

Selected Solutions

Chapter 1, Shankar

11.3 Do functions that vanish at  $x=0, x=L$  form a vector space?

Yes.

Do periodic functions obeying  $f(0) = f(L)$  form a vector space?

Yes.

Functions that obey  $f(0) = 4$

No. They are not closed under scalar multiplication.

(2) (a) No — can multiply a scalar by an integer and yield a non-integer.

(b) Yes  $\rightarrow \infty$

(c) Yes.  $\rightarrow \infty$

(d) Yes.  $\rightarrow 2$  (not 3 since one component is constrained)

(e) No — can add  $-1$  to  $-1$  and be outside set.

③ Shankar 1.3.1

initial vectors  $|A\rangle \Leftrightarrow \begin{pmatrix} 3 \\ 4 \end{pmatrix}$   $|B\rangle \Leftrightarrow \begin{pmatrix} 2 \\ -6 \end{pmatrix}$

$$|1\rangle = \frac{|A\rangle}{|A|} \Leftrightarrow \begin{pmatrix} 3/5 \\ 4/5 \end{pmatrix}$$

$$|2'\rangle = |B\rangle - |1\rangle \langle 1|B\rangle$$

$$= \begin{pmatrix} 2 \\ -6 \end{pmatrix} - \begin{pmatrix} 3/5 \\ 4/5 \end{pmatrix} \begin{pmatrix} 3/5 & 4/5 \end{pmatrix} \begin{pmatrix} 2 \\ -6 \end{pmatrix}$$

$$= \begin{pmatrix} 2 \\ -6 \end{pmatrix} - \begin{pmatrix} 3/5 \\ 4/5 \end{pmatrix} \cdot \left(\frac{6}{5} - \frac{24}{5}\right)$$

$$= \begin{pmatrix} 2 \\ -6 \end{pmatrix} - \begin{pmatrix} -54/25 \\ -72/25 \end{pmatrix}$$

$$= \begin{pmatrix} 104/25 \\ -78/25 \end{pmatrix}$$

$$|2\rangle = \frac{|2'\rangle}{|2'|} = \frac{|2'\rangle}{\sqrt{16900/625}} = \frac{|2'\rangle}{130/25} = \begin{pmatrix} 104/25 \\ -78/25 \end{pmatrix} \frac{5}{26}$$

$$= \begin{pmatrix} 4/5 \\ -3/5 \end{pmatrix}$$

... which is unique unless you count  $(|1\rangle, -|2\rangle)$  as a different basis.

Gram-Schmidt Verfahren

1.3.2

$$|I\rangle = \begin{bmatrix} 3 \\ 0 \\ 0 \end{bmatrix} \quad |II\rangle = \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} \quad |III\rangle = \begin{bmatrix} 0 \\ 2 \\ 5 \end{bmatrix}$$

$$|1\rangle = \frac{1}{\sqrt{[3,0,0] \begin{bmatrix} 3 \\ 0 \\ 0 \end{bmatrix}}} \begin{bmatrix} 3 \\ 0 \\ 0 \end{bmatrix} = \frac{1}{3} \begin{bmatrix} 3 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$|2\rangle = |II\rangle - |1\rangle \langle I|II\rangle$$

$$= \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} - \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} [1,0,0] \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}$$

$$= \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} - \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} (0)$$

$$|2\rangle = \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}$$

$$|2\rangle = \frac{1}{\sqrt{[0,1,2] \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}}} \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} = \frac{1}{\sqrt{5}} \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 1/\sqrt{5} \\ 2/\sqrt{5} \end{bmatrix}$$

$$|3\rangle = |III\rangle - |1\rangle \langle 1|III\rangle - |2\rangle \langle 2|III\rangle$$

$$= \begin{bmatrix} 0 \\ 2 \\ 5 \end{bmatrix} - \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} [1,0,0] \begin{bmatrix} 0 \\ 2 \\ 5 \end{bmatrix} - \begin{bmatrix} 0 \\ 1/\sqrt{5} \\ 2/\sqrt{5} \end{bmatrix} [0, 1/\sqrt{5}, 2/\sqrt{5}] \begin{bmatrix} 0 \\ 2 \\ 5 \end{bmatrix}$$

