



Smead Aerospace

UNIVERSITY OF COLORADO BOULDER



Deep-Space Orbital Telecommunications

Sam Taylor, Tristan Liu, Caelan Maitland, Forrest Jordan, Hunter Rohlman, N. Sebastian Damm, Doug Brough, Conner Lewis, Buck Guthrie, Jennifer Gurtler



Mission Statement

Project DOTCOM is a research-heavy **system modeling** assignment. In this, we explore the functionality and viability of a communications network architecture between the Earth and Moon. The purpose of this project is to **develop software models** to design and optimize a **Lunar communications network**, packaged through **Model-Based System Engineering**.



Table of Contents

1 Project Overview

- 1.1 Performance Targets
- 1.2 Critical Project Elements
- 1.3 CONOPS
- 1.4 Baseline Design
- 1.5 FBD

2 Testing

- 2.1 System Architecture Models
- 2.2 Network Capacity Model
- 2.3 Link Budget Models
- 2.4 ION-DTN Model
- 2.5 SysML Systems Engineering Model
- 2.6 Testing Summary

3 Project Schedule

- 3.1 Schedule Overview
- 3.2 System Architecture Schedule
- 3.3 MBSE Schedule
- 3.4 Hardware Schedule

4 Budget

- 1.1 Procurement Updates
- 1.2 Budget Summary

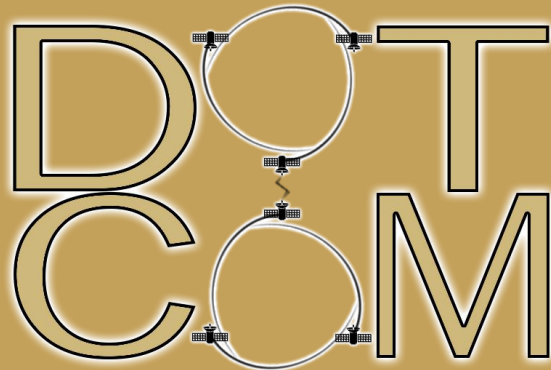
Project Overview

Project Overview

Testing

Project Schedule

Budget





Network Performance Targets



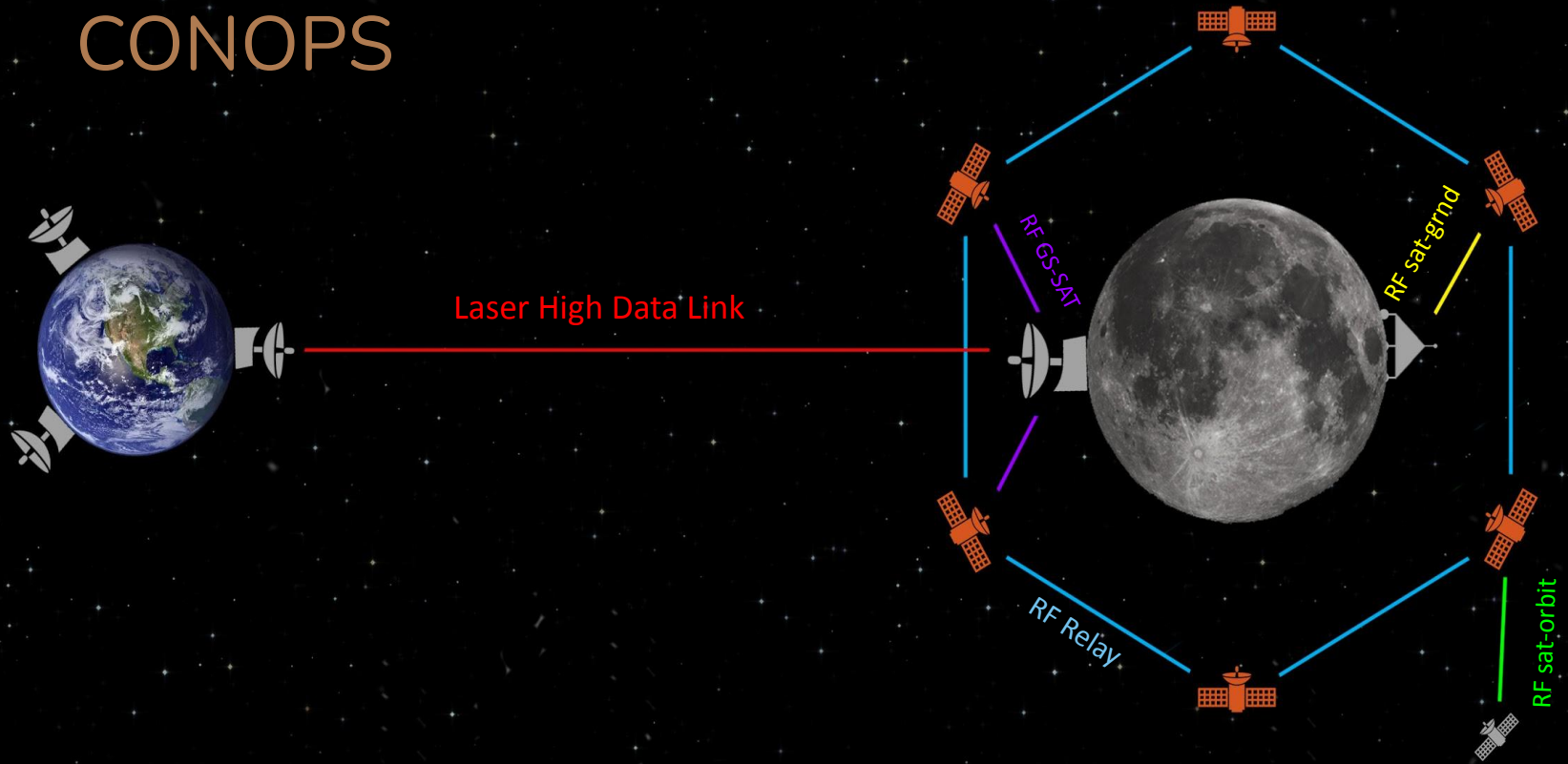
Functional Requirement	Design Requirement
FR 1	99% telecommunications coverage in Lunar orbit
Area Coverage	99% telecommunications coverage on Lunar Surface
FR 2	5+ nodes for simultaneous 'real time' communications on Lunar surface
Endpoint Support	10+ nodes for non simultaneous (within 6 hrs) communication on Lunar surface
	10+ nodes for simultaneous 'real time' communication in Lunar orbit
	20+ nodes for non-simultaneous (within 6 hrs) communication in Lunar orbit
	Earth-Moon data rates: 500 Mbps threshold, 5 Gbps objective
FR 3 Compatibility	Network is compatible with and ensures the safety of existing and future infrastructure



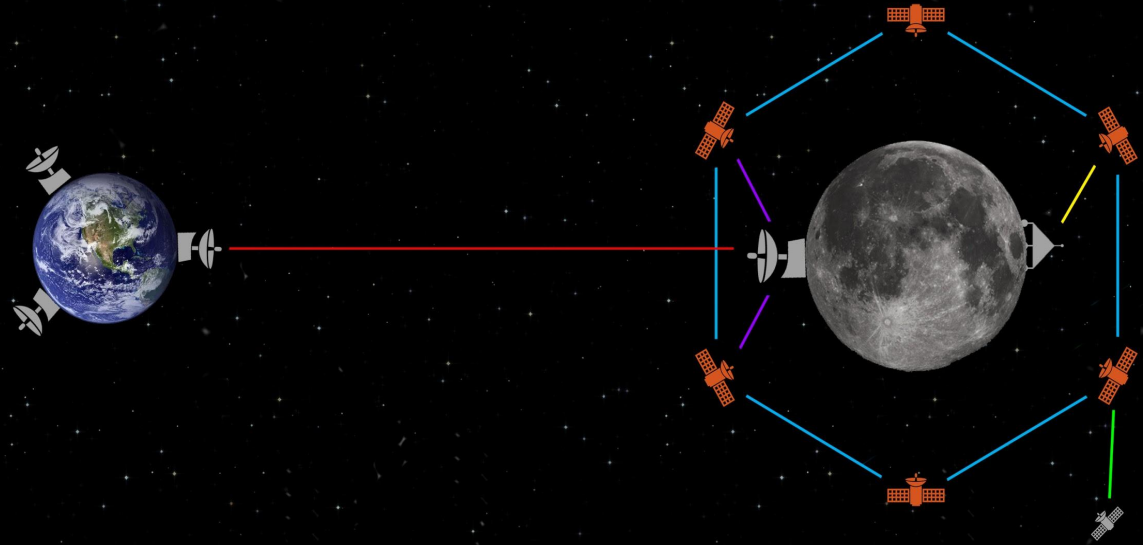
Critical Project Elements

Designation	CPE	Critical Characteristics
CPE-1	Network Protocol	Structured data transmission methodology that allows for high speed reliable communications from node to node.
CPE-2	System Link Budgets	The project will meet certain data-relay rates for communication between all communication nodes.
CPE-3	Relay Stations	Allows for direct access to communications between Earth and The Moon.
CPE-4	Satellite Constellation	Construction of ideal constellation architecture around each planetary body to satisfy coverage requirements.

CONOPS



Baseline Link Budgets

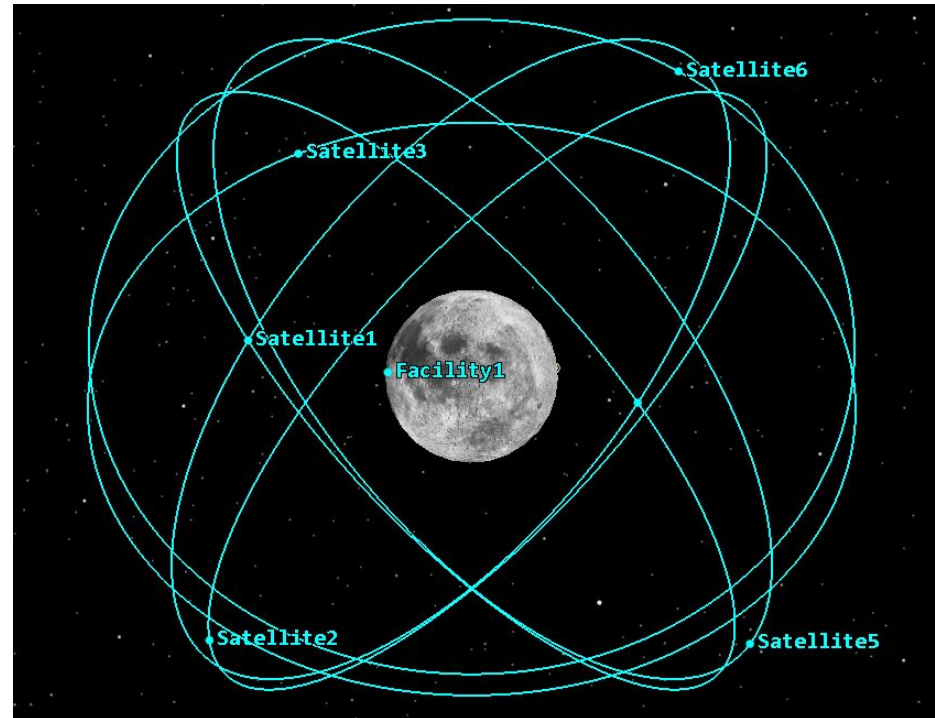


Variables	Satellite to Satellite	Ground Station to Satellite	Orbital Vehicle to Satellite	Ground Vehicle to Satellite	Ground Station to Ground Station
Range	11,024 km	5,509 km	TBD	5,509 km	384,000 km
Frequency	Ka-band (26 GHz)	Ka-band(26 GHz)	Ka-band (26 GHz)	Ka-band(26 GHz)	193.4 THz (1550 nm)
Antenna Size	1 m	1 m	.5 m	.1 m	1.5 m
Receive System Noise Temperature	700 K (Source: ITU)	300 K (Source: Sat. Antenna Trade Study)	700 K	300 K	N/A



Baseline Constellation

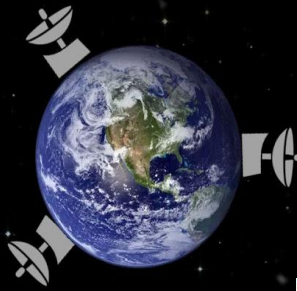
Constellation Design Parameters	Values
Range to Ground	5509 km
Range to Adjacent Satellites	9173-11024 km
Configuration	Walker-Delta 6/6/4
Orbital Period	15.38 hrs
Coverage	Single



