

ASEN 5227
Aerospace Math 1
Fall 2004

Homework 10

Assigned 4 NOV, Due 11 NOV

1. Euler's vector equation of motion for a rigid body is

$$\ddot{\mathcal{J}} \cdot \dot{\boldsymbol{\omega}} + \boldsymbol{\omega} \times (\ddot{\mathcal{J}} \cdot \boldsymbol{\omega}) = \mathbf{M}.$$

Introduce Cartesian components such that

$$\ddot{\mathcal{J}} = I_{ij} \hat{\mathbf{e}}_i \hat{\mathbf{e}}_j, \quad \boldsymbol{\omega} = \omega_i \hat{\mathbf{e}}_i, \quad \mathbf{M} = M_i \hat{\mathbf{e}}_i.$$

Show that Euler's equation can be written in Cartesian tensor form as

$$I_{ij} \dot{\omega}_j + \omega_l \omega_n I_{mn} \varepsilon_{lmi} = M_i \quad i = 1, 2, 3.$$

2. When the body-fixed Cartesian coordinate are aligned with the *principal axes*, the moment-of-inertia tensor takes a simpler form

$$\ddot{\mathcal{J}} = I_{11} \hat{\mathbf{e}}_1 \hat{\mathbf{e}}_1 + I_{22} \hat{\mathbf{e}}_2 \hat{\mathbf{e}}_2 + I_{33} \hat{\mathbf{e}}_3 \hat{\mathbf{e}}_3.$$

Show that the Euler equations now can be written as

$$I_{11} \dot{\omega}_1 + \omega_2 \omega_3 (I_{33} - I_{22}) = M_1$$

$$I_{22} \dot{\omega}_2 + \omega_1 \omega_3 (I_{11} - I_{33}) = M_2$$

$$I_{33} \dot{\omega}_3 + \omega_1 \omega_2 (I_{22} - I_{11}) = M_3.$$

3. Find the eigenvalues and eigenvectors (unit) of

a. $\begin{bmatrix} 4 & -4 & 0 \\ -4 & 0 & 0 \\ 0 & 0 & 3 \end{bmatrix}$

d. $\begin{bmatrix} 2 & -1 & 1 \\ -1 & 0 & 1 \\ 1 & 1 & 2 \end{bmatrix}$

b. $\begin{bmatrix} 1 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix}$

e. $\begin{bmatrix} 3 & 5 & 8 \\ 5 & 1 & 0 \\ 8 & 0 & 2 \end{bmatrix}$

c. $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 3 & -1 \\ 0 & -1 & 3 \end{bmatrix}$

f. $\begin{bmatrix} 2 & -\sqrt{3} & 0 \\ -\sqrt{3} & 4 & 0 \\ 0 & 0 & 4 \end{bmatrix}$

First write the characteristic equation, which you can solve using MATLAB.

4. The components of a stress dyadic at a point, referred to as (X_1, X_2, X_3) system, are (in kips \equiv 1000 psi):

$$\begin{bmatrix} 12 & 9 & 0 \\ 9 & -12 & 0 \\ 0 & 0 & 6 \end{bmatrix}$$

Find the following

- The stress vector acting on a plane perpendicular to the vector $2\hat{e}_1 - 2\hat{e}_2 + \hat{e}_3$ passing through the point.
 - The magnitude of the stress vector and the angle between the stress vector and the normal to the plane.
 - The magnitudes of the normal and tangential components of the stress vector.
5. Verify that

$$\vec{\mathbf{I}} \cdot \vec{\Phi} = \vec{\Phi} \cdot \vec{\mathbf{I}} = \vec{\Phi}$$

6. If \mathbf{a} is an arbitrary vector and $\vec{\Phi}$ is an arbitrary dyadic, verify that:
- $(\vec{\mathbf{I}} \times \mathbf{a}) \cdot \vec{\Phi} = \mathbf{a} \times \vec{\Phi}$.
 - $(\mathbf{a} \times \vec{\mathbf{I}}) \cdot \vec{\Phi} = \mathbf{a} \times \vec{\Phi}$.
 - $(\vec{\Phi} \times \mathbf{a})^T = -\mathbf{a} \times \vec{\Phi}^T$.