$$= \begin{bmatrix} 0 \\ 2 \\ 5 \end{bmatrix} - \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} (0) - \begin{bmatrix} 0 \\ 1/\sqrt{5} \\ 2/\sqrt{5} \end{bmatrix} \left( \frac{2}{\sqrt{5}} + \frac{10}{\sqrt{5}} \right)$$

$$|3\rangle = \begin{bmatrix} 0 \\ 2 \\ 5 \end{bmatrix} - \begin{bmatrix} 0 \\ 12/\sqrt{5} \\ 24/\sqrt{5} \end{bmatrix} = \begin{bmatrix} 0 \\ -2/\sqrt{5} \\ 1/\sqrt{5} \end{bmatrix}$$

$$|3\rangle = \frac{1}{\sqrt{[0, -2/\sqrt{5}, 1/\sqrt{5}] \begin{bmatrix} 0 \\ -2/\sqrt{5} \\ 1/\sqrt{5} \end{bmatrix}}} \begin{bmatrix} 0 \\ -2/\sqrt{5} \\ 1/\sqrt{5} \end{bmatrix} = \frac{1}{\left(\frac{1}{5} - \frac{1}{5}\right)^2} \begin{bmatrix} 0 \\ -2/\sqrt{5} \\ 1/\sqrt{5} \end{bmatrix} = \begin{bmatrix} 0 \\ -2\sqrt{5}/5 \\ \sqrt{5}/5 \end{bmatrix} = \begin{bmatrix} 0 \\ -2/\sqrt{5} \\ 1/\sqrt{5} \end{bmatrix}$$

1.6.2) Given  $\Omega$  and  $A$  are Hermitian  
 what can we say about...

1)  $\Omega A$ ? We know  $\Omega = \Omega^\dagger$ ,  $A = A^\dagger$

$$\text{So, } \Omega A = \Omega^\dagger A^\dagger = (A \Omega)^\dagger$$

$\Rightarrow$  If  $\Omega A = A \Omega$  then  $\Omega A$  is Hermitian.

$\Rightarrow$  If  $[\Omega, A] = 0$  then  $\Omega A$  is Hermitian.

2)  $\Omega A + A \Omega$ :

$$\begin{aligned} \Omega A + A \Omega &= \Omega^\dagger A^\dagger + A^\dagger \Omega^\dagger = (A \Omega)^\dagger + (\Omega A)^\dagger \\ &= (\Omega A)^\dagger + (A \Omega)^\dagger \\ &= (\Omega A + A \Omega)^\dagger \end{aligned}$$

$\Rightarrow \Omega A + A \Omega$  is Hermitian.

3)  $[\Omega, A]$ :

$$[\Omega, A] = \Omega A - A \Omega = \Omega^\dagger A^\dagger - A^\dagger \Omega^\dagger = (A \Omega)^\dagger - (\Omega A)^\dagger$$

$$[\Omega, A] = [\Omega, A]^\dagger = -[A, \Omega] \Rightarrow \boxed{[\Omega, A] \text{ is anti-Hermitian}}$$

4)  $i[\Omega, A]$ :

$$\begin{aligned} i[\Omega, A] &= \{i[\Omega, A]\}^\dagger \\ &= \{i^* [\Omega, A]^\dagger\}^\dagger \quad \text{from part 3)} \\ &= \{-i(-[\Omega, A])\}^\dagger \end{aligned}$$

$$i[\Omega, A] = \{i[\Omega, A]\}^\dagger$$

so  $i[\Omega, A]$  is Hermitian.

⑥ Shankar 1.6.4

Property 2:  $\det U = \det(U^T) = [\det(U^*)]^*$

Property 3:  $\det(U^*U) = (\det U)(\det U^*)$

For a unitary matrix,  $U^*U = \mathbb{1}$ .  $\odot \det(\mathbb{1}) = 1$

$$\begin{aligned} \text{so } 1 &= \det(U^*U) \\ &= (\det U^*)(\det U) \\ &= (\det U)^*(\det U) \quad \text{QED.} \end{aligned}$$

⑦ Shankar 1.6.5

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix} \quad \text{- Orthogonal: obvious.}$$

- Unitary:  $R^+ \Leftrightarrow \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{pmatrix}$

$$R^+R = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = \mathbb{1} \quad \checkmark$$

1.81

$$\det(\Omega - \omega I) = 0$$

$$\det \begin{bmatrix} 1-\omega & 3 & 1 \\ 0 & 2-\omega & 0 \\ 0 & 1 & 4-\omega \end{bmatrix}$$

Characteristic equation:

$$(1-\omega)(2-\omega)(4-\omega) - 3(0) + 1(0) = 0$$

$$\Rightarrow \omega = 1, 2, 4 \text{ are the eigenvalues.}$$

To find the eigenvectors,  $\omega = 1$ :

$$\begin{bmatrix} 1-1 & 3 & 1 \\ 0 & 2-1 & 0 \\ 0 & 1 & 4-1 \end{bmatrix} \Rightarrow \begin{bmatrix} 0 & 3 & 1 \\ 0 & 1 & 0 \\ 0 & 1 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

I)  $3x_2 + x_3 = 0$

II)  $x_2 = 0$

III)  $x_2 + 3x_3 = 0$

So,  $x_2 = 0$

II)  $\Rightarrow x_3 = 0$

we let  $x_1 = 1 \Rightarrow |1\rangle = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$

Now  $\omega = 2$ 

$$\begin{bmatrix} 1-2 & 3 & 1 \\ 0 & 2-2 & 0 \\ 0 & 1 & 4-2 \end{bmatrix} \Rightarrow \begin{bmatrix} -1 & 3 & 1 \\ 0 & 0 & 0 \\ 0 & 1 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0$$

$\Rightarrow -x_1 + 3x_2 + x_3 = 0$

$x_2 + 2x_3 = 0$

$x_1 = 3 - \frac{1}{2} = \frac{5}{2}$

let  $x_2 = 1$ .

$\Rightarrow x_3 = -\frac{1}{2}, x_1 = \frac{5}{2}$

$\Rightarrow |2\rangle = \begin{bmatrix} 5/2 \\ 1 \\ -1/2 \end{bmatrix}$



1.8 (cont.) And finally

$$\begin{bmatrix} 1-4 & 3 & 1 \\ - & 2-4 & 0 \\ 3 & & 4-4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -3 & 3 & 1 \\ 0 & -2 & 0 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0$$

$$\begin{aligned} -3x_1 + 3x_2 + x_3 &= 0 \\ -2x_2 &= 0 \\ x_2 &= 0 \end{aligned}$$

$$\begin{aligned} -3x_1 + x_3 &= 0 \\ x_3 &= 3x_1 \end{aligned} \quad \text{let } x_1 = 1 \\ x_3 = 3$$

$$\Rightarrow |4\rangle = \begin{bmatrix} 1 \\ 0 \\ 3 \end{bmatrix}$$

Normalizing,  $|1\rangle = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$  (already normalized)

$$|2\rangle = \frac{|2'\rangle}{|2|} = \frac{2}{\sqrt{30}} \begin{bmatrix} 5/2 \\ 1 \\ -1/2 \end{bmatrix} = \begin{bmatrix} 5/\sqrt{30} \\ 2/\sqrt{30} \\ -1/\sqrt{30} \end{bmatrix} \leftarrow |2\rangle$$

$$|4\rangle = \frac{|4'\rangle}{|4|} = \frac{1}{\sqrt{10}} \begin{bmatrix} 1 \\ 0 \\ 3 \end{bmatrix} = \begin{bmatrix} 1/\sqrt{10} \\ 0 \\ 3/\sqrt{10} \end{bmatrix} \leftarrow |4\rangle$$

The matrix is not Hermitian,  $\Omega^\dagger \neq \Omega$   
The eigenvectors are not orthogonal

9) Shankar 1.8.7

$$\det \Omega = \omega_1 \omega_2 = 1 - 4 = -3$$

$$\text{Tr } \Omega = \omega_1 + \omega_2 = 1 + 1 = 2$$

So ~~the~~ eigenvalues are presumably 3, -1.

Verifying:  $\det \begin{pmatrix} 1-\omega & 2 \\ 2 & 1-\omega \end{pmatrix} = 0$

$$(1-\omega)^2 - 4 = 0$$

$$1-\omega = \pm 2$$

$$\omega = 3, -1. \quad \checkmark$$

1.8.9) We have a collection of masses  $m_\alpha$  located at  $\vec{r}_\alpha$  and rotating with angular velocity around a common axis.