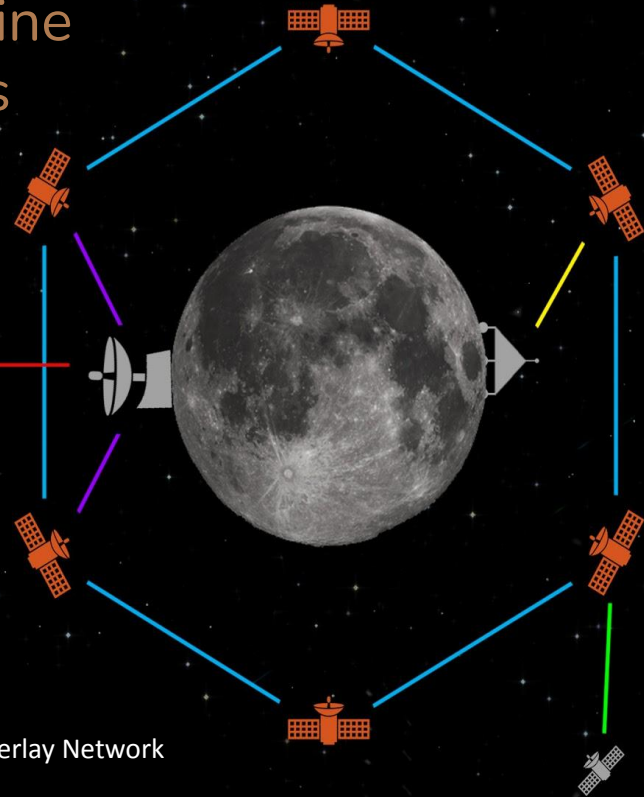
Deep Space Relay Stations

- 3 Earth Ground Stations
120° apart
- 1 Lunar Ground Station at
center of “light” side

Additional Baseline Considerations



User application, e.g., data manager			
CFDP (unacknowledged mode)		AMS messaging	
UT adapter		Remote AMS bridging	
BP DTN routing			
Convergence layer adapters			
LTP		TCP, BRS, UDP, DGR	
encapsulation packets		IP Internet routing	
AOS	Prox-1	802.11	Ethernet
R/F, optical		wire	

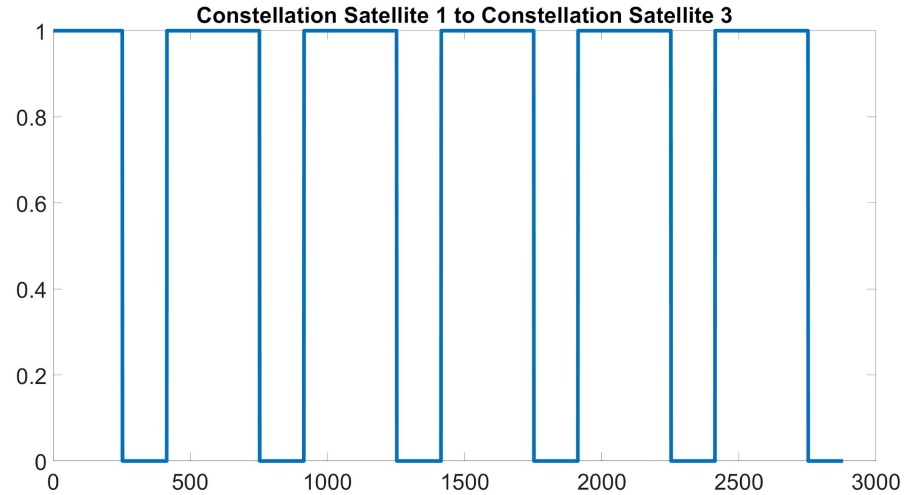
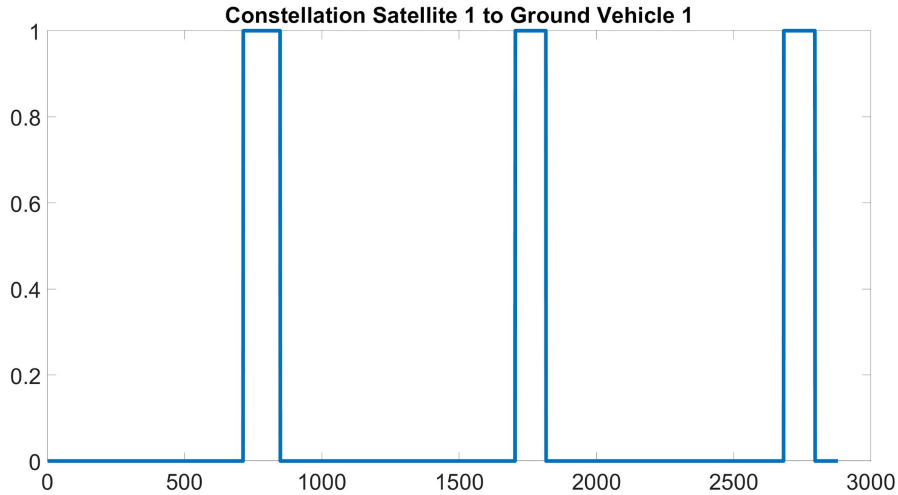


Network Protocol

- Interplanetary Overlay Network (NASA JPL)
- Implements Delay Tolerant Networking (DTN)

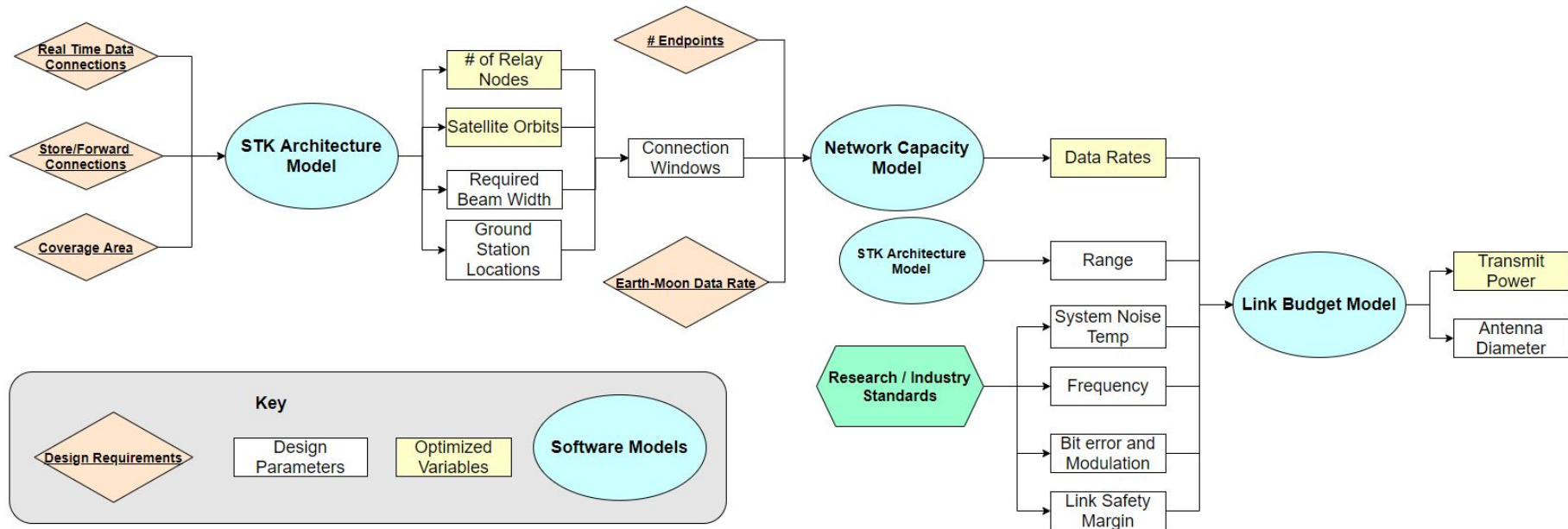


Connection Window Examples





Optimization FBD



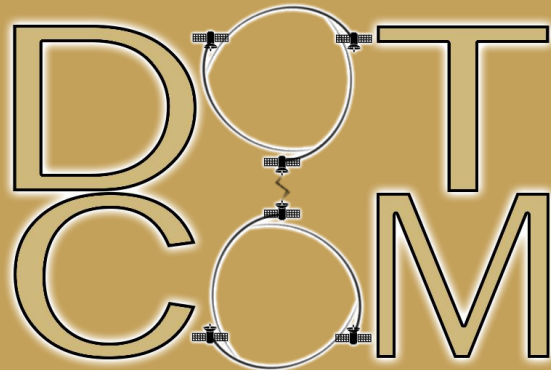
Testing

Project Purpose & Objectives

Testing

Project Schedule

Budget





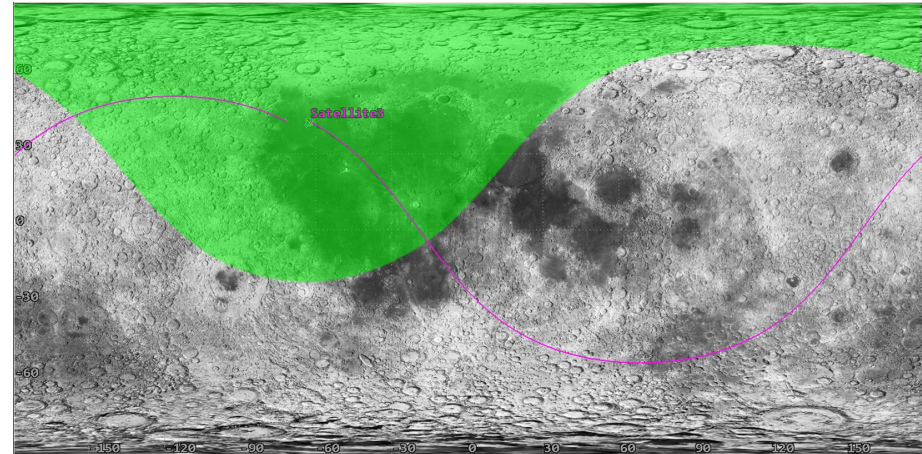
Network Coverage Test

Desired Outcomes:

- Verify that a particular orbit geometry is able to provide >99% coverage of lunar surface and orbit
- Ensure FR1 is met

Test Design:

- Import satellite ephemeris from STK
- Numerically assess the ability of points in the lunar system to connect into the network at each time





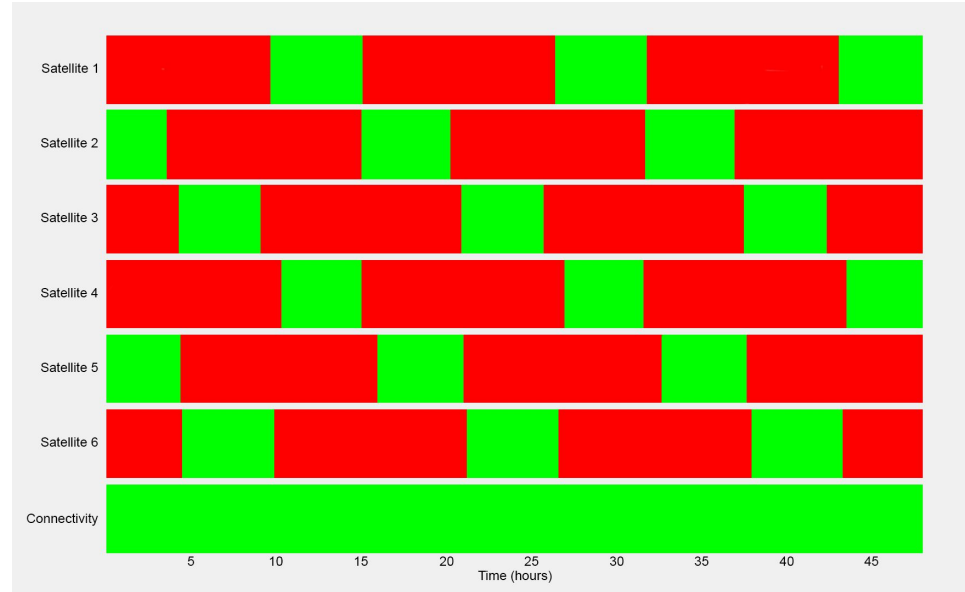
Continuous Connection Test

Desired Outcomes:

- Verify that a particular network configuration allows for **uninterrupted data flow at all times** for required number of nodes
- Ensure **FR 2** is met

Test Design:

- Import **STK network configuration**
- Calculate connection windows for each node
- Verify that connections between endpoints needing continuous connection are **always available**





Data Rate Optimization Test



Desired Outcomes:

1. Optimize data rates
2. Ensure **FR 2** - endpoint communication support is met

Test Design:

1. Vary input/output data rates and **observe changes** to network capacity outputs
2. Performed using the **Network Capacity Model** written in MATLAB



Data Rate Optimization Test - Variables and Controls

Independent Variables:

- Earth Ground Station data rate
- Moon Ground Station data rate
- Constellation Satellite data rate

Controls:

- Connection Windows
- Number of surface vehicles/constellation satellites/ground stations.
- Data generation in network

