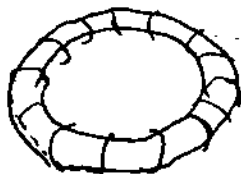


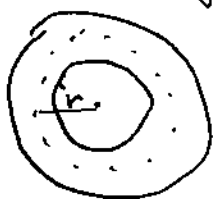
Continuing magnetic materials: Ferromagnetic toroids

Consider a toroidal piece of ferromagnetic material, with a current coil around it: N coils, current I :

What are boundary conditions on \vec{B} , \vec{H} ?



Use Amperian loop along central toroidal axis:

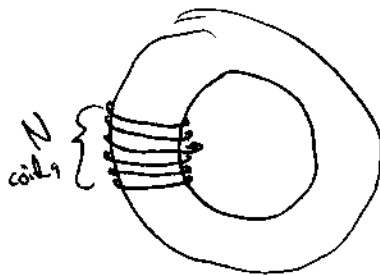


Symmetry allows calculation of H from I_{free} : $\oint d\vec{l} \cdot \vec{H} = I_{free} = NI$

$$\Rightarrow \vec{H} = \frac{NI}{2\pi r} \hat{\phi} \quad \text{and (assume linear): } \vec{B} = \mu \vec{H} = \frac{\mu NI}{2\pi r} \hat{\phi}$$

Very straightforward. What if all the coils are in a small region of toroid?

Integrals of \vec{B} , \vec{H} must be the same.




This is a "magnetic circuit": flux is confined inside the material since there's no source of divergence of curl of \vec{M} , and \vec{B} is kept parallel to surface.

$\Rightarrow \vec{B}$ is same as if coils were distributed around the ring!

$$\oint d\vec{l} \cdot \vec{H} = NI \quad \rightarrow \text{consider only } \phi \text{ component}$$

$$\oint dl H = NI$$

Now, express H as function of total flux Φ through a cross-section of the toroid:



$$\Phi = BA = \mu HA \Rightarrow H = \frac{\Phi}{\mu A}$$

$$\oint dl \frac{\Phi}{\mu A} = NI$$

\Rightarrow In "contained flux" approx, take Φ constant along l .

$$\Phi \int dl \frac{1}{\mu A} = NI$$

↑ magnetic flux
 ↓ Reluctance
 Source current

$$R = \frac{2\pi R}{\mu A} \text{ if simple toroid}$$

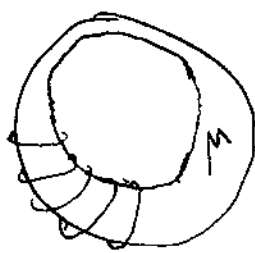
Note - often called "magnetic Ohm's Law":

$$\Phi = \frac{NI}{R}$$

So flux plays role of current in Ohm's Law

permeability \leftrightarrow conductivity
 reluctance \leftrightarrow resistance
 NI \leftrightarrow voltage.

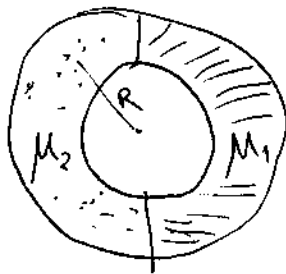
Can now also use this to predict flux with other geometries:



$$R = \oint \frac{dl}{\mu A} = \frac{1}{\mu} \oint \frac{dl}{A}$$

A constriction in the toroid \leftrightarrow increased reluctance
 $\Rightarrow \Phi$ decrease \leftarrow

Two materials:
 (constant cross-sec.)



$$R = \oint \frac{dl}{\mu A}$$

$$= \frac{1}{\mu_2 A} (\pi R) + \frac{1}{\mu_1 A} (\pi R) = \frac{\pi R}{A} \left(\frac{1}{\mu_1} + \frac{1}{\mu_2} \right)$$

Air gap: be careful! If gap is big, contained-flux assumption breaks down! Narrow gap: treat as above, with $\mu = \mu_0$. ($\mu_0 \approx \mu_{\text{air}}$ compared to ferromagnetism).

Can design many geometries of electromagnets this way.

dipoles:

quadrupoles:

