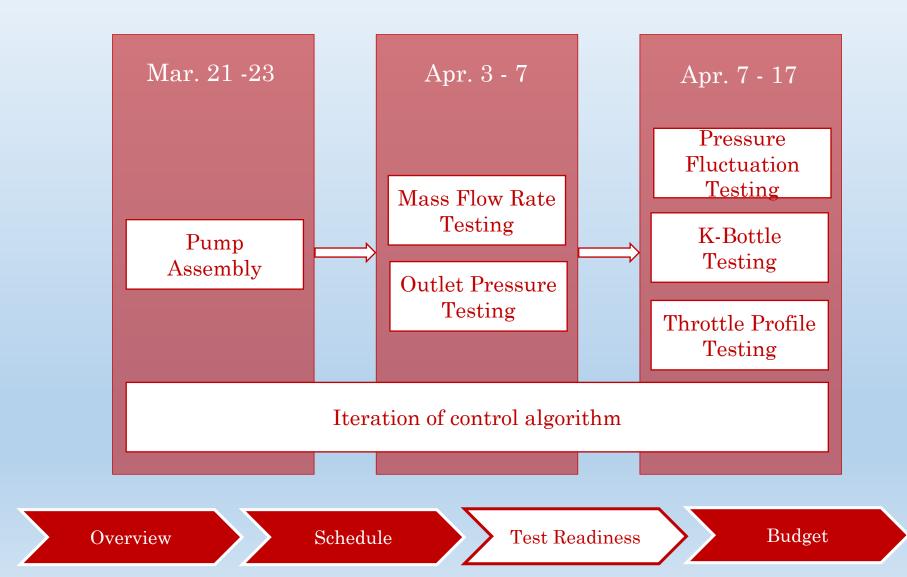
Final Test Plan Overview







Final Test Plan Overview



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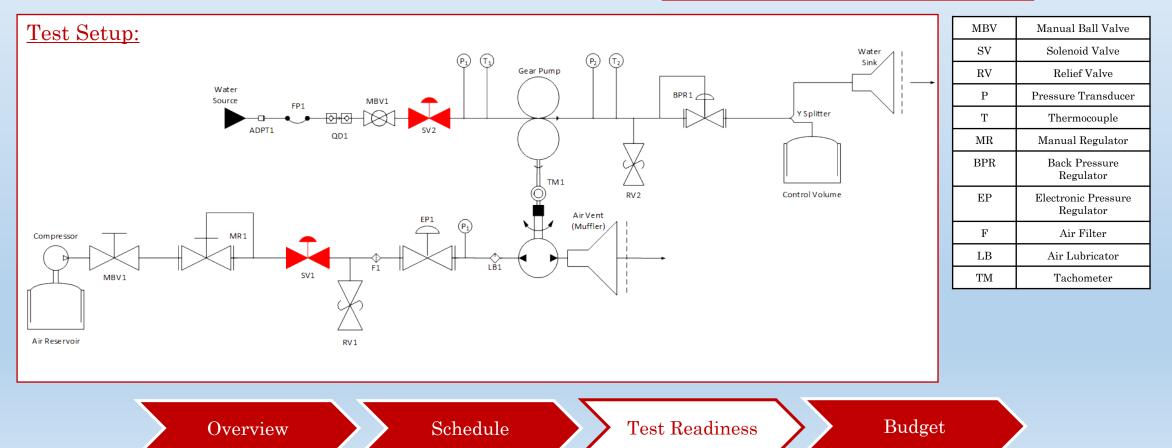
<u>Test Rationale</u>: Verify that after full assembly the pump outputs the expected amount of water for a certain throttle setting.

Equipment required:

• Complete Assembly of all systems, operational DAQ and control components

<u>Facilities required</u>:

• Air compressor providing 100PSI Air @45CFM, provided on East Campus









Test Procedure:

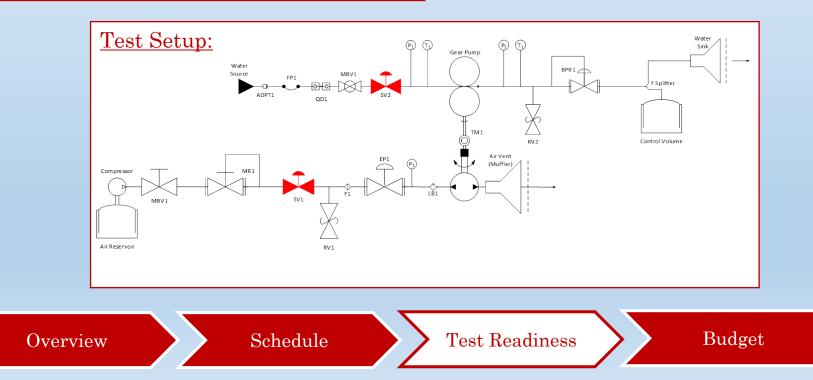
The DAQ system is loaded with a desired throttle setting (constant). The pump is set to run, the flow is switched to the control volume for a certain amount of time and then switched back to the regular sink.

<u>Risk Mitigation</u>: The results of this test will verify that the system meets design expectations, that is meeting an output flow rate of 1.4L/s

<u>Time Requirement:</u> 20 man hours

<u>Requirements met at test completion:</u>

• DR2.1 - Pump operates at 1.4L/s at full throttle







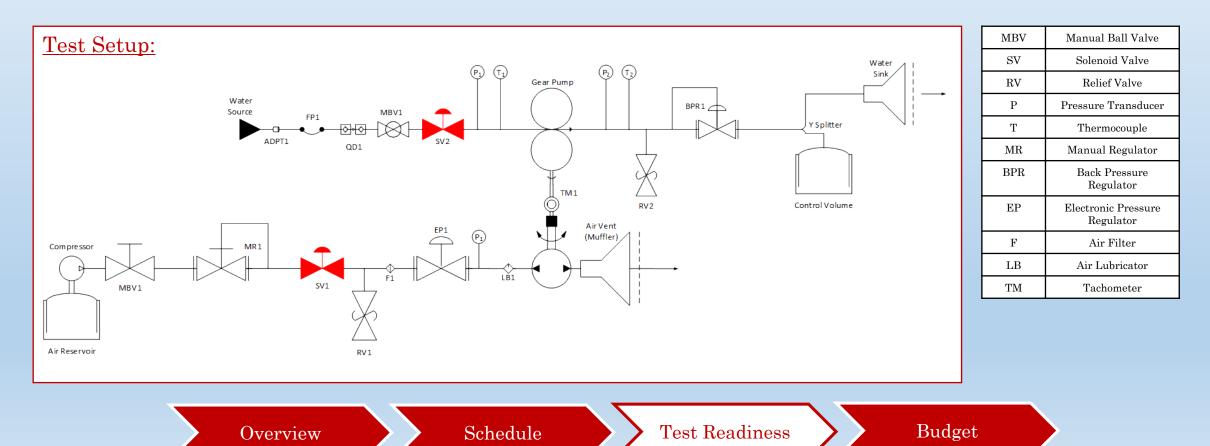
<u>Test Rationale</u>: Verify that after full assembly the pump output flow has minimal pressure fluctuation.

Equipment required:

• Complete Assembly of all systems, operational DAQ and control components

Facilities required:

• Air compressor providing 100PSI Air @45CFM, provided on East Campus





Pressure Fluctuation Testing

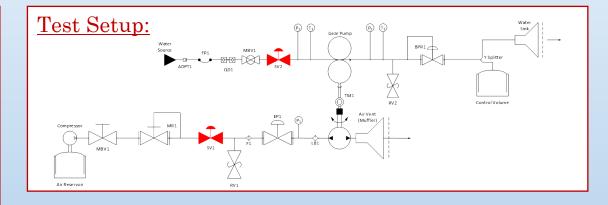


<u>Test Procedure</u>:

The DAQ system is loaded with a desired throttle setting (constant). The pump is set to run, the output flow pressure is measured and recorded.

<u>Risk Mitigation:</u> The results of this test will verify that the pump meets design expectations, that is of having pressure fluctuations no greater than 15PSI.

<u>Time Requirement:</u> 5 man hours



<u>Requirements met at test completion:</u>

• DR2.3 - Pump operates with pressure fluctuations less than 15PSI

Schedule









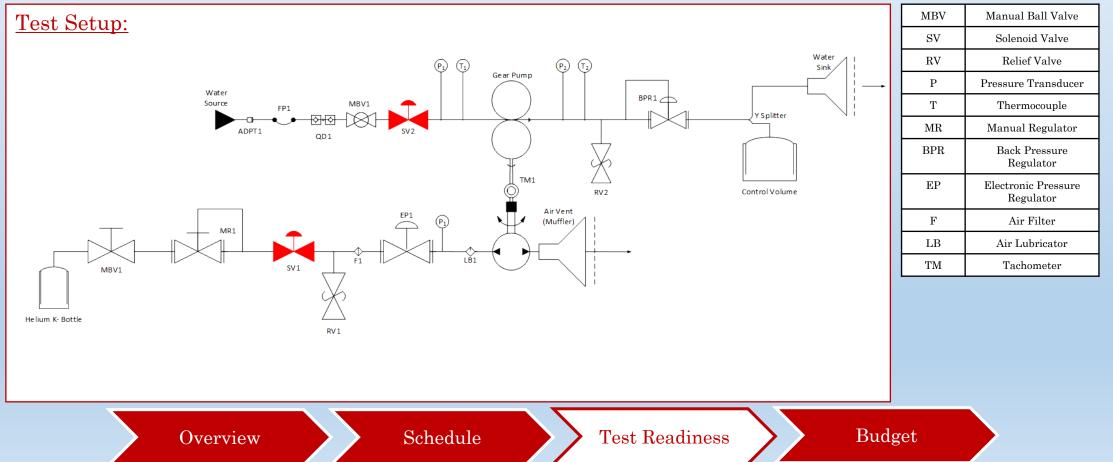
<u>Test Rationale</u>: Verify that after full assembly the pump system can operate using a Helium K-Bottle to run the motor.

Equipment required:

• Complete Assembly of all systems, operational DAQ and control components

Facilities required:

- Water Source
- Helium K-Bottle





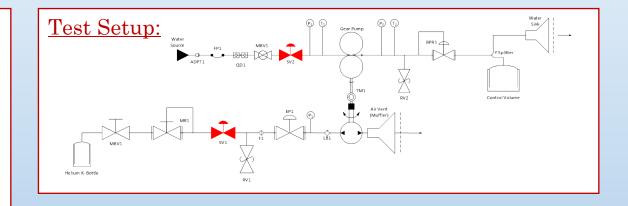




Test Procedure:

The pump system is setup as it normally would except that instead of using compressed air, the motor system uses a helium k-bottle.

<u>Risk Mitigation:</u> The results of this test will verify that the pump meets design expectations, that is of being able to run off of a helium kbottle <u>Time Requirement:</u> 10 man hours



<u>Requirements met at test completion:</u>

• DR1.1 - Pump operates with a Helium K-Bottle







Throttle Profile Testing

<u>Test Rationale</u>: Verify that control algorithms drive the system through a desired throttle profile. Quantify accuracy of control system and slew rates

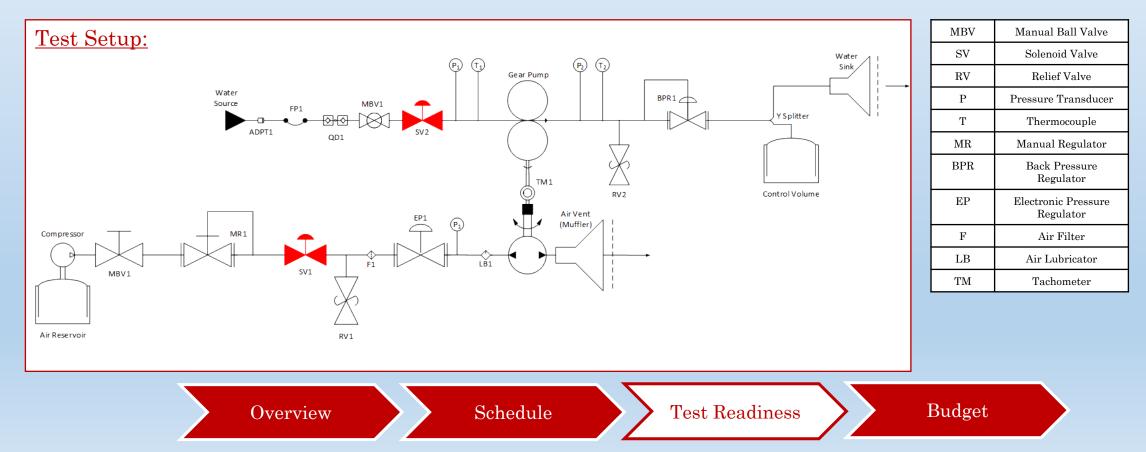


Equipment required:

• Complete Assembly of all systems, operational DAQ and control components

<u>Facilities required</u>:

• Air compressor providing 100PSI Air @45CFM, provided on East Campus





Throttle Profile Testing

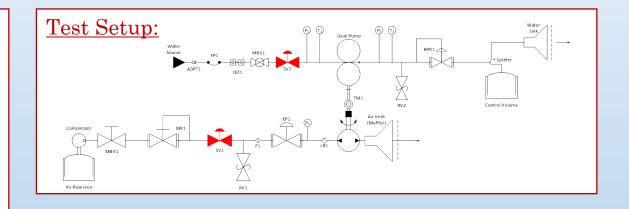


Test Procedure:

The DAQ system is loaded with a desired throttle setting (constant). The pump is set to run, the full system operation is monitored and recorded.

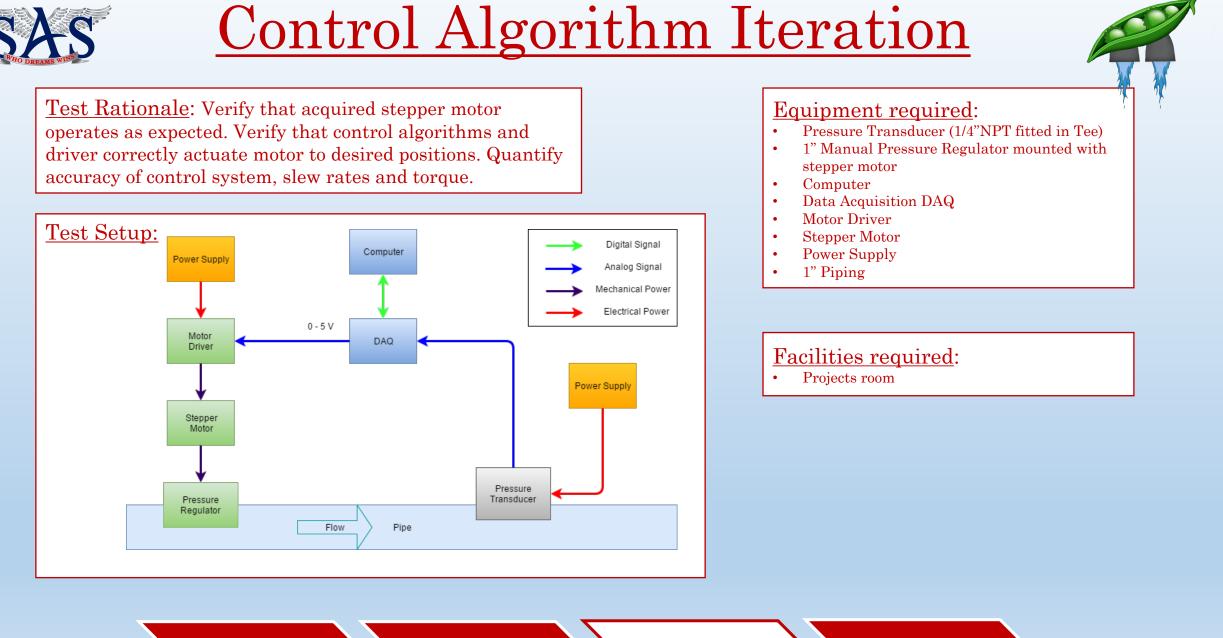
Risk Mitigation: The results of this test will verify that the pump system can correctly run a throttle profile. Successfully doing this would demonstrate the completeness of the project.

