

Part 1 – Sketching Vector Potential

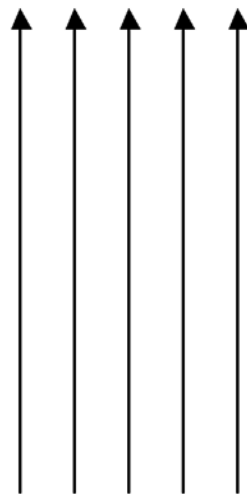
One of Maxwell's equations, $\nabla \times \vec{E} = 0$, made it useful for us to define a scalar potential V , where $\vec{E} = -\nabla V$. Similarly, another one of Maxwell's equations makes it useful for us to define the vector potential, \mathbf{A} .

i. Which if any of Maxwell equations makes it useful for us to define \mathbf{A} ? Explain.

ii. What current density \mathbf{J} would create the \mathbf{B} -field (uniform within a cylindrical volume) in Figure 1 below? Can you write an explicit mathematical formula for it?

Side view:

$$\vec{B}(s \leq a, \phi, z) = B_0 \hat{z}$$



$$\vec{B}(s > a, \phi, z) = 0$$

Figure 1

iii. Notice that the equations defining \mathbf{A} are mathematically analogous to Maxwell's

equations for \mathbf{B} :

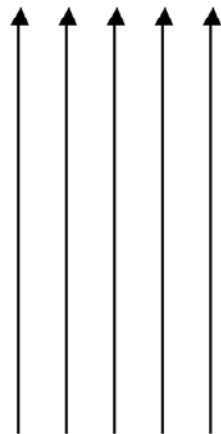
$$\begin{aligned} \nabla \cdot \vec{\mathbf{B}} = 0 & \Leftrightarrow \nabla \cdot \vec{\mathbf{A}} = 0 \\ \nabla \times \vec{\mathbf{B}} = \mu_0 \vec{\mathbf{J}} & \Leftrightarrow \nabla \times \vec{\mathbf{A}} = \vec{\mathbf{B}} \end{aligned}$$

First, sketch \mathbf{B} in Figure 2 (again, note this is a “cylindrical” volume with uniform \mathbf{J}).

Then, using the mathematical similarities above, sketch \mathbf{A} in Figure 3:

Side view:

$$\vec{\mathbf{J}}(s \leq a, \phi, z) = J_o \hat{z}$$

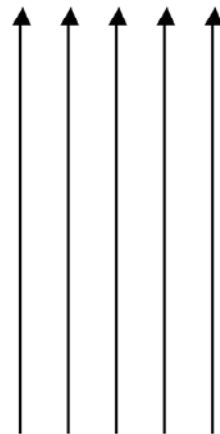


$$\vec{\mathbf{J}}(s > a, \phi, z) = 0$$

Figure 2: Given \mathbf{J} , sketch the \mathbf{B} field.

Side view:

$$\vec{\mathbf{B}}(s \leq a, \phi, z) = B_o \hat{z}$$



$$\vec{\mathbf{B}}(s > a, \phi, z) = 0$$

Figure 3: Given \mathbf{B} , sketch the \mathbf{A} field.

iv. One way to check your previous answer (conceptually) is using an Ampere’s Law analogy. Ampere’s Law tells you that the \mathbf{J} -flux (or I_{encl}) is equal to $\oint \vec{\mathbf{B}} \cdot d\vec{\ell}$.

What is a similar relationship between the vector potential and magnetic field?

Try using this “Ampere’s Law analogy” to (conceptually) check your sketch of \mathbf{A} .

v. A toroidal wire coil looks like a doughnut wrapped with wire, as shown in Fig. 4. On the “blank” toroid, indicate the direction of \mathbf{J} , then sketch the \mathbf{B} and \mathbf{A} fields.