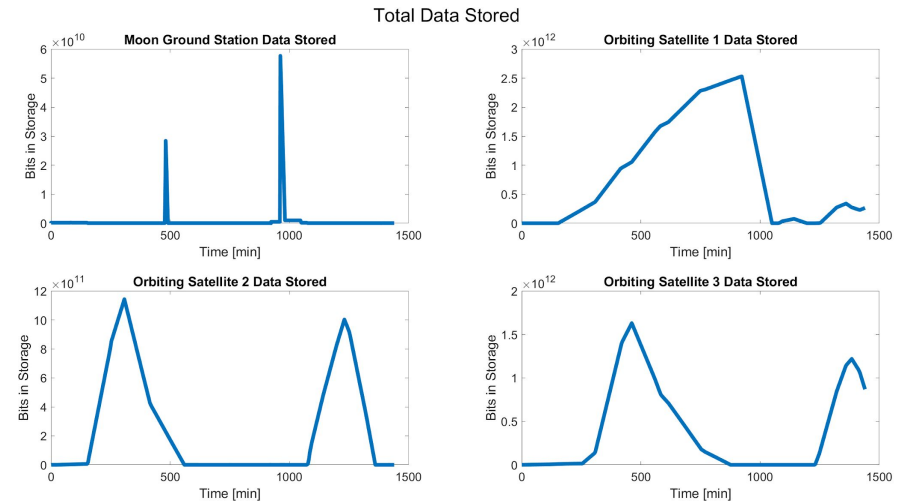
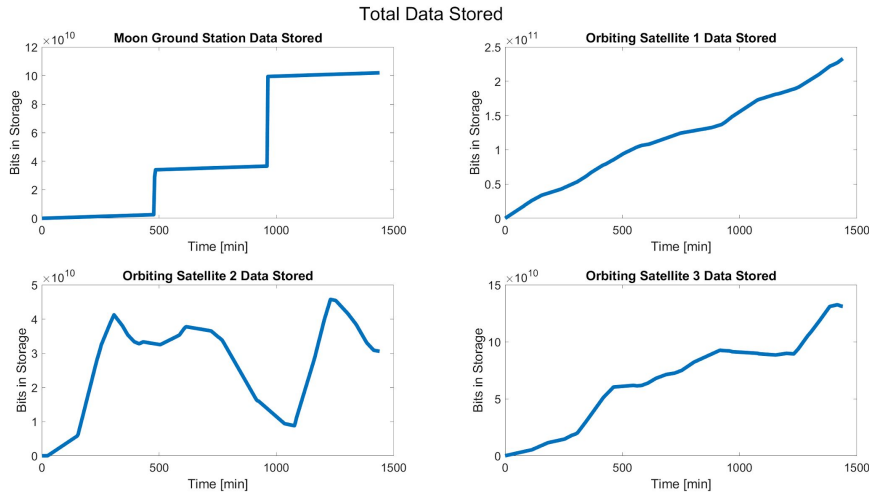


Data Rate Test - Design and Expectations



Over Capacity Network

Under Capacity Network



*An over capacity network **cannot distribute data fast enough** to overcome the incoming data, this gradually fills each node's internal storage

*An under capacity network manages to distribute data to the respective nodes **quicker than the internal storage can fill.**



Capacity Model Hardware Validation Test

Desired Outcomes:

Validate capacity model calculation method through **hardware comparison**.

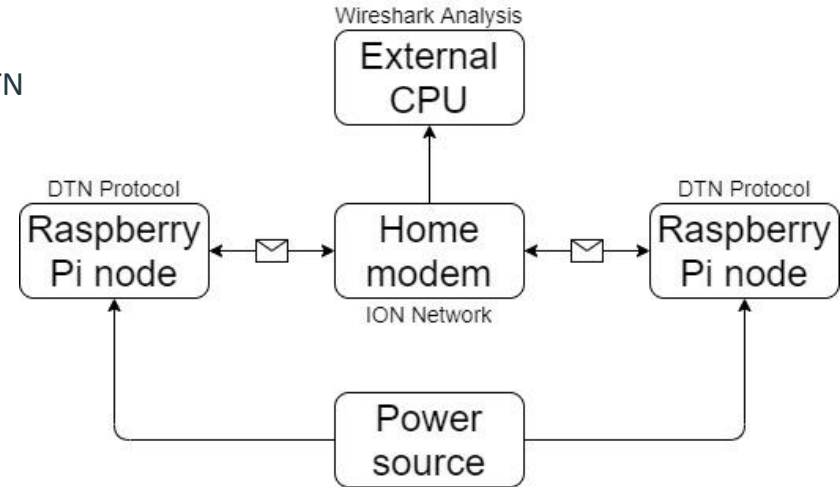
Test Design:

Build a r-pi network of nodes and observe its **data storage behavior**. Match behavior to **hypothesized behavior** generated from capacity model.



Capacity Model Hardware Test Setup

- **Setup**
 - Raspberry Pi nodes configured and running ION-DTN
- **Procedures**
 - Send data throughout the system
- **Collected Data (Wireshark)**
 - Timestamps of data sent and received
 - Data stored in each node
- **Data Analyzation (MATLAB)**
 - Data stored in each node over time
 - Hardware and Software Latency Values





Power Optimization Test

Desired Outcomes:

1. **Optimize power required** in each link budget
2. Ensure data links fall within **acceptable safety factors**

Test Design:

1. Vary key design parameters and observe the **impact to** transmission power required
2. Performed using the **Link Budget** MatLab software model



Power Optimization Test - Variables and Controls

Optimized Parameter:

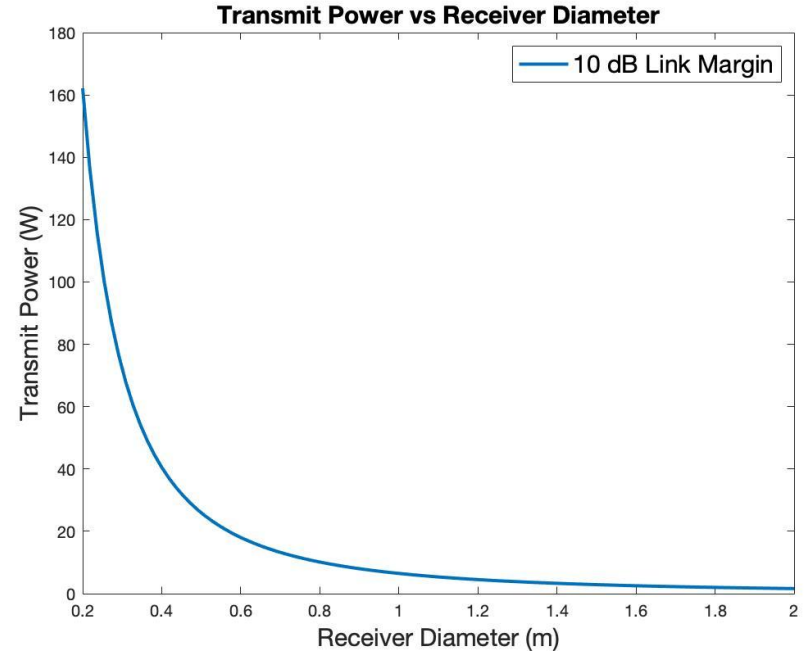
- Power

Independent Variable:

- Antenna Size

Main Control Variables:

- Frequency
- Range
- Data Rate





Link Budget Validation Tests



- AMSAT IARU Link Budget Calculator
 - Check against our link budget model
- Study on Intersatellite Link Antenna
 - Trade off of satellite antennas with associated link budgets



MBSE Validation Test

Desired Outcome:

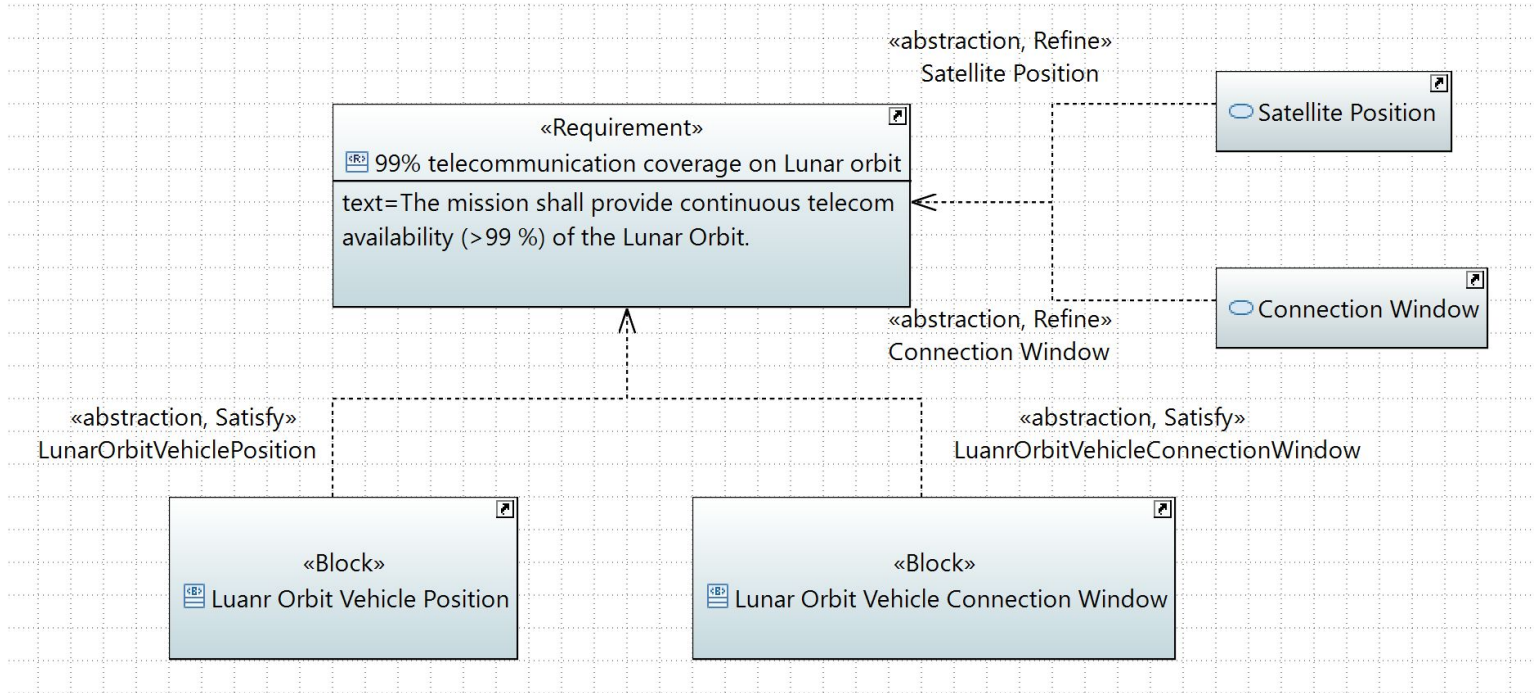
- The output data from system architecture, network capacity and link budget satisfy the project requirement

Test Design:

- **SysML** simulates the output data by tracing requirement to the subsystems to check if they are satisfy the project requirements
- The output data is the text file data that formats in TLE's (Two-line element set)



	A	B
	name : String [0..1]	/satisfiedBy : NamedElement [*]
0 /ownedElement		
1 FR-1: Comms must have transmit/receive capability simultaneously & non-simultaneously between Earth, Moon, Mars.	FR-1: Comms must have transmit/receive capability simultaneously & non-simultaneously between Earth, Moon, Mars.	x
2 /ownedElement		
3 R-001: Real time data relay between environments	R-001: Real time data relay between environments	AntennaIO, AntennaIO, AntennaIO
4 R-005: Data relay between mission segments.	R-005: Data relay between mission segments.	LunarSat, EarthSat, EarthGroundStation, LunarGroundStation
5 R-008: Simultaneous comms to 5 locations on Lunar surface.	R-008: Simultaneous comms to 5 locations on Lunar surface.	inboundSignalProcessing, outboundSignalProcessing
6 R-009: Non-simultaneous comms to 10+ locations on Lunar surface.	R-009: Non-simultaneous comms to 10+ locations on Lunar surface.	inboundSignalProcessing, outboundSignalProcessing, centralStorage





Test Status

- 1) **Architecture Tests**
 - a) **Done:** Established >99% coverage geometry for all time steps
 - b) **In progress:** Verify continuous connection windows for all required nodes
- 2) **Network Capacity**
 - a) **Done:** Created data rate design for an under and over capacity system
 - b) **In progress:** Optimize design to find critical data rates while staying under capacity
- 3) **Link Budget**
 - a) **Done:** Optimized for baseline case
 - b) **In progress:** Optimization for different links
- 4) **Hardware**
 - a) **Done:** Concept proven → 2 Raspberry Pis running ION-DTN
 - b) **In progress:** Establish connection between two nodes, analyze network traffic via Wireshark, determine test node scalability
- 5) **MBSE**
 - a) **Done:** Created the block definition diagram, internal block diagram, and use case diagram
 - b) **In progress:** other structural diagrams and behavioral diagrams that apply to the requirement tracing, implement output data from each subteam to the SysML to do requirement tracking

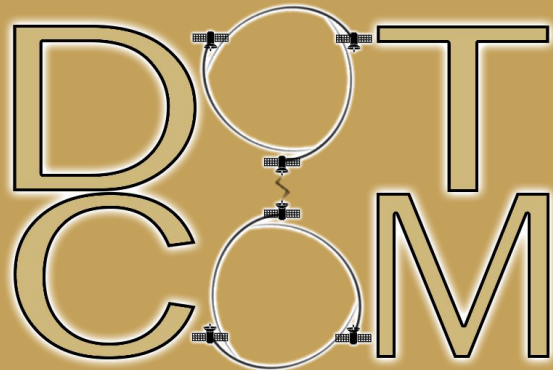
Project Schedule

Project Purpose & Objectives

Testing

Project Schedule

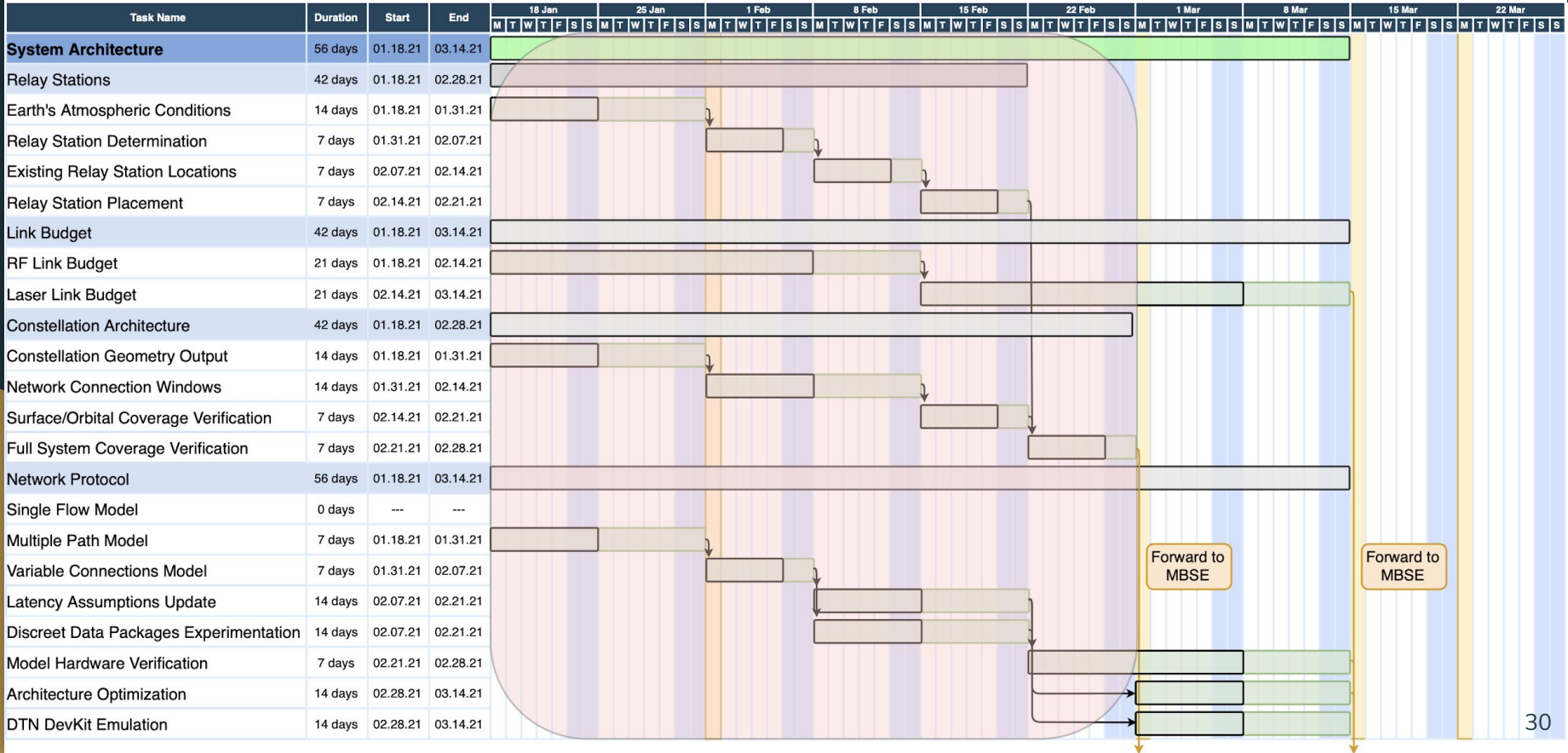
Budget



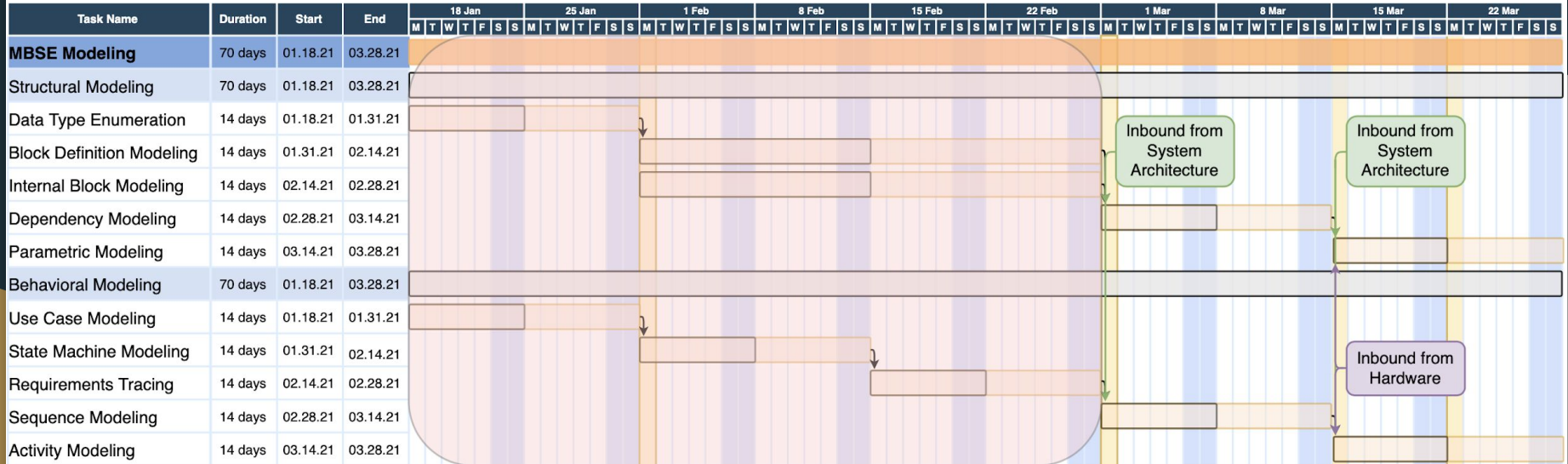
Schedule Overview



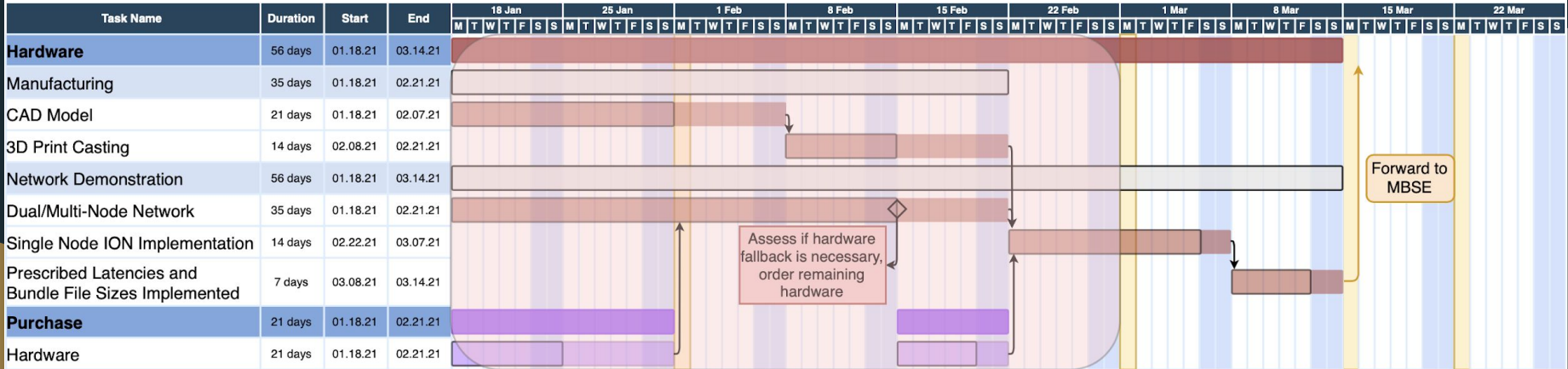
System Architecture Schedule



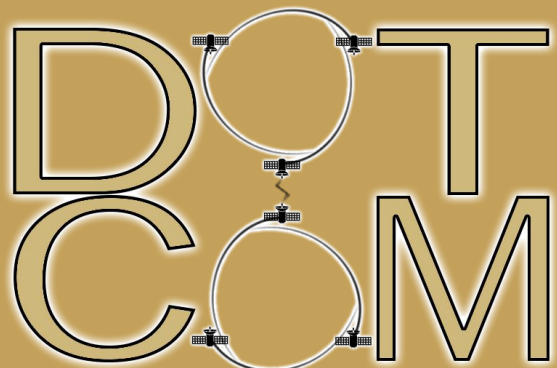
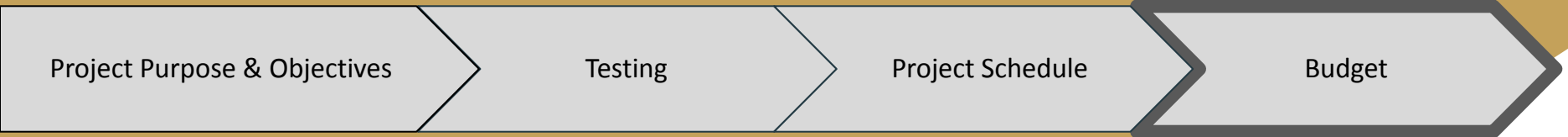
MBSE Schedule



Hardware Schedule



Budget





Hardware Procurement Update



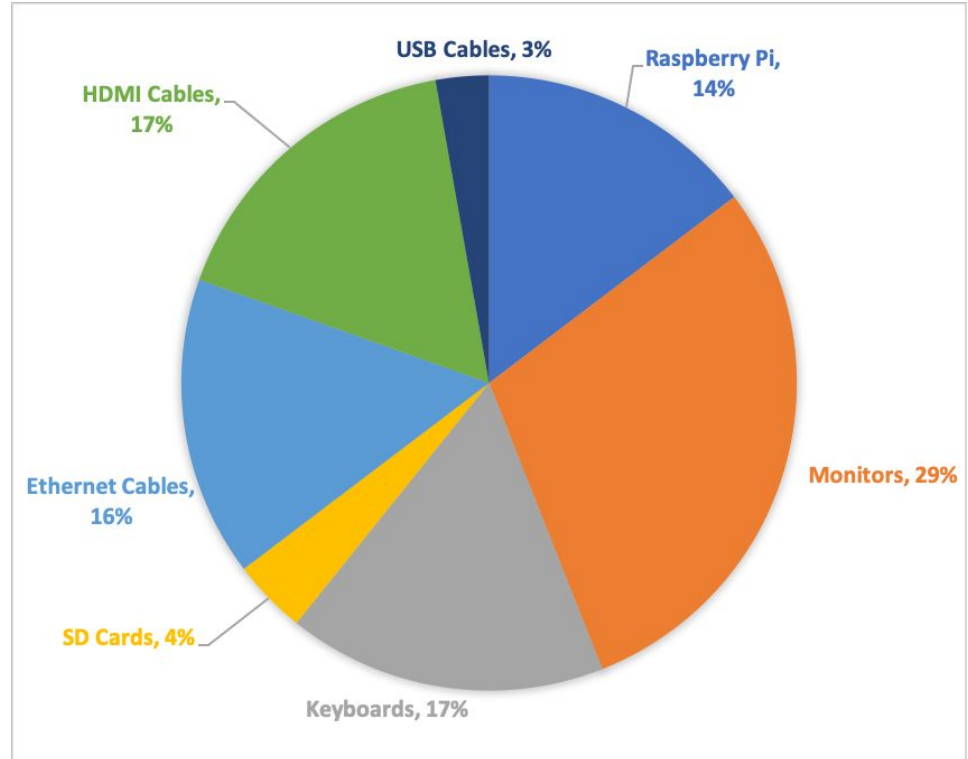
Hardware Parts	Status
2 Raspberry Pis	Received
2 Monitors	Received
2 HDMI Cables	Received
2 Keyboards	Received
2 Ethernet Cables	Received
Total:	\$538.92

Hardware Parts	Status
1 Raspberry Pi	Ordered
2 SD Cards	Yet to be purchased
2 HDMI Cables	Yet to be purchased
2 Ethernet Cables	Yet to be purchased
Total:	\$184.88



Updated Budget

Raspberry Pi (3)
Monitors (2)
SD Cards (2)
Keyboards (2)
HDMI Cables (4)
Ethernet Cables (4)
Total: \$723.80
Margin: \$4,276.20





Smead Aerospace
UNIVERSITY OF COLORADO BOULDER

A space-themed background image showing Earth, the Moon, and Mars. Earth is in the foreground on the left, the Moon is in the middle ground, and Mars is on the right. The scene is set against a dark, starry space background with some nebulae and dust.