Time Requirement: 15 man hours



<u>Requirements met at test completion:</u> •

All requirements are met at this point



Overview

Schedule





Control Algorithm Iteration

Test Procedure:

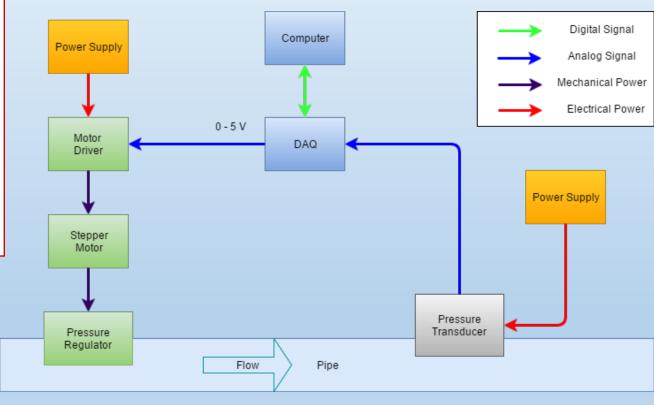
LabVIEW will be set to a specific pressure where the computer will control stepper motor to regulated the pressure through the pressure regulator. Different pressures will be tested to understand the slew rate for the system.

<u>Risk Mitigation:</u> The results of this test will verify that the stepper motor can actuate the regulator to the desire pressure, in order to guarantee electronic throttle-ability. This test will also quantify the slew rate of this control system.

<u>Time Requirement:</u> 20 man hours

<u>Requirements met at test completion:</u>

• FR2 - Pump is electronically throttleable



Schedule





Budget







Catagory	Ordered	Unordered	Total	
Manufacturing	1998.58	0	1998.58	
Hardware	3356.22	750.30	4106.52	
Management	0	100.00	100.00	
Shipping	509.25	112.55	621.8	
		Total	\$6,826.90	
		Funds	\$8,000.00	
		Margin	17.18%	\$1,173.10

- 85.89% of Parts purchased (by dollar value)
- \$1173.10 of Margin!

*See backup slides for full itemized budget









Part	Price	Quantitity	Subtotal	Shipping	Total
Drivers	300	2.00	600	90.00	690.00
Report Printing/ Binding	100	1.00	100	0.00	100.00
Brackets	100	1.00	100	15.00	115.00
Coupler	25.15	2.00	50.3	7.55	57.85

Left to buy: \$962.85







Questions?

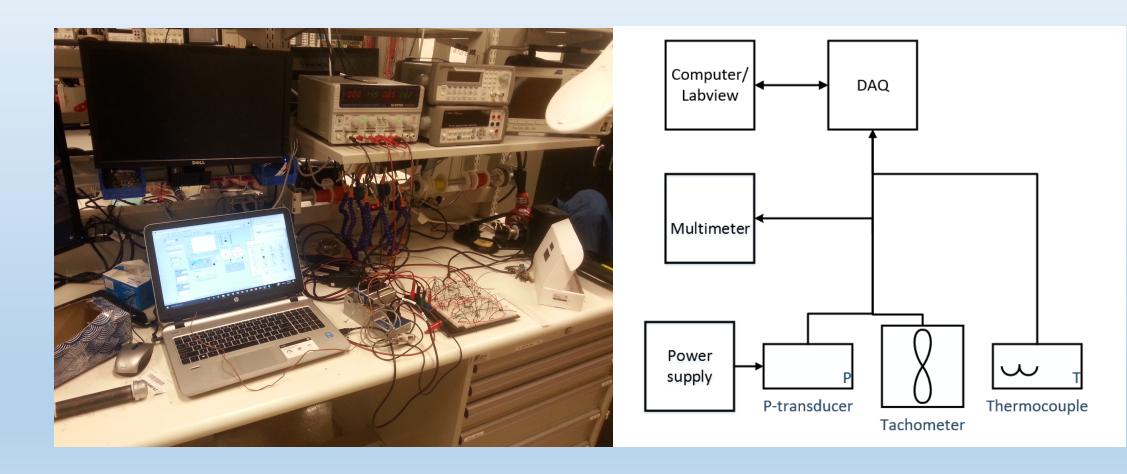




Backup













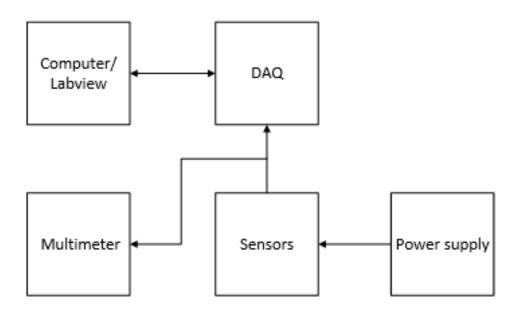
- Goals
 - Determine data variance and system (non-sensor) error
 - Qualitatively verify all datalinks work
- Equipment
 - DAQ
 - PC (with LabVIEW)
 - Thermocouples
 - Pressure transducers
 - Tachometer
 - Solenoid valves
 - DC power supply





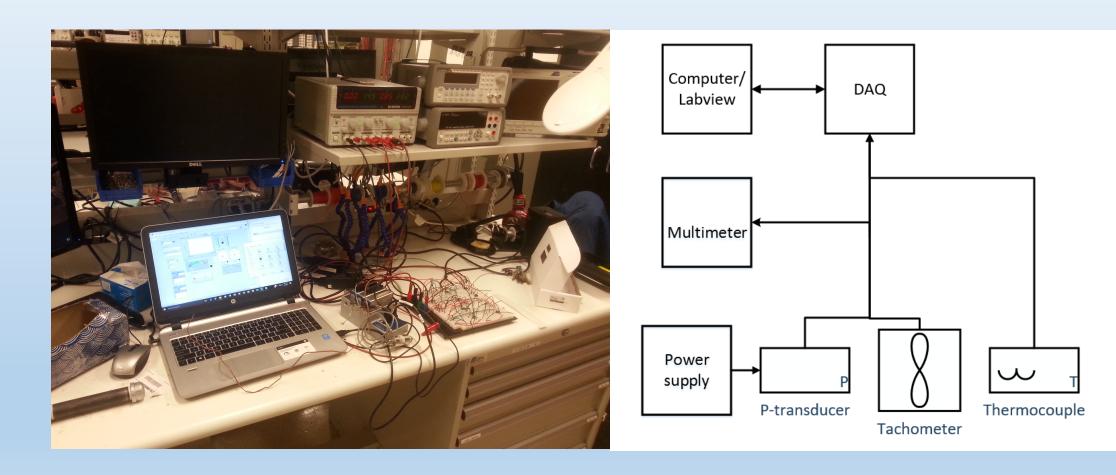
System Tests

- Procedure
 - Connect all devices appropriately
 - Run LabVIEW code (LabVIEWDAQpractice10) collect pressure, temperature, tachometer data
 - Stop code, save data
 - Analyze data on MATLAB













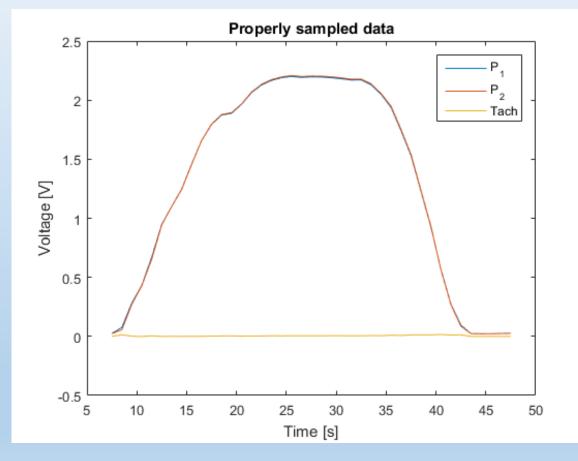


Results:

- Nominal sample rate limited to 1 kHz
- Max error 4 mV (vs multimeter)
- Data spiking (right) corrected by using lower sample rate (rate shown: 1 kHz)

Verified

- Accuracy of thermocouple, pressure, and tachometer readings
- Maximum control loop rate
- Control possible, gain limits to be determined