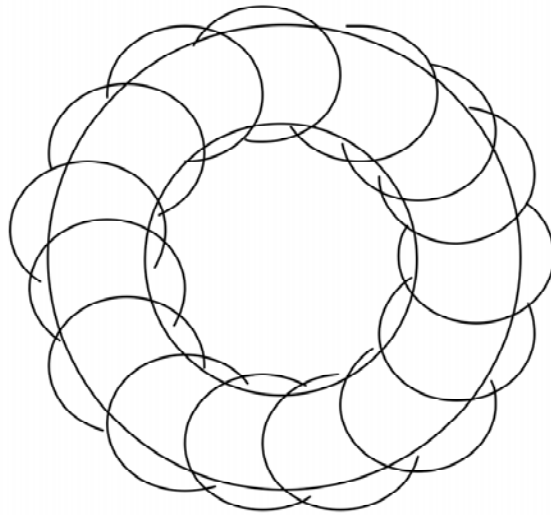
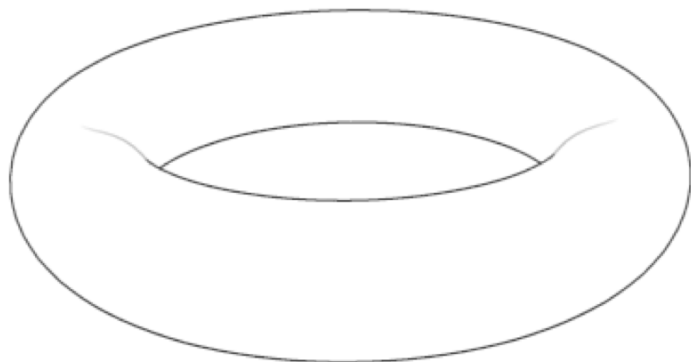


Figure 4



Part 2 – Calculating Vector Potential

On a previous homework, you calculated the magnetic field produced by a uniform surface current: $K(z=0) = K_o \hat{x}$. The answer you should have calculated is:

$$\vec{B}(z > 0) = \frac{-\mu_o K_o}{2} \hat{y}$$

$$\vec{B}(z < 0) = \frac{+\mu_o K_o}{2} \hat{y}$$

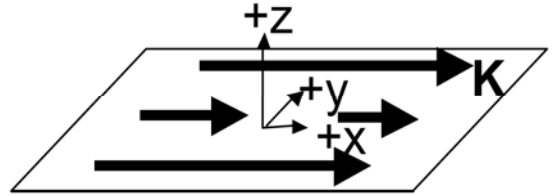


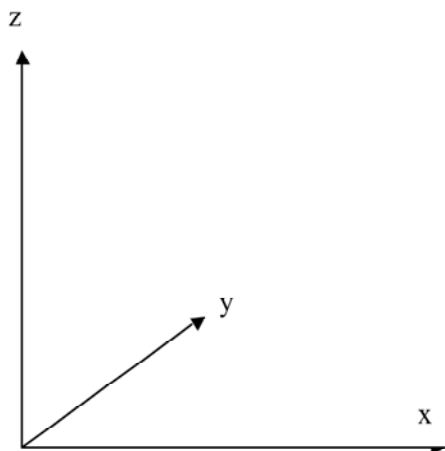
Figure 5

i. Which of the following practical devices can be modeled by the currents or fields shown in figures 2 through 5?

A: Tokamak, B: Solenoid, C: Ribbon conductor, D: Wire of finite diameter

ii. Sketch your best guess of what \mathbf{A} looks like for the uniform surface current.

Which components (x, y, or z) does \mathbf{A} have (it might help to look at relationship between \mathbf{A} , \mathbf{B} , and \mathbf{J} in the two examples in Part 1)? Which variables (x, y, or z) does \mathbf{A} depend on?



iii. Using your assumption for which components \mathbf{A} has, and which variables \mathbf{A} depends on, calculate (or guess) what \mathbf{A} is. Check your answer by calculating the \mathbf{B} field from your vector potential \mathbf{A} .

iv. Does your sketch of \mathbf{A} agree with the answer you calculated (or guessed)?