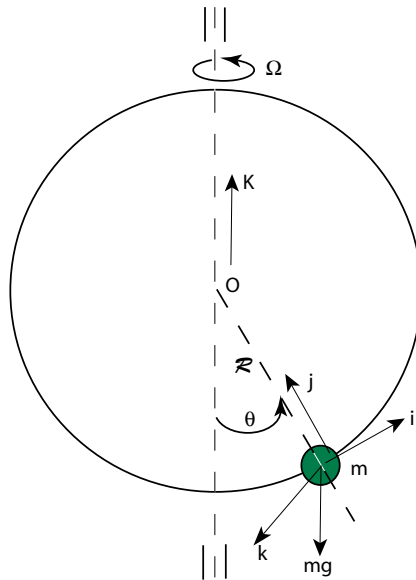


Hint for Problem 2.1:



The position vector of mass m can be expressed as (see the figure)

$$\mathbf{r} = -R \mathbf{j} \quad (1)$$

Hence, the velocity \mathbf{v} can be expressed as

$$\mathbf{v} = -R \dot{\mathbf{j}} \quad (2)$$

Using the definition of the angular velocity given by

$$\dot{\mathbf{j}} = \boldsymbol{\omega} \times \mathbf{j} \quad (3)$$

and noting that

$$\boldsymbol{\omega} = \Omega \mathbf{K} + \dot{\theta} \mathbf{k}, \quad \mathbf{k} = \mathbf{i} \times \mathbf{j} \quad (4)$$

one obtains

$$\mathbf{v} = -R (\Omega \mathbf{K} + \dot{\theta} \mathbf{k}) \times \mathbf{j} \quad (5)$$

Of course, you can employ other kinematics. However, the result should be the same. I hope this will help!