DAQ Input Testing

<u>Goals:</u> Verify correct real-time acquisition of data from pressure transducer, thermocouple, and tachometer

- <u>Procedure highlights</u>
 - Connect equipment
 - Run control and data VI
 - Measure pressure/tachometer data
 - Vary pressure and test device rotation speed
 - Run emergency shutoff
 - Stop VI
 - Process Data

<u>Equipment required</u>:

- 1 Pressure Regulator Test setup
- 1 thermocouple
- 1 tachometer
- 1 power drill (modified)
- 1 DAQ and PC system
- 1 DC power supply
- 1 multimeter

<u>Risk Mitigation</u>: The results of this test will ensure the certainty of data being measured from the pump, and validate the safety and control systems





Received	Ordered	Part	Part #	Price	Quantity	subtotal	Shipping	Total
x	x	Globe Motor	VA10J	1238.00	1	1238.00	125	1363.00
x	x	Tachometer		349.00	1	349.00	0	349.00
x	x	Reflective Tape		5.00	1	5.00	0	5.00
x	x	Reflective tab		5.00	1	5.00	0	5.00
x	x	Water Pipe		29.44	1	29.44	21.9	51.34
x	x	Hose2Pipe Adptr		4.81	4	19.24	10	29.24
x	x	Air Regulator		228.00	1	228.00	33.21	261.21
x	x	Pipe tee		14.27	2	28.54	15.3	43.84
x	x	Air filter		78.10	1	78.10	0	78.10
x	x	lubricator		82.58	1	82.58	0	82.58
x	x	lube		24.47	1	24.47	0	24.47
x	x	steel pipe		14.72	1	14.72	27.21	41.93
x	x	pipe nipple		3.93	1	3.93	0	3.93
x	x	brass valve		18.53	1	18.53	0	18.53
x	x	steel pipe		7.78	1	7.78	0	7.78
x	x	3 port ball valve		35.83	1	35.83	0	35.83
x	x	bushing adapter		8.56	1	8.56	0	8.56
x	x	hose 1		12.00	1	12.00	0	12.00
x	x	hose 2		12.33	1	12.33	0	12.33
x	x	pipe		79.72	1	79.72	0	79.72
x	x	bushing adapter		13.76	1	13.76	0	13.76
x	x	inline tee		8.68	2	17.36	0	17.36

x	x	stepper motor	0.00	1	0.00	0	0.00
x	x	3/4 solenoid	64.95	1	64.95	0	64.95
x	x	1" solenoid	87.95	1	87.95	0	87.95
x	x	Flexible Steel Hose	57.37	1	57.37	11.25	68.62
	x	EDM	1150.00	1	1150.00	0	1150.00
	x	BPRegulator	652.00	1	652.00	25.22	677.22
x	x	Housing block	495.00	1	495.00	113.87	608.87
x	x	304 Bushing	7.70	1	7.70	6.6	14.30
x	x	304 Straight Connector	11.30	1	11.30	0	11.30
x	x	Inline Tee Reducer	8.68	2	17.36	0	17.36
x	x	304 Stainless Bushing Female	7.70	1	7.70	0	7.70
x	x	Back Plate	125.00	1	125.00	0	125.00
	x	Pressure Relief Valve	69.00	2	138.00	9.99	147.99
		brackets	100.00	1	100.00	15	115.00
		coupler	25.15	2	50.30	7.55	57.85
x	x	Aluminum plate	43.58	1	43.58	8.63	52.21
x	x	Aluminum rod	26.00	1	26.00	6.21	32.21
		Drivers	300.00	2	600.00	90	690.00
	x	tooling	159.00	1	159.00	6.21	165.21
x	x	teflon seal	0.00	1	0.00	0	0.00
		report binding	100.00	1	100.00	0	100.00
x	x	microsoft office	0.00	1	0.00	0	0.00
x	x	labview	0.00	1	0.00	0	0.00
x	x	Matlab	0.00	1	0.00	0	0.00
x	x	solidworks	0.00	1	0.00	0	0.00
x	x	Gantter	0.00	1	0.00	0	0.00