The total angular momentum is

$$\vec{L} = \sum_{\alpha} M_{\alpha} (\vec{r}_{\alpha} \times \vec{v}_{\alpha}), \text{ where } \vec{v}_{\alpha} = \vec{\omega} \times \vec{r}_{\alpha}. \text{ Note } \vec{r}_{\alpha} = (r_{\alpha x}, r_{\alpha y}, r_{\alpha z})$$

Recall,  $\vec{A} \times (\vec{B} \times \vec{C}) = \vec{B}(\vec{A} \cdot \vec{C}) - \vec{C}(\vec{A} \cdot \vec{B})$

Substituting,  $\vec{L} = \sum_{\alpha} M_{\alpha} (\vec{r}_{\alpha} \times \vec{\omega} \times \vec{r}_{\alpha})$ , and applying the identity,

$$\vec{L} = \sum_{\alpha} M_{\alpha} [(\vec{\omega})(\vec{r}_{\alpha} \cdot \vec{r}_{\alpha}) - \vec{r}_{\alpha}(\vec{r}_{\alpha} \cdot \vec{\omega})]$$

Lets write this in Dirac notation...

$$\vec{L} = \sum_{\alpha} M_{\alpha} \left[ \underbrace{|\omega\rangle \langle r_{\alpha} | r_{\alpha} \rangle}_{\text{I}} - \underbrace{|r_{\alpha}\rangle \langle r_{\alpha} | \omega \rangle}_{\text{II}} \right]$$

Looking at the terms separately:

$$\text{I: } |\omega\rangle \langle r_{\alpha} | r_{\alpha} \rangle = r_{\alpha}^2 |\omega\rangle = r_{\alpha}^2 \underbrace{\mathbb{I}}_{\substack{\text{identity} \\ \text{operator}}} |\omega\rangle = \begin{bmatrix} r_{\alpha}^2 & 0 & 0 \\ 0 & r_{\alpha}^2 & 0 \\ 0 & 0 & r_{\alpha}^2 \end{bmatrix} |\omega\rangle$$

$$\text{II: } \underbrace{|r_{\alpha}\rangle \langle r_{\alpha} |}_{\text{a } 3 \times 3 \text{ matrix}} \omega \rangle = \begin{bmatrix} r_x \\ r_y \\ r_z \end{bmatrix} \begin{bmatrix} r_x & r_y & r_z \end{bmatrix} |\omega\rangle = \begin{bmatrix} r_x r_x & r_x r_y & r_x r_z \\ r_y r_x & r_y r_y & r_y r_z \\ r_z r_x & r_z r_y & r_z r_z \end{bmatrix} |\omega\rangle$$

note: I've dropped the  $\alpha$ -subscript for clarity.

→

$$\vec{l} = \sum_x M_x \underbrace{\begin{bmatrix} r^2 - r_x r_x & -r_x r_y & -r_x r_z \\ -r_y r_x & r^2 - r_y r_y & -r_y r_z \\ -r_z r_x & -r_z r_y & r^2 - r_z r_z \end{bmatrix}}_M |\omega\rangle$$

If we adjust the rotation  $x \rightarrow 1, y \rightarrow 2, z \rightarrow 3$  and put the  $\alpha$ 's back we have:

$$M_{ij} = \sum_x M_x [r_x^2 \delta_{ij} - (\vec{r}_x)_i (\vec{r}_x)_j]$$

or more compactly  
 $|\vec{l}\rangle = M|\omega\rangle$

1) Will  $|\vec{l}\rangle$  and  $|\omega\rangle$  always be parallel?

$|\vec{l}\rangle$  and  $|\omega\rangle$  are parallel if they vary by a scalar multiple:  $|\vec{l}\rangle = \lambda|\omega\rangle$

Then,  $M|\omega\rangle = \lambda|\omega\rangle$  so all  $|\omega\rangle$  must be eigenvectors of  $M$ . But,  $M$  is  $3 \times 3$  and Hermitian so it will have at most 3 eigenvectors.

Picking a  $|\omega\rangle$  that is not one of these 3 will not be parallel to  $|\vec{l}\rangle$

2)  $M$  is Hermitian ( $M^\dagger = M$ ) because it is symmetric about its diagonal. Since all its elements are obviously real it is sufficient to observe that  $M^T = M$ .

3) See 1). We find the  $|\omega\rangle$ 's which are parallel to  $|\vec{l}\rangle$  by finding the eigenvalues and their corresponding eigenvectors.

4) For a sphere, the moment of inertia matrix,  $M_{\text{cm}}$  is diagonal and the eigenvalues are the same,  $\frac{2}{5}MR^2$ .