Questions?

APPENDIX

Power Optimization Variables

Link Parameters	Value
Max Range	11,024 km
Frequency	26 GHz
Antenna Size (Diameter)	Varied
Transmit Power	Output
Data Rate	50 Mbps
Receive System Noise Temperature	700 K *
Required Eb/No [BPSK Modulation, BER = 10 ⁻⁷]	11 dB
Required Safety Design Margin	3 dB
Link Margin	10 dB

*Source: Robert C. Morre, "Satellite RF Communications and Onboard Processing", Encyclopedia of physical Science and Technology (Third Edition), 2003

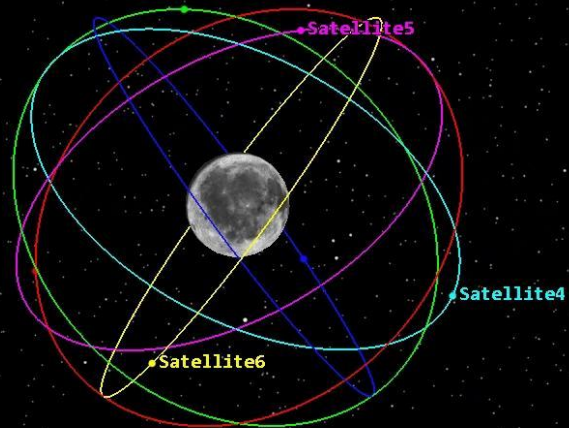
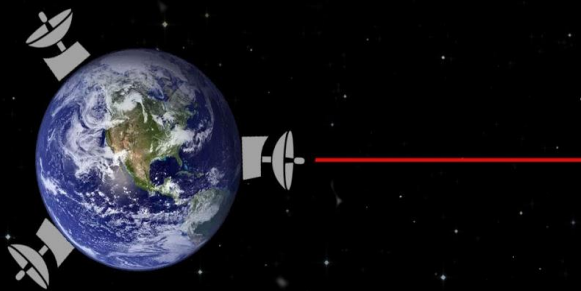
Baseline Parameters for Intersatellite Link

Key Input Variables	Value
Range (km)*	11,024 km
Frequency (GHz)	26
Antenna Size (D)	1 m
Transmit Power (W)	30 W
Data Rate (Mbps)*	50 Mbps
Receive System Noise Temperature (K)	700 K
Required Eb/No (dB) [BPSK Modulation, BER = 10 ⁻⁷]*	11 dB
Required Design Margin*	3 dB

Outputs	Value
EIRP	61.9 dB
Antenna Gain	46.1 dB
Free Space Loss	200 dB
Received Power	-139.6 dB
Signal to Noise	19.5 dB
Link Margin	5.5 dB

Satellite Constellation Architecture

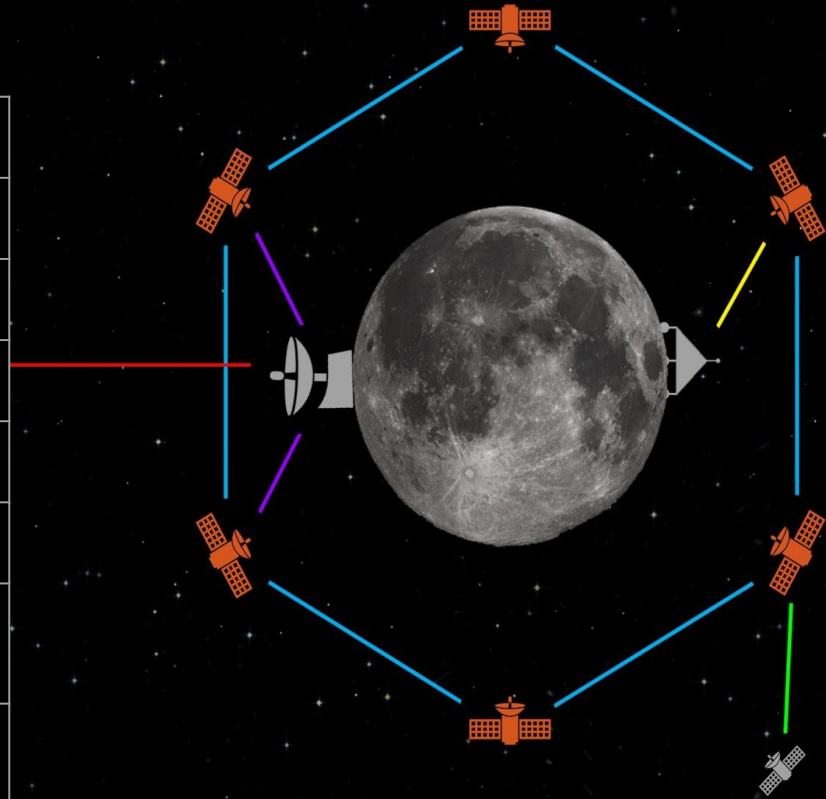
- Walker-Delta configuration
 - ~53 deg inclination
 - 6/6/4 configuration
 - MEO equivalent altitude

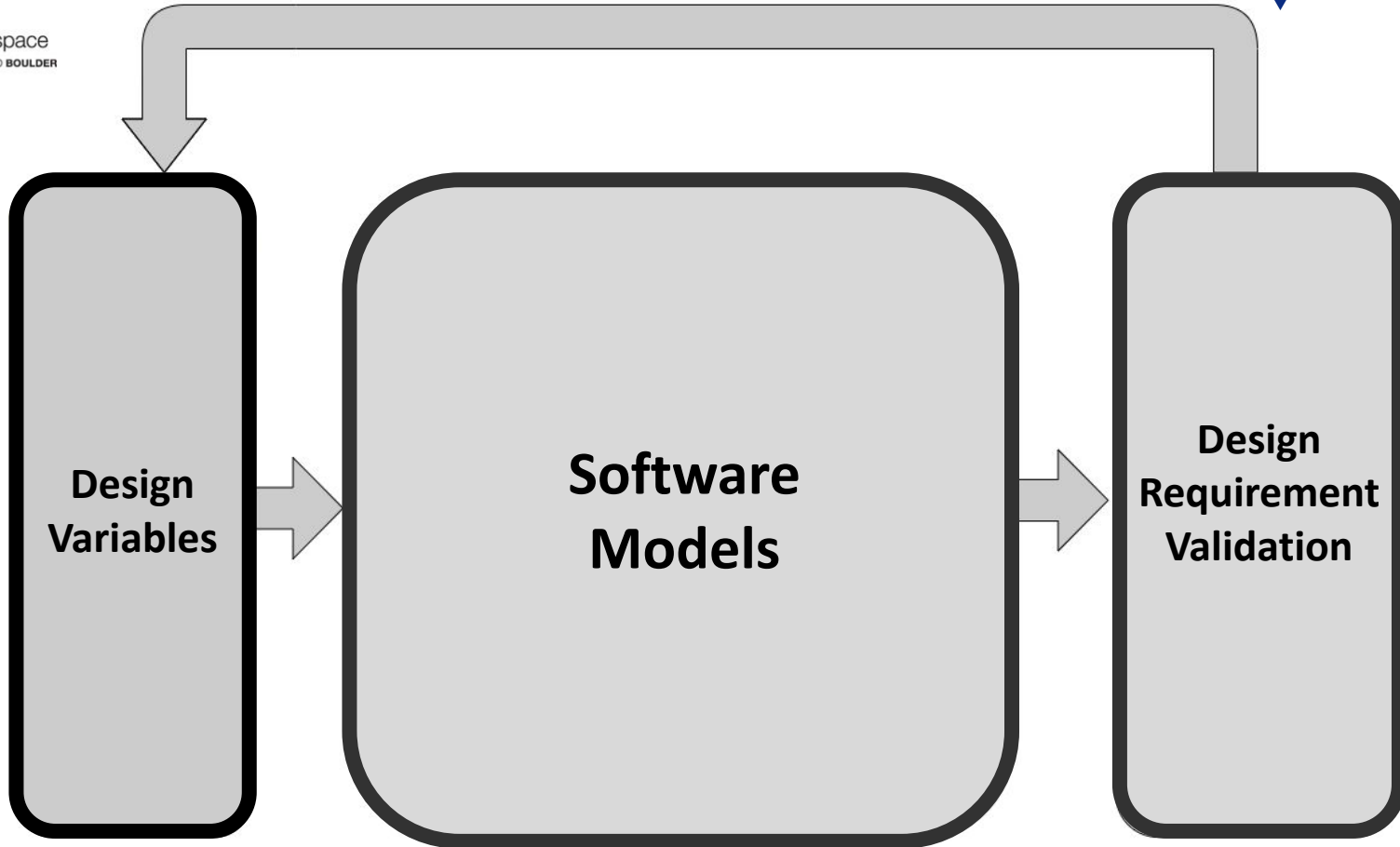


Moon Inertial Axes
29 Jan 2021 21:12:00.000 Time Step: 180.00 sec

Inter-Constellation Satellite Link Budget

Link Parameters	Value
Max Range	11,024 km
Frequency	26 GHz
Antenna Size (Diameter)	1 m
Transmit Power	30 W
Data Rate	500 Mbps
Receive System Noise Temperature	700 K
Required Eb/No [BPSK Modulation, BER = 10^{-7}]	11 dB
Required Safety Design Margin	3 dB







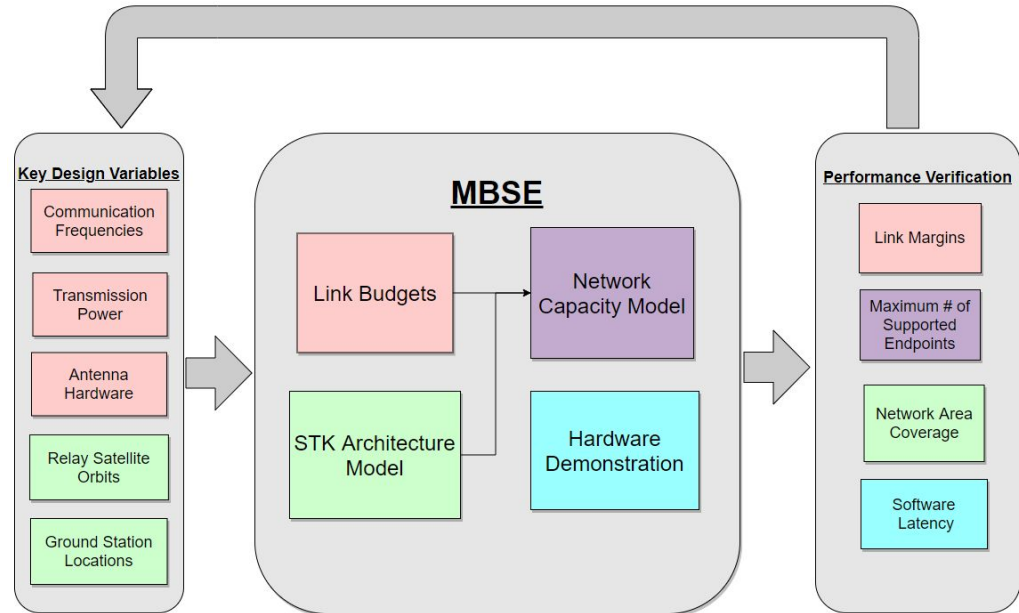
Manufacturing Tasks

To be **manufactured**:

- 1) STK Architecture Model
- 2) Network Link Budgets
- 3) Network Capacity Model
- 4) MBSE System Model

To be **purchased**:

- 5) Hardware Demonstration





STK Architecture Model



Purpose: Determine the ground station configuration and satellite constellation architecture necessary to enable 99% Lunar coverage and “real time” communication between the Earth and the moon.

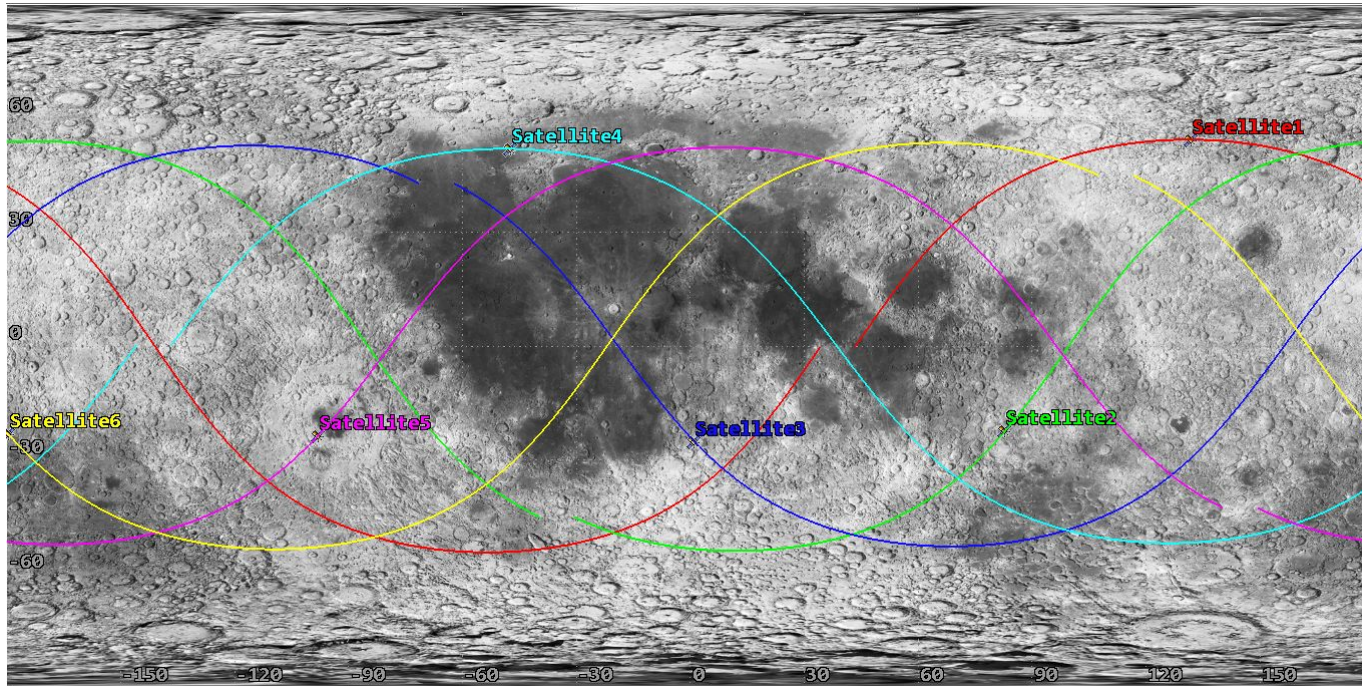
Model Logistics:

- Connection window simulation using Orbital STK
- **Inputs:** ground station locations (based on findings from atmospheric attenuation), satellite orbit geometry, satellite downlink beamwidth
- **Outputs:** Connection window illustration, 99% lunar coverage verification

Model Validation: Existing architecture verification (Deep Space Network), sensitivity analysis, and available literature/research.



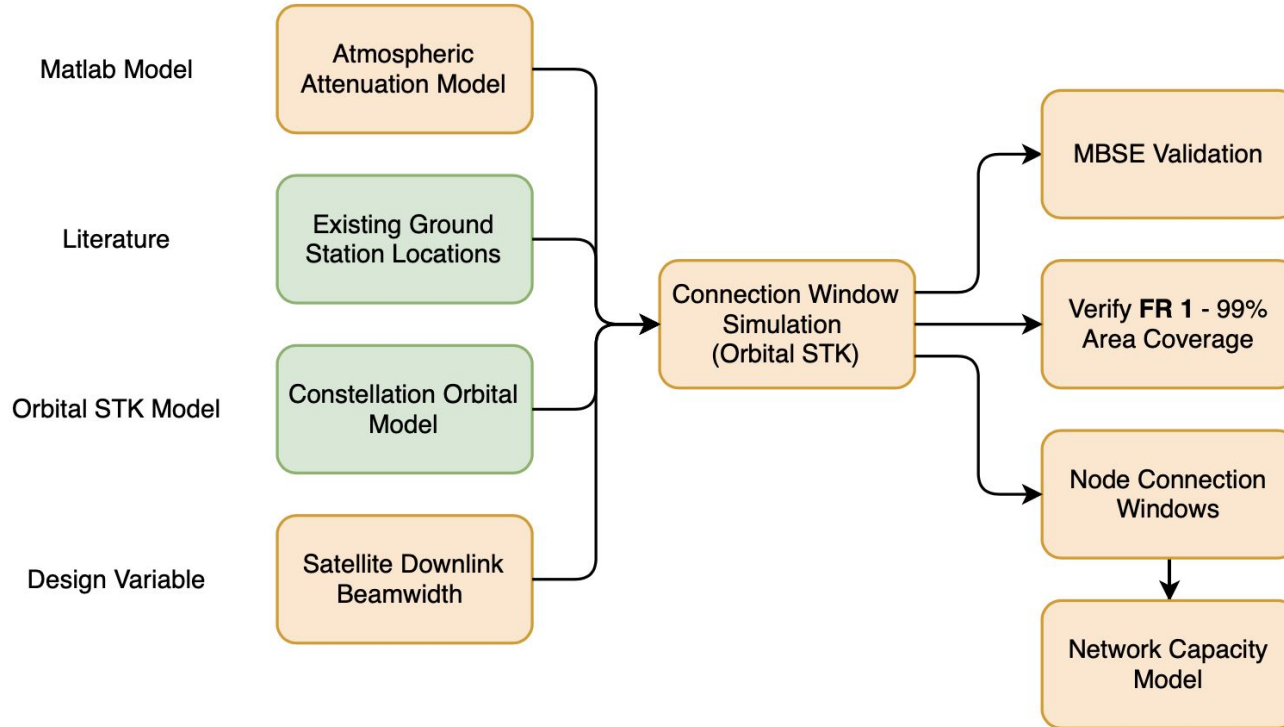
STK Constellation Orbital Model



*Pictured above (baseline design) - Walker J.G., Continuous Whole-Earth Coverage by Circular-Orbit Satellite Patterns, Royal Aircraft Establishment, September 23, 1977



STK Architecture Build Progress





RF Link Model

Purpose: Process necessary inputs to create a successful link (positive link margin)

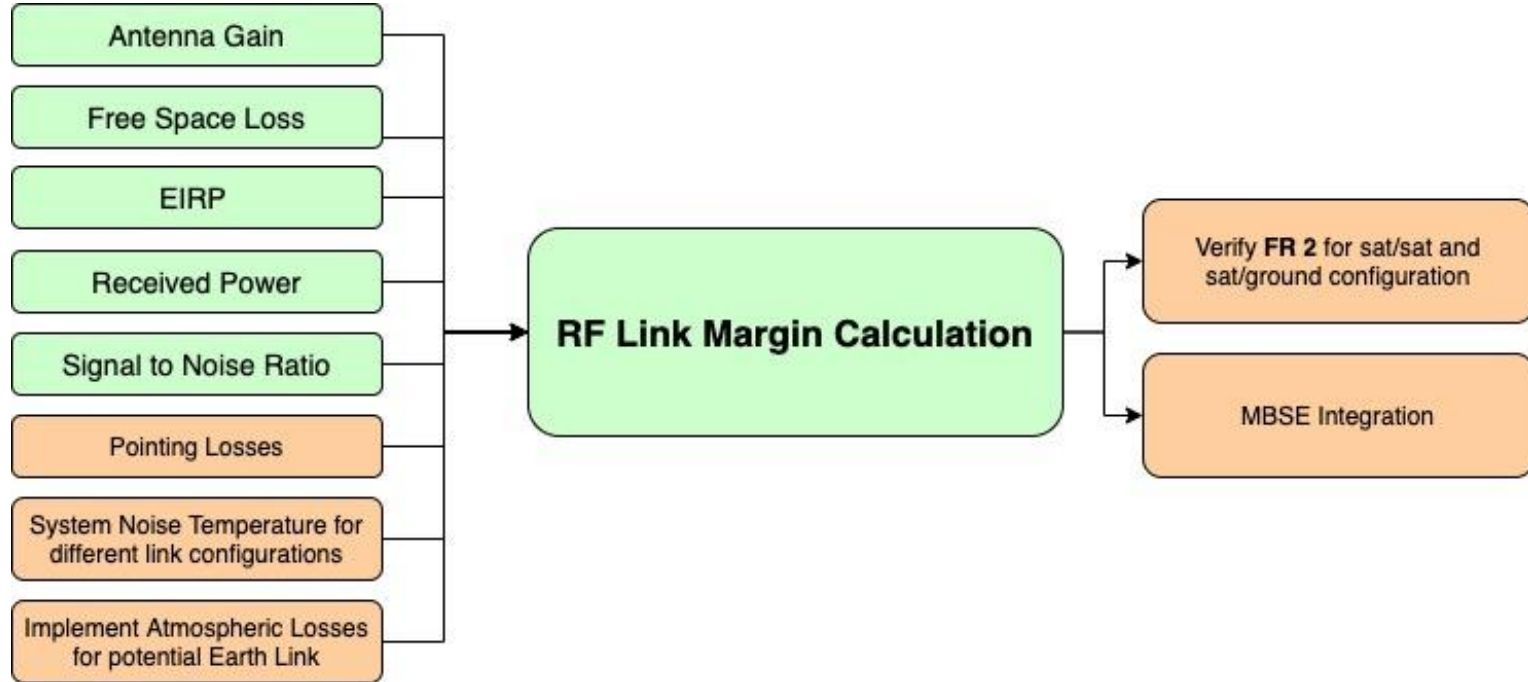
Model Logistics:

- Programmed using MatLab
- **Inputs:** Range, Frequency, Antenna Size, Transmit Power, Data Rate, System Noise temperature, Required Energy per bit to noise ratio (E_b/N_0) for desired BER, Required Design Margin
- **Outputs:** Link Margin

Model Validation: Available literature and research, sensitivity analysis



RF Link Model Progress





Laser Link Model



Purpose: Process necessary inputs to create a successful link (positive link margin)

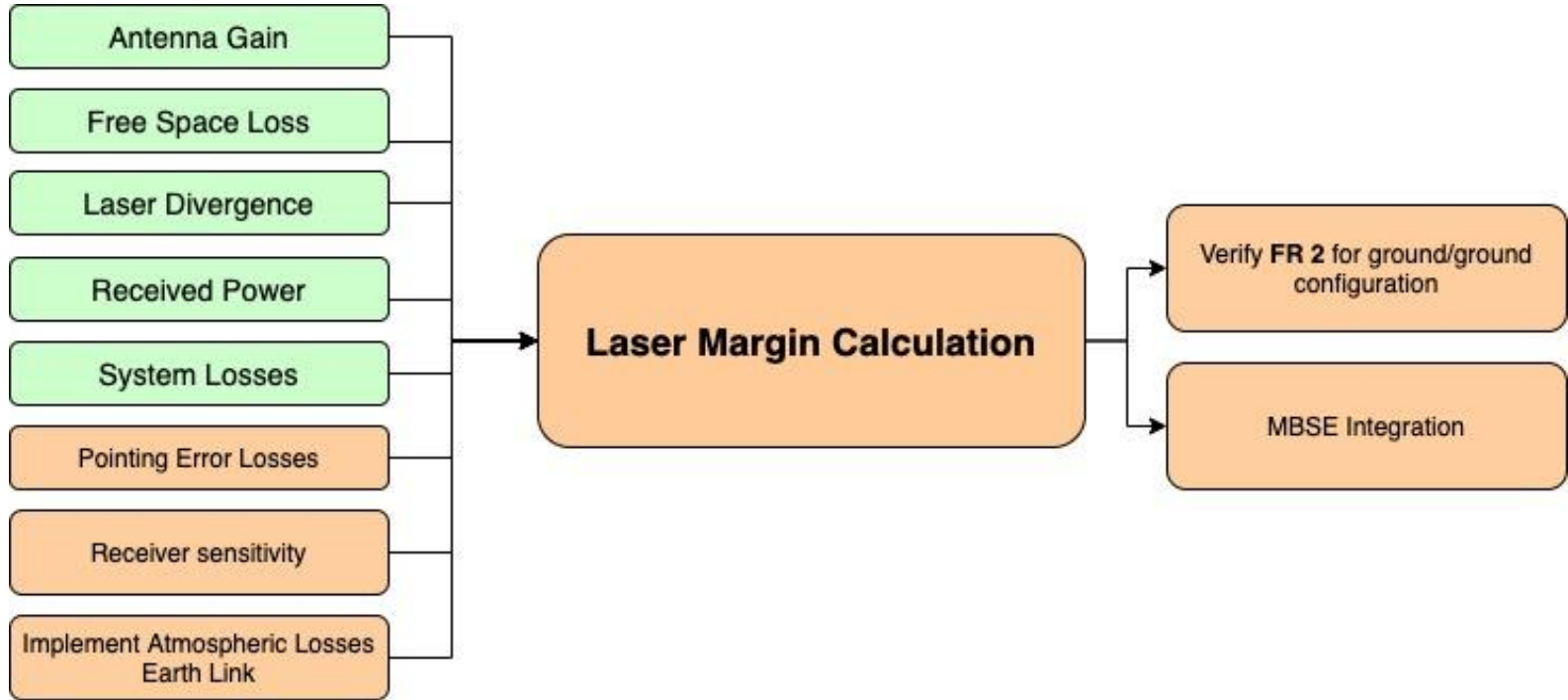
Model Logistics:

- Programmed using MatLab
- **Inputs:** Range, Frequency, Antenna Size, Transmit Power, Data Rate, System Losses (Atmospheric, transmit, receiver)
- **Outputs:** Link Margin

Model Validation: Available literature and research, sensitivity analysis



Laser Link Model Progress





Network Capacity Model

Purpose: Verify that the network can support the required number of endpoints

Model Logistics:

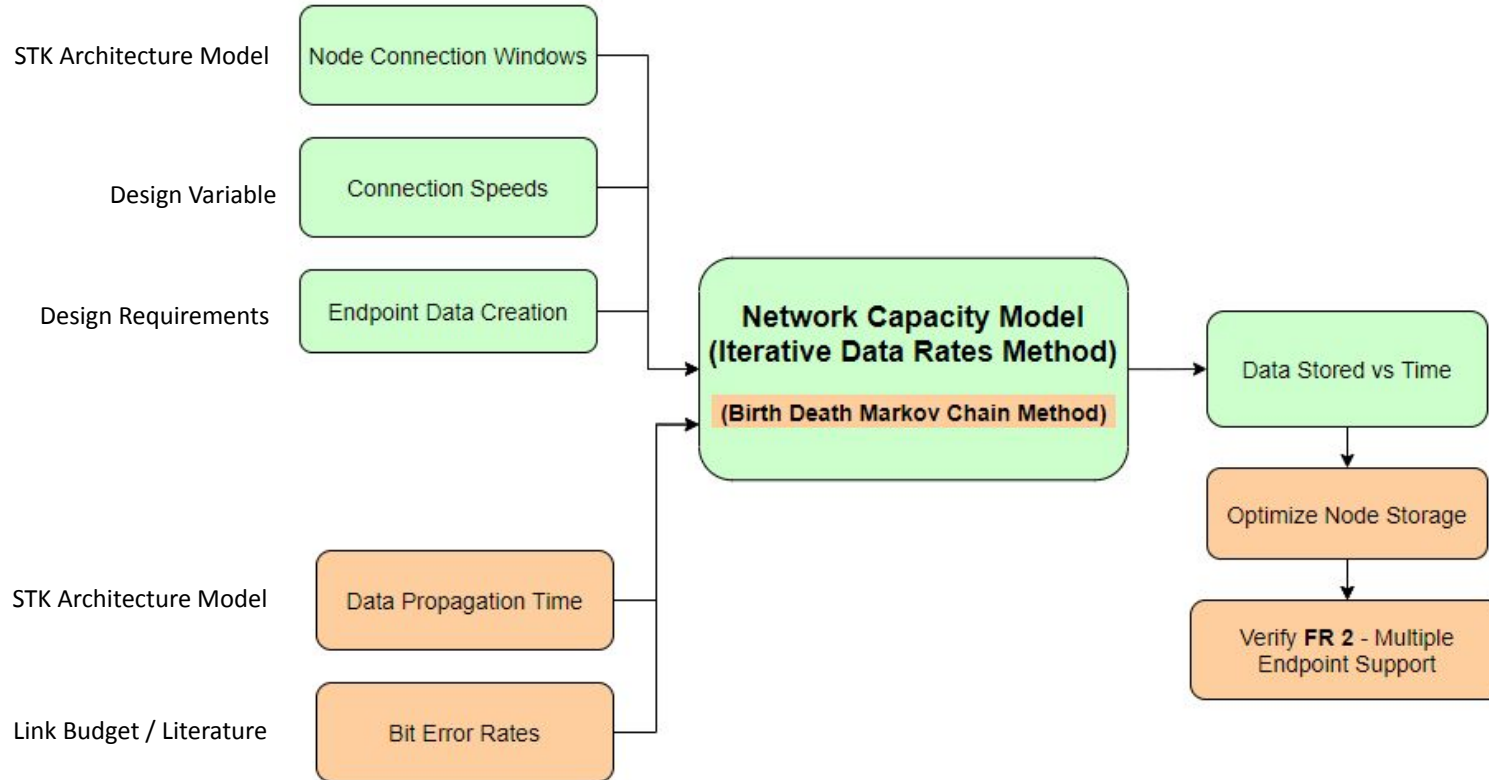
- Iterative data rates computation method performed using MatLab
- **Inputs:** node connections, link data rates, endpoint data requirements, bit error rates, data propagation delay
- **Outputs:** Data stored in each node over time

Model Validation: Benchmarking and hardware verification test





Capacity Model: Build Progress





Hardware Demonstration



Purpose: Demonstrate functionality of DTN protocol for Earth-based applications using ION-DTN software

Model Logistics:

- **ION-DTN** software downloaded from SourceForge.net and loaded onto two Ubuntu 18.04 server machines

Model Validation: ION-DTN was developed by Dr. Scott Burleigh of NASA's Jet Propulsion Laboratory



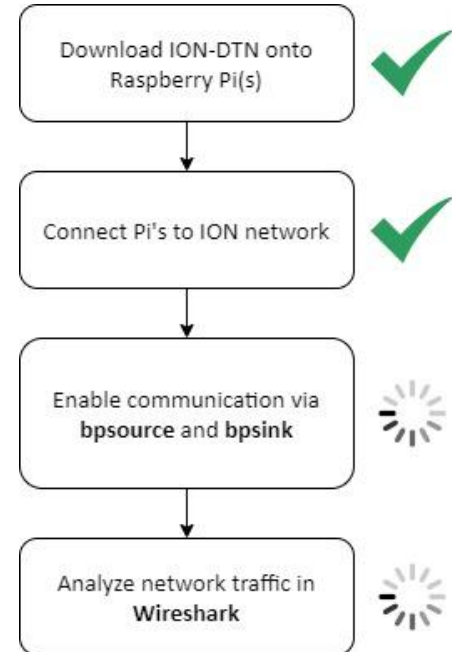
Hardware Demonstration Timeline

Current development:

- Ubuntu server & ION-DTN installed
- Validating proof-of-concept

Future Development:

- Enabling communications between two Pi machines
 - Must debug given **Assembly** test file
- Use **Wireshark** to calculate internal hardware latencies
 - **RISK:** time intensive, steep learning curve





SysML Modeling/MBSE



Purpose: Integration of separate project elements and model outputs (network capacity, link budget, etc.) into one project space, and trace requirements to the subsystems that satisfy them.

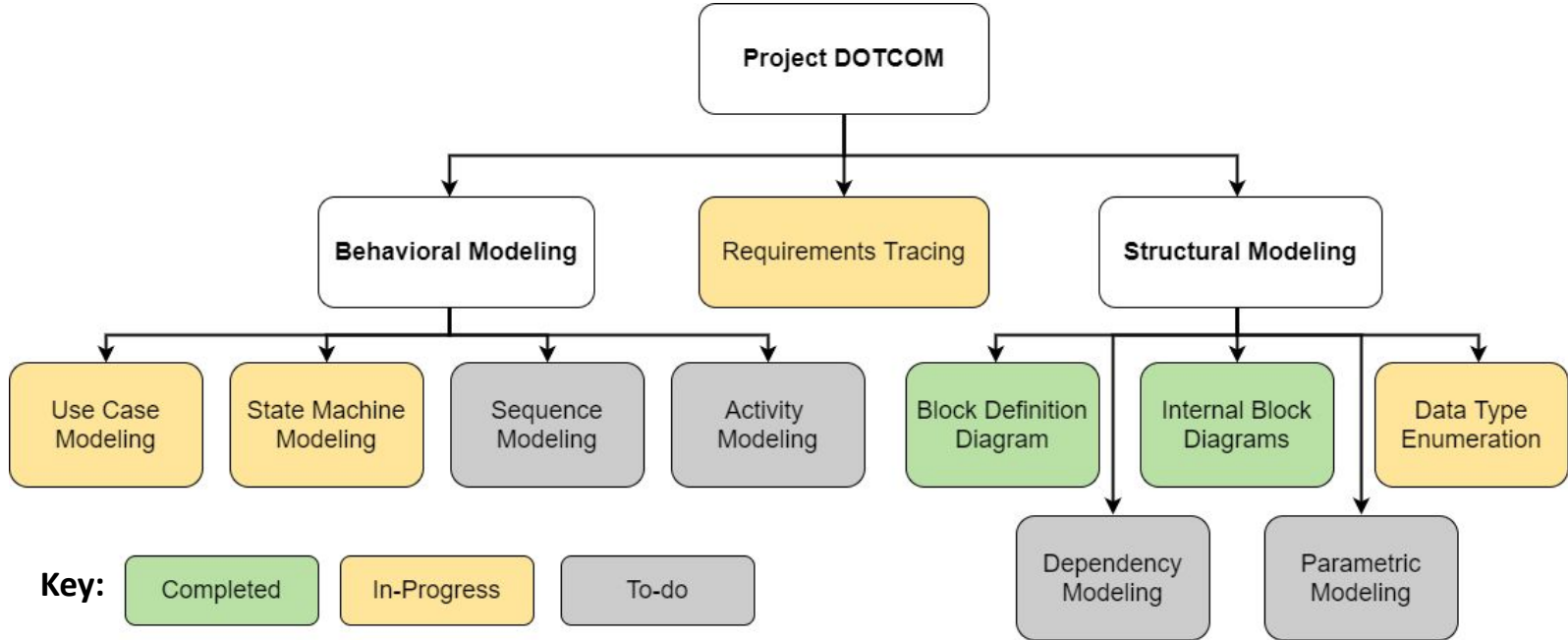
Model Logistics:

- Created in the SysML modeling language
- **Inputs:** Completed modeling of project subsystems
- **Outputs:** Cohesive DOTCOM project deliverable, including mapping of subsystem connections and modeling behavior of network nodes.

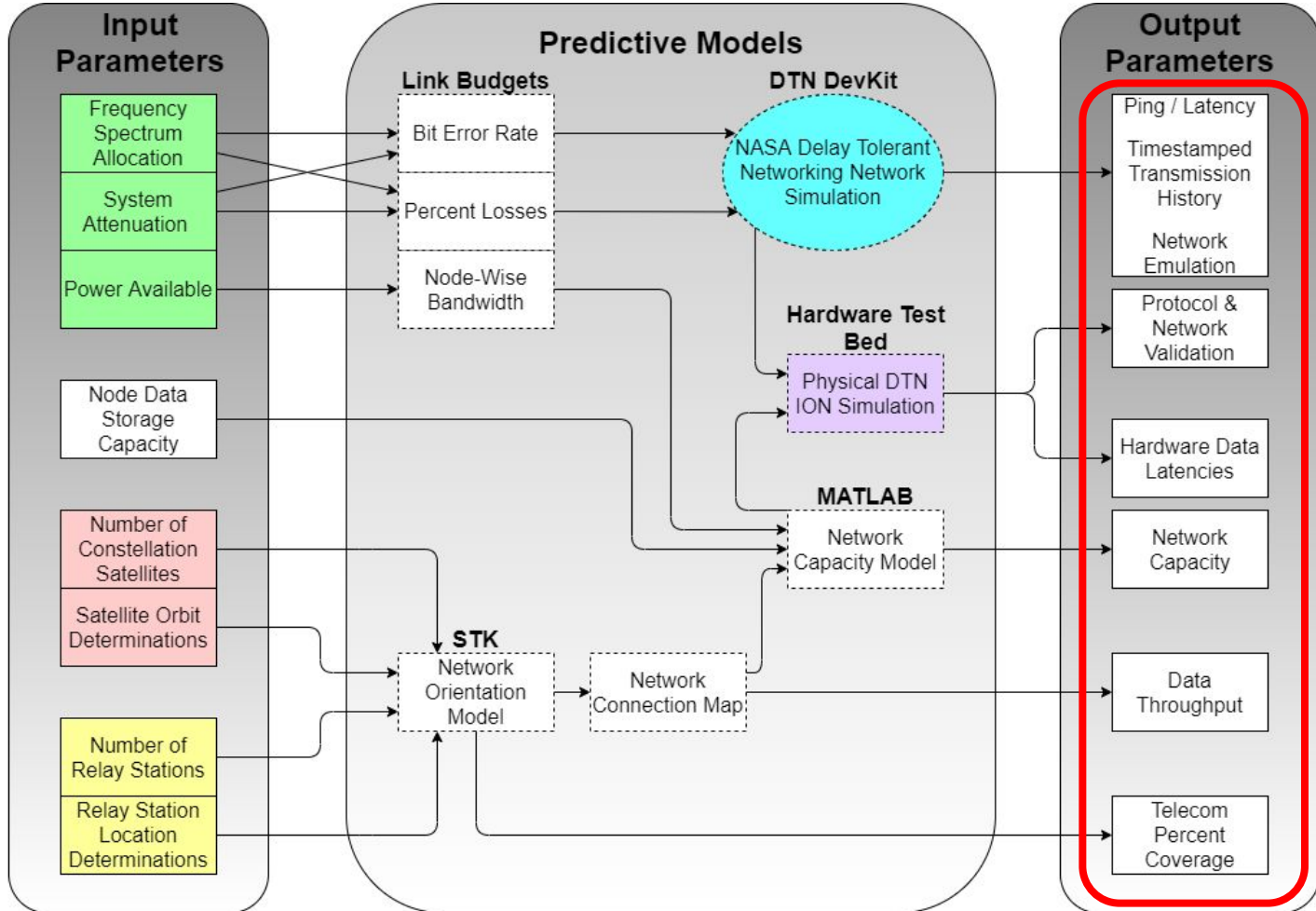
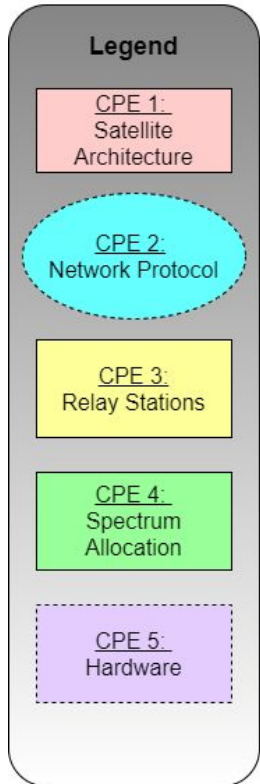
Model Validation: Validation of project inputs will come from their own verification and testing steps, as outputs from these models are loaded into the SysML simulation.



SysML Modeling Progress Update



System FBD



Relay Station Models

- **Atmospheric Attenuation Evaluation (Matlab)**
 - Input: Atmospheric humidity, angle of signal through atmosphere, height of relay station
 - Output: Attenuation (atmospheric loss variable)
 - Status: In progress
- **Model Verification (Orbital STK)**
 - Repeat modeling techniques for well-documented system (Deep Space Network)
 - Compare modeled results to real-life behavior
 - Status: Not started

Constellation Architecture Testing and Verification

- Connection Window Evaluation (Matlab)
 - Input: Satellite position vs. time data
 - Output: Viability of each link at all times
 - Status: In progress
- Coverage Map (Matlab)
 - Input: Satellite position vs. time data
 - Output: Map of which points in the system have coverage at all times (target: >99%)
 - Status: In progress
- Model Verification
 - Repeat modeling techniques for well-documented system (GPS)
 - Compare modeled results to real-life behavior
 - Status: Not started

Constellation Configuration 6/6/4

Variables
Number of Satellites (T)
Number of Orbital Planes (P)
Satellite Spacing (F)
Inclination (i)
Right Ascension of Ascending Node (RAAN)
True Anomaly (v)

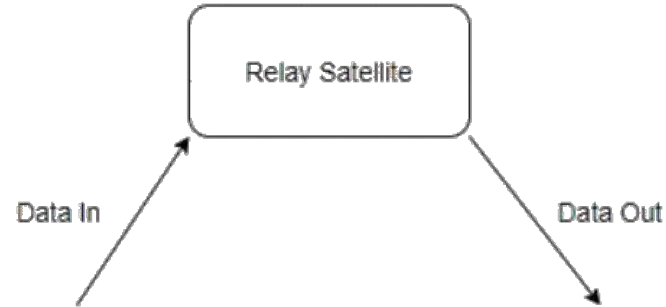
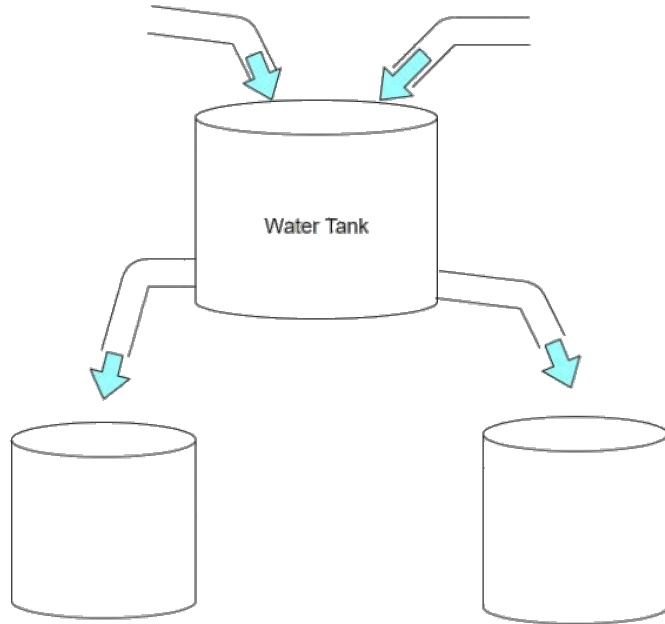
Configuration has format T/P/F

RAAN separation = $360^\circ/P = 60^\circ$

v separation = $F * \text{RAAN separation} = 240^\circ$

$i = 53.1^\circ = \text{constant}$

Network Capacity Model



Overflowing water tank is analogous to a saturated / max capacity network

$\text{Data Rate in} - \text{Data Rate out} = \text{Used Memory Change Rate}$

Network endpoints analogous to faucets adding water to the system



Data Rates



Forward Link Requirements

Data Type (Reliable Channel)

	Data Rates
Speech	10 kbps
Digital Channel	200 bps
Digital Channel	2 kbps



Element

Astronaut
Astronaut
Transport / Rover / Base

Data Type (High Rate Channel)

	Data Rates
Command Loads	100 kbps
CD-quality Audio	128 kbps
Video (TV, Videoconference)	1.5 Mbps

Element

Transport / Rover / Base
Astronaut
Astronaut

Return Link Requirements

Data Type (Reliable Channel)

	Data Rates
Speech	10 kbps
Engineering Data	2 kbps
Engineering Data	20 kbps
Video	100 kbps
Video	1.5 Mbps

Element

Astronaut
Astronaut
Transport / Rover / Base
Helmet Camera
Rover

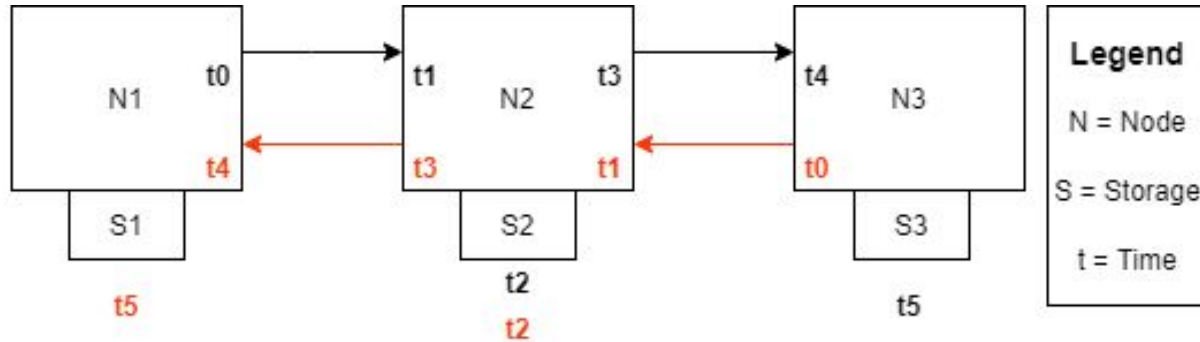
Data Type (High Rate Channel)

	Data Rates
High Definition TV	20 Mbps
Biomedics	35 Mbps
Hyperspectral Imaging	150 Mbps
Synthetic Aperture Radar	100 Mbps

Element

Astronaut
Astronaut
Science Payload
Science Payload

Key Measurement Methodology



Synchronous

t1 - t0 = Light Time Latency
t2 - t1 = N2 Storage Latency
t3 - t2 = N2 Forward Latency

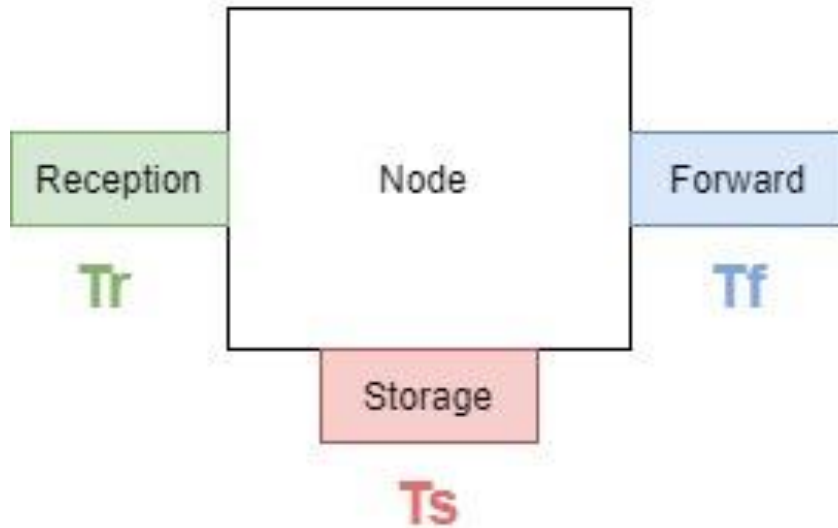
t3 - t1 = N2 Hardware Latency
t5 - t0 = Total Signal Latency
(t5-t0)-t4-t1 = Total Hardware Latency

Asynchronous

t1 - t0 = Light Time Latency
t2 - t1 = N2 Storage Latency
t3 - t2 = N2 Forward Latency

t3 - t1 = N2 Hardware Latency
t5 - t0 = Total Signal Latency
(t5-t0)-t4-t1 = Total Hardware Latency

$$T_f - T_r = \text{Hardware Latency}$$



Legend:

T_r = Time stamp
for reception

T_s = Time stamp
for storage

T_f = Time stamp
for forwarding

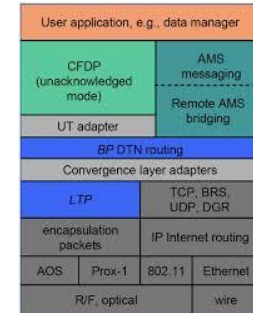
Completed testing

Completed:

- 1) Ubuntu installed
- 2) Software installed
- 3) Software configured

In progress:

- 1) Debug given test file



1 Project Purpose and Objectives

1.1 Mission Statement

1.2 CONOPS

1.2.1 Hardware CONOPS

1.2.2 System CONOPS

1.3 Functional Requirements


1.4 Project Goals


Hardware CONOPS

Level 1 Success



Legend

 Raspberry Pi node

 Ground station to ground station link

1 Project Purpose and Objectives

1.1 Mission Statement

1.2 CONOPS

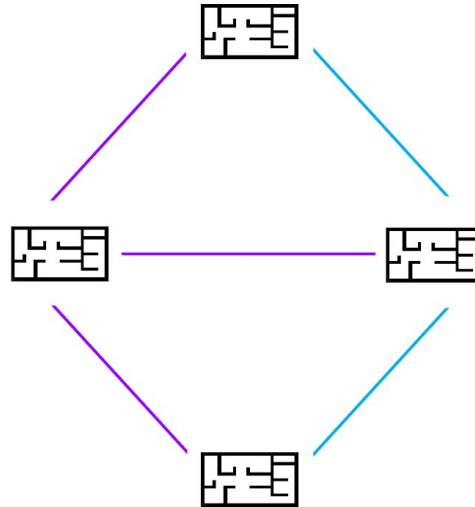
1.2.1 Hardware CONOPS

1.2.2 System CONOPS

1.3 Functional Requirements

1.4 Project Goals

Level 2 Success



Legend



Raspberry Pi node



Ground station to constellation satellite link



Constellation satellite to constellation satellite link

1 Project Purpose and Objectives

1.1 Mission Statement

1.2 CONOPS

1.2.1 Hardware CONOPS

1.2.2 System CONOPS

1.3 Functional Requirements

1.4 Project Goals

Level 3 Success

Legend



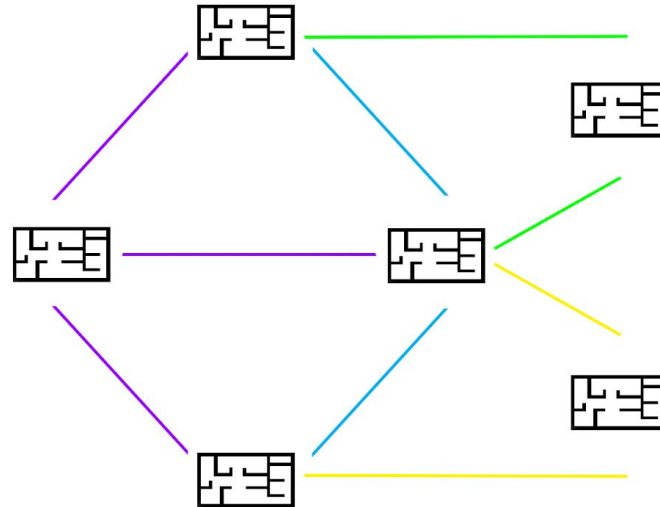
Raspberry Pi node

Ground station to constellation satellite link

Constellation satellite to constellation satellite link

Constellation satellite to ground vehicle link

Constellation satellite to orbital vehicle link



1 Project Purpose and Objectives

1.1 Mission Statement

1.2 CONOPS

1.2.1 Hardware CONOPS

1.2.2 System CONOPS

1.3 Functional Requirements

1.4 Project Goals

Level 4 Success

Legend



Raspberry Pi node



Ground station to ground station link



Ground station to constellation satellite link



Constellation satellite to constellation satellite link



Constellation satellite to ground vehicle link



Constellation satellite to orbital vehicle link

